•	1	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions		MIL illum.
Intake Camshaft Actuator Solenoid Circuit – Bank 1	P0010	Detects a VVT system	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.	Value		> 11 Volts, and < 32 Volts	20 failures out of 25 samples	Trips 2 B Type
Intake Camshaft System Performance – Bank 1	P0011	desired and actual cam positions when VVT is activated	Camshaft position error [absolute value of (desired position - actual position)] is compared to thresholds to determine if excessive	sErrorLimlc1 Deg (see Supporting	sensors	and System Voltage < 32 Volts Desired cam position cannot vary more than 7.5 Cam Deg for at least KtPHSD_t_StablePositionTim elc1 seconds (see Supporting Table)	200 failures out of 1000 samples 100 ms /sample	Trips 2 B Type
Exhaust Camshaft Actuator Solenoid Circuit – Bank 1			The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		System supply voltage is within limits Output driver is commanded on, Ignition switch is in crank or run position	> 11 Volts, and < 32 Volts	19 failures out of 30 samples 250 ms /sample, continuous	Trips 2 B Type

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
		Description	Criteria	Value	Parameters	Conditions	Required	illum.
Exhaust Camshaft System Performance – Bank 1		error by comparing the desired and actual cam positions when VVT is activated	Camshaft position error [absolute value of (desired position - actual position)] is compared to thresholds to determine if excessive	1)Cam Position Error > KtPHSD_phi_CamPo sErrorLimEc1 Deg (see Supporting	P0013 ExhCMP B1	System Voltage > 11 Volts, and System Voltage < 32 Volts Desired cam position cannot vary more than 1.0 Cam Deg for at least KtPHSD_t_StablePositionTim eEc1 seconds (see Supporting Table)	100 failures out of 150 samples	Trips 2 B Type
					VVT is enabled Desired camshaft position > 0 Power Take Off (PTO) not active		·	
Crankshaft Position (CKP)- Camshaft Position (CMP) Correlation Bank 1 Sensor A		misalignment by monitoring if cam sensor pulse for bank 1 sensor A occurs	4 cam sensor pulses more than 11 crank degrees before or 11 crank degrees after nominal position in one cam revolution.		Engine Speed Crankshaft and camshaft position signals are synchronized	< 1200	4 failures out of 5 samples if the engine is being assisted by the starter	Type B 2 trips
					Cam phaser is in "parked" position		24 failures out of 30 samples if the engine is running	
					No Active DTCs:	P0335, P0336 P0340, P0341 5VoltReferenceA_FA 5VoltReferenceB_FA	without assistance from the starter	
					No Pending DTCs:	P0341		
							One sample per cam rotation	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Crankshaft Position (CKP)- Camshaft Position (CMP) Correlation Bank 1 Sensor B	P0017	Detects cam to crank misalignment by monitoring if cam sensor pulse for bank 1 sensor B occurs during the incorrect crank position	4 cam sensor pulses more than 8 crank degrees before or 9 crank degrees after nominal position in one cam revolution.		Engine Speed Crankshaft and camshaft position signals are synchronized	< 1200	4 failures out of 5 samples if the engine is being assisted by the starter	Type B 2 trips
		Crank position			Cam phaser is in "parked" position No Active DTCs:	P0335, P0336	24 failures out of 30 samples if the engine is running without	
					No Pending DTCs:	P0365, P0366 5VoltReferenceA_FA 5VoltReferenceB_FA P0366	assistance from the starter	
							One sample per cam rotation	
O2S Heater Control Circuit Bank 1 Sensor 1	P0030	This DTC checks the Heater Output Driver circuit for electrical integrity.	Voltage low during driver open state (indicates short-to- ground or open circuit) or voltage high			11.0 volts < Ign Voltage <	20 failures out of 25 samples	2 trips Type B
			during driver closed state (indicates short to voltage).		Engine Speed	> 400 RPM	250 ms /sample	
							Continuous	
Supercharger Bypass Valve Control Circuit	P0033	Electrical Integrity of Supercharger Bypass Valve Control Circuitry	ECM detects that commanded and actual states of output driver do not match		Ignition Voltage Ignition Voltage Engine Speed	>= 11.00 Volts <= 32.00 Volts > 0	20 failures out of 25 samples 1 sample every 250 msec	Type B 2 trips

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
O2S Heater Control Circuit Bank 1 Sensor 2	P0036	This DTC checks the Heater Output Driver circuit for electrical integrity.	Voltage low during driver open state (indicates short-to-ground or open circuit) or voltage high during driver closed state (indicates short to voltage).		Ign Switch position Ignition Voltage Engine Speed		20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
O2S Heater Control Circuit Bank 2 Sensor 1	P0050	This DTC checks the Heater Output Driver circuit for electrical integrity.	Voltage low during driver open state (indicates short-to-ground or open circuit) or voltage high during driver closed state (indicates short to voltage).		Ign Switch position Ignition Voltage Engine Speed		20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
HO2S Heater Resistance Bank 1 Sensor 1	P0053	Detects an oxygen sensor heater having an incorrect or out of range resistance value.	Learned Heater Resistance.	Calculated Heater Resistance < 2.8 ohms -OR- Calculated Heater Resistance > 9.5 ohms	No Active DTC's Coolant – IAT Coolant Temp Ignition Voltage Engine Soak Time Engine Run Time	-30.0 °C ≤ Coolant ≤ 45.0 °C < 32.0 volts > 28800 seconds	Once per valid cold start	2 trips Type B
HO2S Heater Resistance Bank 1 Sensor 2	P0054	Detects an oxygen sensor heater having an incorrect or out of range resistance value.	Learned Heater Resistance.	Calculated Heater Resistance < 4.1 ohms -OR- Calculated Heater Resistance > 10.8 ohms	No Active DTC's Coolant – IAT Coolant Temp Ignition Voltage Engine Soak Time Engine Run Time	> 28800 seconds	Once per valid cold start	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
O2S Heater Control Circuit Bank 2 Sensor 2	P0056	This DTC checks the Heater Output Driver circuit for electrical integrity.	Voltage low during driver open state (indicates short-to-ground or open circuit) or voltage high during driver closed state (indicates short to voltage).		Ign Switch position Ignition Voltage Engine Speed		20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
HO2S Heater Resistance Bank 2 Sensor 1	P0059	Detects an oxygen sensor heater having an incorrect or out of range resistance value.	Learned Heater Resistance.	Calculated Heater Resistance < 2.8 ohms -OR- Calculated Heater Resistance > 9.5 ohms	Coolant – IAT Coolant Temp Ignition Voltage Engine Soak Time Engine Run Time	> 28800 seconds < 3.00 seconds	Once per valid cold start	2 trips Type B
HO2S Heater Resistance Bank 2 Sensor 2	P0060	Detects an oxygen sensor heater having an incorrect or out of range resistance value.	Learned Heater Resistance.	Calculated Heater Resistance < 4.1 ohms -OR- Calculated Heater Resistance > 10.8 ohms	No Active DTC's Coolant – IAT Coolant Temp Ignition Voltage Engine Soak Time Engine Run Time	-30.0 °C ≤ Coolant ≤ 45.0 °C < 32.0 volts > 28800 seconds	Once per valid cold start	2 trips Type B
MAP / MAF / Throttle Position Correlation	P0068	Detect when MAP and MAF do not match estimated engine airflow as established by the TPS	1) Difference between measured MAP and estimated MAP exceeds threshold (kPa), or P0651 (5 Volt Ref), or P0107 (MAP circuit low), or P0108 (MAP circuit high) have failed this key cycle, then MAP portion of diagnostic fails	Table, f(TPS). See supporting tables	Engine Speed	> 800 RPM Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	Continuously fail MAP and MAF portions of diagnostic for 0.1875 sec Continuous in primary processor	Trips: 1 Type: A MIL: YES

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			2) Absolute difference between MAF and estimated MAF exceed threshold (grams/sec), or P0102 (MAF circuit low), or P0103 (MAF circuit hi) have failed this key cycle, or maximum MAF versus RPM (Table) is greater than or equal to maximum MAF versus battery voltage, then MAF portion of diagnostic fails					
Barometric Pressure (BARO) - Supercharger Inlet Pressure Correlation	P006D	Compares baro sensor to the calculated baro estimate (part throttle calculation or unthrottled Supercharger Inlet Pressure)	Difference between baro sensor reading and estimated baro when distance since last estimated baro update OR Difference between baro sensor reading and estimated baro when distance since last optimated baro	> 15.0 kPa <= 0.01 miles > 15.0 kPa	No Active DTCs:	AmbientAirPressCktFA ECT_Sensor_Ckt_FA IAT_SensorFA MAF_SensorFA AfterThrottlePressureFA_SC TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA	20 failures out of 25 samples 1 sample every 250 msec	Type B 2 trips
			baro sensor reading and estimated baro	> 15.0 kPa				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Intake Air Temperature Sensor 2 Circuit Performance	P0096	Detects an IAT2 sensor that has stuck in range by comparing to IAT and engine coolant temperature at startup	ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up ECT - Power Up IAT2) > ABS(Power Up ECT - Power Up IAT)	> 20 deg C	Time between current ignition cycle and the last time the engine was running No Active DTCs:	> 28800 seconds ECT_Sensor_FA ECT_Sensor_Ckt_FA IAT_SensorFA IAT2_SensorFA	Executes once at the beginning of each ignition cycle if enable conditions are met	Type B 2 trips
			AND P0116 is passing			P0116 Test Aborted = FALSE P0116 Test Complete =		
			o rro is passing			TRUE		
Intake Air Temperature Sensor 2 Circuit Low (High Temperature)	P0097	Detects a continuous short to ground in the IAT 2 signal circuit or the IAT 2 sensor	Raw IAT 2 Input	< 45 Ohms (~150 deg C)	Engine Run Time Coolant Temp Vehicle Speed No Active DTCs:	> 0.0 seconds < 150 deg C >= 0.00 MPH ECT_Sensor_Ckt_FA ECT_Sensor_Ckt_FP VehicleSpeedSensorError	50 failures out of 63 samples 1 sample every 100 msec	Type B 2 trips
Intake Air Temperature Sensor 2 Circuit High (Low Temperature)	P0098	Detects a continuous open circuit in the IAT 2 signal circuit or the IAT 2 sensor	Raw IAT 2 Input	> 420000 Ohms (~-60 deg C)	Engine Run Time Coolant Temp Vehicle Speed Engine Air Flow No Active DTCs:	> 0.0 seconds > -40 deg C <= 318.00 MPH >= 512 gm/sec ECT_Sensor_Ckt_FA ECT_Sensor_Ckt_FP VehicleSpeedSensorError MAF_SensorFA MAF_SensorFP MAF_SensorTFTKO	50 failures out of 63 samples 1 sample every 100 msec	Type B 2 trips
Radiator Coolant Temp Sensor Circuit Low Voltage	P00B3		RCT Resistance (@ 150°C)	< 55 Ohms	Engine run time Or IAT min	_		2 trips Type B

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
<u> </u>							Continuous	
Radiator Coolant Temp Sensor Circuit High Voltage	P00B4	Circuit Continuity This DTC detects a short to high or open in the RCT signal circuit or the RCT sensor.	RCT Resistance (@ -60°C)	> 160500 Ohms	Or	> 10.0 seconds ≥ -7.0 °C	5 failures out of 25 samples 1 sec /sample Continuous	2 trips Type B
Radiator Coolant Temp - Engine Coolant Temp (ECT) Correlation		This DTC detects a difference between ECT and RCT after a soak condition.	power up & RCT at power up is ≥ an IAT based threshold table	See "P00B6: Fail if power up ECT exceeds RCT by these values" in the Supporting tables section	No Active DTC's	VehicleSpeedSensor_FA IAT_SensorCircuitFA RCT_Sensor_Ckt_FA ECT_Sensor_Ckt_FA IgnitionOffTimeValid	1 failure 500 msec /sample Once per valid cold start	2 trips Type B
			2) Absolute difference between ECT at power up & RCT at power up is > by 19.3 C and a block heater has not been detected.		Engine Off Soak Time Non-volatile memory initization	TimeSinceEngineRunningValid > 28800 seconds = Not occurred		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			3) ECT at power up >					
			IAT at power up by					
			19.3 C and the time					
			spent cranking the					
			engine without					
			starting is greater					
			than 10.0 seconds					
			with the					
			LowFuelConditionDia					
			g	= False	Test complete this trip	= False		
					Test aborted this trip			
						≥ -7 °C		
					LowFuelCondition			
						= False		
					_		1	
					Block Heater d	etection is enabled	1	
						he following occurs:]	
					1) ECT at power up > IAT		1	
					at power up by			
					Cranking time	< 10.0 Seconds]	
							I	
					Block Heate	r is detected and	1	
					diagnostic is a	borted when 1)or 2)		
						stic is aborted when		
					3) or	4) occurs:]	
					1a) Vehicle drive time	> 400 Seconds with	1	
					1b) Vehicle speed	> 14.9 MPH and		
					1c) Additional Vehicle			
					drive time is provided to			
					1a when Vehicle speed is			
					below 1b as follows:	0.00 times the seconds with		
						vehicle speed below 1b		
					1d) IAT drops from power			
						≥ 3.3 °C		
					2a) ECT drops from			
					power up ECT	≥ 1 °C Within		
					2b) Engine run time	≤ 30 Seconds		
							1	
					3) Engine run time with			
					vehicle speed below 1b	> 1800 Seconds		
					4) Minimum IAT during		1	
					test	> -7.0 °C		
							1	
L				1	1	1	1	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Mass Air Flow	P0101	Determines if the MAF	Filtered Throttle		Engine Speed	>= 450 RPM	Continuous	Туре В
System		sensor is stuck within	Model Error	<= 250 kPa*(g/s)	Engine Speed	<= 6700 RPM		2 trips
Performance		the normal operating	AND	(5 /	Coolant Temp	> -7 Deg C	Calculation are	
(naturally		range	ABS(Measured Flow		Coolant Temp	< 125 Deg C	performed every	
aspirated)			- Modeled Air Flow)		Intake Air Temp	> -20 Deg C	12.5 msec	
			Filtered	> 12 grams/sec	Intake Air Temp	< 125 Deg C		
			AND		Minimum total weight			
			ABS(Measured MAP		factor (all factors			
			– MAP Model 2)		multiplied together)			
			Filtered	> 15.0 kPa				
						>= 0.00		
						Filtered Throttle Model		
						multiplied by TPS Residual		
						Weight Factor based on RPM		
						Modeled Air Flow multiplied		
						by MAF Residual Weight		
						Factor based on RPM and		
						MAF Residual Weight Factor		
						Based on MAF Estimate		
						Bassa sir iii ii Esiinats		
						MAD Madal O multiplied by		
						MAP Model 2 multiplied by		
						MAP2 Residual Weight Factor based on RPM		
						racioi baseu on Rrivi		
						See table "IFRD Residual		
						Weighting Factors".		
					No Active DTCs:	MAP_SensorCircuitFA		
						EGRValve_FP		
						EGRValvePerformance_FA		
						MAF_SensorCircuitFA		
						CrankSensor_FA		
						ECT_Sensor_FA		
						ECT_Sensor_Ckt_FA		
						IAT_SensorFA		
						IAT_SensorFP		
						CylDeacSystemTFTKO		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Mass Air Flow	P0101	Determines if the MAF			Engine Speed	>= 450 RPM	Continuous	Type E
System		sensor is stuck within	"Supercharger Intake		Engine Speed	<= 6200 RPM		2 trips
Performance		the normal operating	Flow Rationality		Coolant Temp	> -7 Deg C	Calculation are	
supercharged)		range	Diagnostic Failure		Coolant Temp	< 125 Deg C	performed every	
			Matrix" for		Intake Air Temp	> -20 Deg C	12.5 msec	
			combinations of		Intake Air Temp	< 125 Deg C		
			model failures that		Minimum total weight			
			can set this DTC.		factor (all factors			
					multiplied together)			
	TPS model fails when Filtered Throttle Model Error > 400 kPa*(g/s)	TPS model fails when			>= 0.00 RPM			
		Filtered Throttle			Filtered Throttle Model			
		> 400 kPa*(g/s)		multiplied by TPS Residual				
						Weight Factor based on RPM		
			MAF model fails when	odel fails when				
			ABS(Measured Flow			Modeled Air Flow multiplied		
			– Modeled Air Flow)			by MAF Residual Weight		
			Filtered	> 21 grams/sec		Factor based on RPM and		
						MAF Residual Weight Factor		
			MAP1 model fails			Based on MAF Estimate		
			when					
			ABS(Measured MAP					
			– MAP Model 1)			MAP Model 1 multiplied by		
			Filtered	> 22.0 kPa		MAP1 Residual Weight		
						Factor based on RPM and		
			MAP2 model fails			Boost Residual Weight Factor		
			when			based on % of Boost		
			ABS(Measured MAP					
			– MAP Model 2)					
			Filtered	> 22.0 kPa		MAP Model 2 multiplied by		
						MAP2 Residual Weight		
			SCIAP1 model fails			Factor based on RPM and		
			when			Boost Residual Weight Factor		
			ABS(Measured			based on % of Boost		
		SCIAP – SCIAP						
			Model 1) Filtered					
				> 14.0 kPa			1	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			SCIAP2 model fails when ABS(Measured SCIAP – SCIAP Model 2) Filtered	> 14.0 kPa		SCIAP Model 1 multiplied by SCIAP1 Residual Weight Factor based on RPM and Boost Residual Weight Factor based on % of Boost		
						SCIAP Model 2 multiplied by SCIAP2 Residual Weight Factor based on RPM and Boost Residual Weight Factor based on % of Boost		
						See table "IFRD Residual Weighting Factors".		
					No Active DTCs:	MAP_SensorCircuitFA EGRValve_FP EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensor_FA ECT_Sensor_FA ECT_Sensor_Ckt_FA IAT_SensorFP CylDeacSystemTFTKO IAT2_SensorFA IAT2_SensorFA IAT2_SensorCircuitFP SCIAP_SensorCircuitFP AmbientAirDefault_SC		
Mass Air Flow Sensor Circuit Low Frequency	P0102	Detects a continuous short to low or a open in either the signal circuit or the MAF sensor	MAF Output	<= 291 Hz (~ 1.02g/sec)	Engine Run Time Engine Speed Ignition Voltage Above criteria present for a period of time	> 1.0 seconds >= 400 RPM >= 9.0 Volts >= 1.0 seconds	400 failures out of 500 samples 1 sample every cylinder firing event	Type B 2 trips

		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Mass Air Flow Sensor Circuit High Frequency		Detects a high frequency output from the MAF sensor	MAF Output	>= 14500 Hz (~ 1037.5 gm/sec)	Engine Run Time Engine Speed Ignition Voltage Above criteria present for a period of time	> 1.0 seconds >= 400 RPM >= 9.0 Volts >= 1.0 seconds	400 failures out of 500 samples 1 sample every cylinder firing event	2 trips
Manifold Absolute Pressure Sensor Performance (naturally aspirated)		Determines if the MAP sensor is stuck within the normal operating range	Filtered Throttle Model Error AND ABS(Measured MAP – MAP Model 1) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered	<= 250 kPa*(g/s) > 15.0 kPa > 15.0 kPa	Engine Speed Coolant Temp Coolant Temp Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together)	>= 450 RPM <= 6700 RPM > -7 Deg C < 125 Deg C > -20 Deg C < 125 Deg C > -125 Deg C > -20 Deg C > -20 Deg C > -20 Deg C > -20 Deg C >= 0.00 Filtered Throttle Model multiplied by TPS Residual Weight Factor based on RPM MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors".	Continuous Calculations are performed every 12.5 msec	Type B 2 trips
					No Active DTCs:	MAP_SensorCircuitFA EGRValve_FP EGRValvePerformance_FA MAF_SensorCircuitFA		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						CrankSensorFA		
						ECT_sensor_FA		
						ECT_Sensor_FP		
						IAT_SensorFA		
						IAT_SensorCircuitFP		
						CylDeacSystemTFTKO		
Manifold Absolute	P0106	Determines if the MAP	See table		Engine Speed	>= 450 RPM	Continuous	Type B
Pressure Sensor		sensor is stuck within	"Supercharger Intake		Engine Speed	<= 6200 RPM		2 trips
Performance		the normal operating	Flow Rationality		Coolant Temp	> -7 Deg C	Calculation are	
(supercharged)		range	Diagnostic Failure		Coolant Temp	< 125 Deg C	performed every	
			Matrix" for		Intake Air Temp	> -20 Deg C	12.5 msec	
			combinations of		Intake Air Temp	< 125 Deg C		
			model failures that		Minimum total weight			
			can set this DTC.		factor (all factors			
					multiplied together)			
			TPS model fails when			>= 0.00		
			Filtered Throttle					
			Model Error	> 400 kPa*(g/s)		Filtered Throttle Model		
						multiplied by TPS Residual		
			MAF model fails when			Weight Factor based on RPM		
			ABS(Measured Flow					
			– Modeled Air Flow)			Modeled Air Flow multiplied		
			Filtered	> 21 grams/sec		by MAF Residual Weight		
						Factor based on RPM and		
			MAP1 model fails			MAF Residual Weight Factor		
			when			Based on MAF Estimate		
			ABS(Measured MAP					
			- MAP Model 1)					
			Filtered	> 22.0 kPa		MAP Model 1 multiplied by		
						MAP1 Residual Weight		
			MAP2 model fails			Factor based on RPM and		
			when			Boost Residual Weight Factor		
			ABS(Measured MAP			based on % of Boost		
		– MAP Model 2)						
			· · · · · · · · · · · · · · · · · · ·	> 22.0 kPa				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						MAP Model 2 multiplied by		
						MAP2 Residual Weight		
i						Factor based on RPM and		
						Boost Residual Weight Factor		
						based on % of Boost		
			SCIAP1 model fails					
1			when					
			ABS(Measured					
			SCIAP - SCIAP					
			Model 1) Filtered	> 14.0 kPa				
1								
1						SCIAP Model 1 multiplied by		
			SCIAP2 model fails			SCIAP1 Residual Weight		
			when			Factor based on RPM and		
			ABS(Measured			Boost Residual Weight Factor		
			SCIAP – SCIAP			based on % of Boost		
			Model 2) Filtered	> 14.0 kPa				
1			,					
1						SCIAP Model 2 multiplied by		
						SCIAP2 Residual Weight		
						Factor based on RPM and		
						Boost Residual Weight Factor		
						based on % of Boost		
1								
1						See table "IFRD Residual		
1						Weighting Factors".		
1						Trong it dottors i		
1					No Active DTCs:	MAP_SensorCircuitFA		
						EGRValve_FP		
1						EGRValvePerformance_FA		
						MAF_SensorCircuitFA		
1						CrankSensorFA		
1						ECT_sensor_FA		
1						ECT_Sensor_FP		
1						IAT_SensorFA		
						IAT_SensorCircuitFP		
1						CylDeacSystemTFTKO		
						IAT2_SensorFA		
1						IAT2_SensorCircuitFP		
1						SCIAP_SensorCircuitFA		
1						SCIAP_SensorCircuitFP		
						AmbientAirDefault_SC		

•		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Manifold Absolute Pressure Sensor Circuit Low	P0107	Detects a continuous short to low or open in either the signal circuit or the MAP sensor.	MAP Voltage	< 3.0 % of 5 Volt Range (0.2 Volts = 3.5 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type B 2 trips
Manifold Absolute Pressure Sensor Circuit High	P0108	Detects an open sensor ground or continuous short to high in either the signal circuit or the MAP sensor.	MAP Voltage	> 90.0 % of 5 Volt Range (4.5 Volts = 115.1 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type B 2 trips
Intake Air Temperature Sensor Circuit Performance	P0111	that has stuck in range by comparing to IAT2 and engine coolant temperature at startup	ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up ECT - Power Up IAT) > ABS(Power Up ECT - Power Up IAT2) AND P0116 is failing	> 20 deg C	Time between current ignition cycle and the last time the engine was running No Active DTCs:		Executes once at the beginning of each ignition cycle if enable conditions are met	Type B 2 trips
Intake Air Temperature Sensor Circuit Low (High Temperature)		Detects a continuous short to ground in the IAT signal circuit or the IAT sensor	Raw IAT Input	< 45 Ohms (~150 deg C)	Engine Run Time Coolant Temp Vehicle Speed No Active DTCs:	< 150 deg C >= 0.00 MPH	50 failures out of 63 samples 1 sample every 100 msec	Type B 2 trips

Component/			Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Intake Air Temperature Sensor Circuit High (Low Temperature)	P0113	Detects a continuous open circuit in the IAT signal circuit or the IAT sensor	Raw IAT Input	> 163000 Ohms (~-60 deg C)	Engine Run Time Coolant Temp Vehicle Speed Engine Air Flow No Active DTCs:	> 0.0 seconds > -40 deg C <= 318.00 MPH <= 512 gm/sec ECT_Sensor_Ckt_FA ECT_Sensor_Ckt_FP VehicleSpeedSensorError MAF_SensorFA MAF_SensorFP MAF_SensorFTKO	50 failures out of 63 samples 1 sample every 100 msec	Type B 2 trips
Engine Coolant Temperature (ECT) Sensor Performance	P0116	This DTC detects ECT temp sensor stuck in mid range.	lookup value after a minimum 28800		Non-volatile memory	VehicleSpeedSensor_FA IAT_SensorFA ECT_Sensor_Ckt_FA IgnitionOffTimeValid TimeSinceEngineRunningValid	1 failure 500 msec /sample Once per valid cold start	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			3) ECT at power up >					
			IAT at power up by					
			15.0 C after a					
			minimum 28800					
			seconds soak and the					
			time spent cranking					
			the engine without					
			starting is greater					
			than 10.0 seconds					
			with the					
			LowFuelConditionDia					
			g	= False	Test aborted this trip	n = False		
				1 0.00		T ≥ -7 °C		
					LowFuelCondition Diag			
					Low-delCondition Diag	9 = False		
						- I alse		
					Block Hoator	detection is enabled	┪	
						the following occurs:		
					1) ECT at power up > IA		-	
					at power up by			
					2) Cranking time	e < 10.0 Seconds		
					2) Cranking time	e	_	
					Block Hoats	er is detected and	7	
						aborted when 1)or 2)		
						ostic is aborted when		
						r 4) occurs:		
						e > 400 Seconds with	-	
					1b) Vehicle speed			
					1c) Additional Vehicle			
					drive time is provided to 1a when Vehicle speed is			
					Delow 15 as follows	0.00 times the seconds with		
					1 d) IAT d f	vehicle speed below 1b		
					1d) IAT drops from powe			
					2a) ECT drops fron	T ≥ 8.0 °C	-	
						n T > 256 °C Within		
					2b) Engine run time	e > 0 Seconds	-	
					3) Engine was time			
					3) Engine run time with			
	I				vehicle speed below 18	> 1800 Seconds		

Code	Description	Criteria	IV-1	I —		1	
			Value	Parameters	Conditions	Required	illum.
				4) Minimum IAT during			
				test	≤ -7 °C		
	This DTC detects a	ECT Resistance				5 failures out of 6	2 trips
		(@ 150°C)	< 45 Ohms			samples	Type B
	the ECT Sensor.					1 000	
						/Sample	
						Continuous	
						Continuous	
P0118	Circuit Continuity	ECT Resistance				5 failures out of 6	2 trips
				Engine run time	> 10.0 seconds	samples	Type B
				Or			
				IAT min	≥ -7.0 °C		
	or the ECT sensor.					1 sec	
						/sample	
						Continuous	
P0120	Detects a continuous	Secondary TPS1			Run/crank voltage or	19 / 39 counts or	Trips:
			0.325				1
			0.020			continuous; 12.5	Type:
	the secondary		4.75		false, else the failure will be	ms/count in the	A
					reported for all conditions	secondary	MIL:
						processor	YES
	primary processor						
					No 5 V reference #2 error		
					No E V reference #2 DTC		
P0121	Determines if the	Filtered Throttle		Engine Speed	,	Continuous	Туре В
			> 250 kPa*(g/s)				2 trips
						Calculation are	
	•			Coolant Temp		performed every	
		Modeled Air Flow)		Intake Air Temp	> -20 Deg C	12.5 msec	
		Filtered	> 12 grams/sec	Intake Air Temp	< 125 Deg C		
				·			
F	P0120	short to ground in the ECT signal circuit or the ECT sensor. Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor. P0120 Detects a continuous or intermittent short or open in TPS1 circuit on the secondary processor but sensor is in range on the primary processor Determines if the Throttle Position Sensor input is stuck	short to ground in the ECT signal circuit or the ECT sensor. P0118 Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor. P0120 Detects a continuous or intermittent short or open in TPS1 circuit on the secondary processor but sensor is in range on the primary processor P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range SECT Resistance (@ -60°C) P0120 Detects a continuous or intermittent short or open in TPS1 voltage < or Secondary TPS1 Voltage > P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range	short to ground in the ECT signal circuit or the ECT sensor. P0118 Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor. P0120 Detects a continuous or intermittent short or open in TPS1 circuit on the secondary processor but sensor is in range on the primary processor P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range SECT Resistance (@ -60°C) > 450000 Ohms P0120 Obtects a continuous or intermittent short or open in TPS1 Voltage < or Secondary TPS1 Voltage > 4.75 P0121 Determines if the Throttle Model Error AND ABS(Measured Flow) ABS(Measured Flow) AMS(Measured Flow) AMS(Measured Flow) AMS(Measured Flow) AMS(Measured Flow)	short to ground in the ECT signal circuit or the ECT sensor. P0118 Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor. P0120 Detects a continuous or intermittent short or open in TPS1 circuit on the secondary processor but sensor is in range on the primary processor P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range P0121 Determines if the Throttle Position Sensor input is stuck within the normal operating range P0122 Secondary TPS1 (@ 150°C) < 45 Ohms Engine run time Or IAT min P0123 O.325 Or Secondary TPS1 Voltage < 0.325 Or Secondary TPS1 Voltage > 4.75 Engine Speed Engine Speed Coolant Temp Coolant Temp Intake Air Temp	short to ground in the ECT signal circuit or the ECT sensor. Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor.	short to ground in the ECT signal circuit or the ECT sensor. Circuit Continuity This DTC detects a short to high or open in the ECT signal circuit or the ECT sensor.

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Minimum total weight factor (all factors multiplied together)			
						>= 0.00		
						Filtered Throttle Model multiplied by TPS Residual Weight Factor based on RPM		
						Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate		
						See table "IFRD Residual Weighting Factors".		
					No Active DTCs:	MAP_SensorCircuitFA EGRValve_FP EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensorFA ECT_sensor_FA ECT_Sensor_FP IAT_SensorFA IAT_SensorCircuitFP CylDeacSystemTFTKO		
Throttle Position Sensor Performance (supercharged)	P0121	Determines if the Throttle Position Sensor input is stuck within the normal operating range	See table "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC.		Engine Speed Engine Speed Coolant Temp Coolant Temp Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together)	>= 450 RPM <= 6200 RPM > -7 Deg C < 125 Deg C > -20 Deg C < 125 Deg C >= 0.00	Continuous Calculation are performed every 12.5 msec	Type B 2 trips

Component/		Monitor Strategy		Threshold				MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			TPS model fails when					
			Filtered Throttle			Filtered Throttle Model		
			Model Error	> 400 kPa*(g/s)		multiplied by TPS Residual		
						Weight Factor based on RPM		
			MAF model fails when					
ı			ABS(Measured Flow			Modeled Air Flow multiplied		
			– Modeled Air Flow)			by MAF Residual Weight		
			Filtered	> 21 grams/sec		Factor based on RPM and		
						MAF Residual Weight Factor		
			MAP1 model fails			Based on MAF Estimate		
			when					
			ABS(Measured MAP					
			– MAP Model 1)			MAP Model 1 multiplied by		
			Filtered	> 22.0 kPa		MAP1 Residual Weight		
						Factor based on RPM and		
			MAP2 model fails			Boost Residual Weight Factor based on % of Boost		
			when			based on 70 of boost		
			ABS(Measured MAP – MAP Model 2)					
			Filtered	> 22 0 kDa		MAD Model 2 multiplied by		
			i illered	> 22.0 kPa		MAP Model 2 multiplied by MAP2 Residual Weight		
			SCIAP1 model fails			Factor based on RPM and		
			when			Boost Residual Weight Factor		
			ABS(Measured			based on % of Boost		
			SCIAP – SCIAP					
				> 14.0 kPa				
			,			SCIAP Model 1 multiplied by		
			SCIAP2 model fails			SCIAP1 Residual Weight		
			when			Factor based on RPM and		
			ABS(Measured			Boost Residual Weight Factor		
			SCIAP – SCIAP			based on % of Boost		
			Model 2) Filtered	> 14.0 kPa				
						OCIAD Marting or 18515 At		
						SCIAP Model 2 multiplied by		
						SCIAP2 Residual Weight Factor based on RPM and		
						Boost Residual Weight Factor		
						based on % of Boost		
						Basea on 70 of Boost		

•		0,	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					No Active DTCs:	See table "IFRD Residual Weighting Factors". MAP_SensorCircuitFA EGRValve_FP EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensorFA ECT_sensor_FA ECT_Sensor_FP IAT_SensorFa IAT_SensorCircuitFP CylDeacSystemTFTKO IAT2_SensorFA IAT2_SensorCircuitFP SCIAP_SensorCircuitFP SCIAP_SensorCircuitFP		
TPS1 Circuit Low	P0122	Detects a continuous or intermittent short or open in TPS1 circuit on both processors or just the primary processor		0.325		AmbientAirDefault_SC Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the primary processor	Trips: 1 Type: A MIL: YES
			Secondary TPS1 Voltage <	0.325		No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
TPS1 Circuit High	P0123	Detects a continuous or intermittent short in TPS1 circuit on both processors or just the primary processor		4.75		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the primary processor	Trips: 1 Type: A MIL: YES

Component/	Fault	•	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Secondary TPS1 Voltage >	4.75		No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
Engine Coolant Temperature Below Stat Regulating Temperature	P0128	This DTC detects if the engine coolant temperature rises too slowly due to an ECT or Cooling system fault	Actual accumulated airflow is > predicted accumulated airflow	conditions" in the Supporting tables section.	Engine not run time Engine run time Fuel Condition Range #1 (Primary) Test ECT at start run Average Airflow Vehicle speed Range #2 (Alternate) Test ECT at start run Average Airflow Vehicle speed	MAF_SensorFA TPS_Performance_FA TPS_FA TPS_ThrottleAuthorityDefault ed IAT_SensorFA ECT_Sensor_Ckt_FA ECT_Sensor_Perf_FA VehicleSpeedSensor_FA ≥ 1800 seconds ≥ 120 seconds Ethanol ≤ 87% ≤ 70.0 °C ≥ 5.0 gps > 5 mph for at least 2.4 miles	Once per ignition key cycle	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					2) Zero Airflow accumulated when airflow is 3) With AFM active Airflow added to acculmulated is multiplyed by	50.0 gps < 12.0 gps 0.50%		
Engine Coolant Temperature Below Stat Regulating Temperature (For applications with a two coolant sensors)	P0128	temperature rises too slowly due to an ECT or Cooling system fault	Engine run time is accumulated when airflow is ≥ 17 grams per sec during Range #1 or #2: Range #1 (Primary) ECT reaches target temperature of 75.0 °C when IAT min is < 54.5°C and ≥ 10.0°C.	See "P0128: Maximum Accumulated Time for IAT and Start-up ECT conditions" in the Supporting tables section.	Engine not run time Engine	IAT_SensorFA THMR_RCT_Sensor_Ckt_FA THMR_ECT_Sensor_Ckt_FA	1 failure to set DTC 1 sec /sample Once per ignition key cycle	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Range #2 (Alternate) ECT reaches target temperature of 65.0		Fred Condition			
			°C		Fuel Condition	Ethanol ≤ 87%		
			when IAT min is < 10.0°C and ≥ -7.0°C.		Range #1 (Primary) Test			
					ECT at start run Average Airflow	-7.0 ≤ ECT ≤ 70.0 °C ≥ 17.0 gps		
					Range #2 (Alternate) Test ECT at start run Average Airflow	-7.0 ≤ ECT ≤ 60.0 °C ≥ 17.0 gps		
Supercharger Inlet Absolute Pressure (SCIAP) Sensor Performance	P012B	Determines if the Supercharger Inlet Absolute Pressure Sensor input is stuck within the normal operating range	See table "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC.		Engine Speed Engine Speed Coolant Temp Coolant Temp Intake Air Temp Intake Air Temp Minimum total weight factor (all factors multiplied together)	>= 450 RPM <= 6200 RPM > -7 Deg C < 125 Deg C > -20 Deg C < 125 Deg C	Continuous Calculation are performed every 12.5 msec	Type E 2 trips
			TPS model fails when Filtered Throttle Model Error MAF model fails when	> 400 kPa*(g/s)		>= 0.00 Filtered Throttle Model multiplied by TPS Residual Weight Factor based on RPM		
			ABS(Measured Flow – Modeled Air Flow) Filtered MAP1 model fails when	> 21 grams/sec		Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			ABS(Measured MAP					
			– MAP Model 1)			MAP Model 1 multiplied by		
			Filtered	> 22.0 kPa		MAP1 Residual Weight		
						Factor based on RPM and		
			MAP2 model fails			Boost Residual Weight Factor		
			when			based on % of Boost		
						2000 011 /0 01 20000		
			ABS(Measured MAP					
			– MAP Model 2)					
			Filtered	> 22.0 kPa		MAP Model 2 multiplied by		
						MAP2 Residual Weight		
			SCIAP1 model fails			Factor based on RPM and		
			when			Boost Residual Weight Factor		
			ABS(Measured			based on % of Boost		
			SCIAP - SCIAP					
			Model 1) Filtered	> 14.0 kPa				
			, ,	11.01 4		SCIAP Model 1 multiplied by		
			SCIAP2 model fails			SCIAP1 Residual Weight		
						Factor based on RPM and		
			when					
			ABS(Measured			Boost Residual Weight Factor		
			SCIAP – SCIAP			based on % of Boost		
			Model 2) Filtered	> 14.0 kPa				
						SCIAP Model 2 multiplied by		
						SCIAP2 Residual Weight		
						Factor based on RPM and		
						Boost Residual Weight Factor		
						based on % of Boost		
						2000 011 /0 01 20000		
						See table "IFRD Residual		
						Weighting Factors".		
					No Active DTCs:	MAP_SensorCircuitFA		
						EGRValve_FP		
						EGRValvePerformance_FA		
						MAF_SensorCircuitFA		
						CrankSensorFA		
						ECT_sensor_FA		
						ECT_Sensor_FP		
						IAT_SensorFA		
						IAT_SensorCircuitFP		
				1	1	CylDeacSystemTFTKO		

•		•	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters		Required	illum.
						IAT2_SensorFA IAT2_SensorCircuitFP SCIAP_SensorCircuitFA SCIAP_SensorCircuitFP AmbientAirDefault_SC		
Supercharger Inlet Absolute Pressure (SCIAP) Sensor Circuit Low	P012C	Detects a continuous short to low or open in either the signal circuit or the SCIAP sensor.	SCIAP Voltage	< 3.0 % of 5 Volt Range (0.2 Volts = 3.5 kPa)	Continuous	_	320 failures out of 400 samples 1 sample every 12.5 msec	Type B 2 trips
Supercharger Inlet Absolute Pressure (SCIAP) Sensor Circuit High	P012D	Detects an open sensor ground or continuous short to high in either the signal circuit or the SCIAP sensor.	SCIAP Voltage	> 90.0 % of 5 Volt Range (4.5 Volts = 115.0 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type B 2 trips
O2S Circuit Low Voltage Bank 1 Sensor 1	P0131	This DTC determines if the O2 sensor circuit is shorted to low.		Oxygen Sensor signal is < 50 mvolts		MAP_SensorFA AIR System FA Ethanol Composition Sensor FA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA = Not active = Not active	380 failures out of 475 samples Frequency: Continuous in 100 milli - second loop	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
System	Code	Description	Сптепа	value	EGR intrusive test System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Diag Equivalence Ratio Throttle Position Fuel Control State Closed Loop Active All Fuel Injectors for active Cylinders Fuel Condition Fuel State All of the	= Not active 10.0 volts < system voltage< 32.0 volts = Not active = False 0.9922 ≤ equiv. ratio ≤ 1.0137 3 % <= Throttle <= 70 % = Closed Loop = TRUE	Required	illum.
O2S Circuit High Voltage Bank 1 Sensor 1	P0132	This DTC determines if the O2 sensor circuit is shorted to high.		Oxygen Sensor signal is > 1050 mvolts		TPS_ThrottleAuthorityDefault ed MAP_SensorFA MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA = Not active = Not active = Not active	100 failures out of 125 samples Frequency: Continuous in 100 milli - second loop	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Diag Equivalence Ratio Throttle Position Fuel Control State Fuel Control State Closed Loop Active All Fuel Injectors for active Cylinders Fuel State	10.0 volts < system voltage< 32.0 volts = Not active = False 0.9922 ≤ equiv. ratio ≤ 1.0137 0.0 % <= Throttle <= 70.0 % = Closed Loop not = Power Enrichment = TRUE		
					. 45. 55.14.1.			
					All of the	above met for	1	
					Time	> 2 seconds		
O2S Slow Response Bank 1 Sensor 1	P0133	This DTC determines if the O2 sensor response time is degraded.	The average response time is caluclated over the test time, and compared to the threshold. Refer to "P0133 - O2S Slow Response Bank 1 Sensor 1" Pass/Fail Threshold table in the Supporting Tables tab.		No Active DTC's	TPS_ThrottleAuthorityDefault ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA	Sample time is 60 seconds Frequency: Once per trip	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						EthanolCompositionSensor_F		
						A		
						EngineMisfireDetected_FA		
					Bank 1 Sensor 1 DTC's			
						= P0131, P0132 or P0134		
						10.0 volts < system voltage<		
					System Voltage			
					EGR Device Control			
					Idle Device Control			
					Fuel Device Control			
					AIR Device Control			
					7 til C Devide Golitici	- Not dolive		
					Low Fuel Condition Diag	= False		
						= Not Valid, See definition of		
						Green Sensor Delay Criteria		
						(B1S1) in Supporting Tables		
					Green O2S Condition			
					O2 Heater on for			
					Learned Htr resistance			
					Engine Coolant			
						> -40 °C		
					Engine Run Time			
					-			
					Time since any AFM			
						> 0.0 seconds		
					Time since Purge On to			
						> 0.0 seconds		
					Time since Purge Off to			
						> 0.0 seconds		
					Purge duty cycle	>= 0 % duty cycle		
						15 gps <= engine airflow <=		
					Engine airflow			
						1000 <= RPM <= 3000		
						< 87 % Ethanol		
						> 70 kpa		
					Throttle Position	>= 5 %		
					1. 5.40 5.	l		
					Low Fuel Condition Diag			
					Fuel Control State	= Closed Loop		
					Closed Loop Active			
					LTM fuel cell			
					Transient Fuel Mass			
					Baro	= Not Defaulted		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Fuel State Commanded Proportional	not = Power Enrichment DFCO not active >= 0.0 %		
						above met for		
					Time	> 3.0 seconds		
O2S Circuit Insufficient Activity Bank 1 Sensor 1	P0134	This DTC determines if the O2 sensor circuit is open.		350 mvolts < Oxygen Sensor signal < 550 mvolts	System Voltage AFM Status Heater Warm-up delay Predicted Exhaust Temp	TPS_ThrottleAuthorityDefault ed MAF_SensorFA EthanolCompositionSensor_F A 10.0 volts < system voltage< 32.0 volts = All Cylinders active = Complete	Minimum of 0 delta TPS changes required	2 trips Type B
					Engine Run Time Fuel	<= 87 % Ethanol	100msec loop	
O2S Heater Performance Bank 1 Sensor 1	P0135	This DTC determines if the O2 sensor heater is functioning properly by monitoring the current through the heater circuit.	Measured Heater Current.	Measured Heater current < 0.3 amps -OR- Measured Heater current > 3.1 amps	No Active DTC's System Voltage Heater Warm-up delay B1S1 O2S Heater Duty Cycle	10.0 volts < system voltage< 32.0 volts	8 failures out of 10 samples Frequency: 1 tests per trip 5 seconds delay between tests and 1 second execution rate	2 trips Type B

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					O2S Heater device			
					control	= Not active		
					A.II. 641			
						above met for		
					Time	> 120 seconds		
O2S Circuit Low	P0137	This DTC determines if		Oxygen Sensor	No Active DTC's	TPS_ThrottleAuthorityDefault		
Voltage Bank 1		the O2 sensor circuit is	Sensor Signal.	signal is < 50 mvolts		ed	540 samples	Type B
Sensor 2		shorted to low.				MAP_SensorFA		
						AIR System FA	Frequency:	
							Continuous in	
						Ethanol Composition Sensor	100 milli - second	
						FA	loop	
						EvapPurgeSolenoidCircuit_F A		
						EvapFlowDuringNonPurge_F		
						A		
						EvapVentSolenoidCircuit FA		
						EvapSmallLeak_FA		
						EvapEmissionSystem_FA		
						FuelTankPressureSnsrCkt_F		
						A		
						FuelInjectorCircuit_FA		
					AIR intrusive test			
					Fuel intrusive test			
					Idle intrusive test			
					EGR intrusive test			
						10.0 volts < system voltage<		
					System Voltage			
					EGR Device Control			
					Idle Device Control	= Not active		
					Fuel Device Control	= Not active		
					AIR Device Control	= Not active		
					Low Fuel Condition Diag	= False		
					Donation Diag	0.9922 ≤ equiv. ratio ≤ 1.0137		
					Equivalence Ratio			
						3 % <= Throttle <= 70 %		
					Fuel Control State			
					Closed Loop Active			

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					All of the	above met for	1	
					Time	> 2.0 seconds		
O2S Circuit High Voltage Bank 1 Sensor 2	P0138	This DTC determines if the O2 sensor circuit is shorted to high.		Oxygen Sensor signal is > 1050 mvolts	AIR intrusive test Fuel intrusive test Idle intrusive test Idle intrusive test EGR intrusive test EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Diag Equivalence Ratio Throttle Position Fuel Control State	= Not active = Not active 10.0 volts < system voltage< 32.0 volts = Not active = False 0.9922 ≤ equiv. ratio ≤ 1.0137 3.0 % <= Throttle <= 70.0 %	100 failures out of 125 samples Frequency: Continuous in 100 milli - second loop	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Fuel Condition All of the			
					Time	2 seconds		
O2 Sensor Slow Response Rich to Lean Bank 1 Sensor 2	P013A	This DTC determines if the post catalyst O2 sensor has Slow Response in a predefined Rich to Lean voltages range during Rich to Lean transition. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response.	Post O2 sensor normalized integral value is greater than the threshold. OR The Accumulated mass air flow monitored during the	1) B1S2 EWMA normalized integral value > 8.2 units OR 2) Accumulated air flow during slow rich to lean test > 75 grams (upper threshold is 450 mvolts and lower threshold is 150 mvolts)	B1S2 Failed this key	= Valid	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed	1 trips Type A EWMA

Component/	Fault		Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Green O2S Condition Low Fuel Condition Diag Post fuel cell	= False		
					DTC's Passed DTC's Passed	applicable)) = P013E (and P014A (if		
					DFCO mod	onditions are met: de is continued iated pedal input).		
O2 Sensor Slow Response Lean to Rich Bank 1 Sensor 2	P013B	transition. The diagnostic is an	Post O2 sensor normalized integral value is greater than the threshold. OR The Accumulated mass air flow monitored during the	1) B1S2 EWMA normalized integral value > 32.0 units OR 2) Accumulated air flow during slow lean to rich test > 150 grams (lower threshold is 350 mvolts and upper	No Active DTC's	TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA	Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive	1 trips Type A EWMA
		required rich threshold.		threshold is 650 mvolts)	R1S2 Failed this key	MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013A, P013E, P013F,	= TRUE, multiple tests per trip are allowed	
						P2270 or P2271		

Component/	Fault		Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					System Voltage Learned heater resistance ICAT MAT Burnoff delay Green O2S Condition Low Fuel Condition Diag Post fuel cell DTC's Passed DTC's Passed DTC's Passed DTC's Passed	= Valid = Not Valid = Not Valid, See definition of Green Sensor Delay Criteria (B1S2) in Supporting Tables tab. = False = enabled = P2270 (and P2272 (if applicable)) = P013E (and P014A (if applicable)) = P013A (and P013C (if applicable)) = P2271 (and P2273 (if applicable)) = P013F (and P014B (if		
						onditions are met: mode continued.		
						I		
O2 Sensor Slow Response Rich to Lean Bank 2 Sensor 2	P013C	This DTC determines if the post catalyst O2 sensor has Slow Response in a predefined Rich to Lean voltages range during Rich to Lean transition. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response.	The EWMA of the Post O2 sensor normalized integral value is greater than the threshold. OR The Accumulated mass air flow monitored during the Slow Response Test (between the upper and lower voltage thresholds) is greater than the airflow threshold.	1) B1S2 EWMA normalized integral value > 8.2 units OR 2) Accumulated air flow during slow rich to lean test > 75 grams (upper threshold is 450 mvolts and lower threshold is 150 mvolts)	No Active DTC's	TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed	1 trips Type A EWMA

		Monitor Strategy	Malfunction	Threshold	,	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
1						FuelInjectorCircuit_FA		
1						FuelTrimSystemB1_FA		
1						FuelTrimSystemB2_FA		
1						EngineMisfireDetected_FA		
1						EthanolCompositionSensor_F		
1						A		
1					B2S2 Failed this key	P013D, P014A, P014B,		
1					cycle	P2272 or P2273		
1						10.0 volts < system voltage<		
1					System Voltage	32.0 volts		
1					Learned heater			
1					resistance	= Valid		
1					ICAT MAT Burnoff delay	= Not Valid		
1						= Not Valid, See definition of		
1						Green Sensor Delay Criteria		
1						(B2S2) in Supporting Tables		
1					Green O2S Condition			
1								
1					Low Fuel Condition Diag	= False		
1					Post fuel cell			
1						= P2270 (and P2272 (if		
1					DTC's Passed			
1						= P013E (and P014A (if		
1					DTC's Passed			
1								
1					After above o	onditions are met:		
1						de is continued		
1						iated pedal input).		
1					,	,		
O2 Sensor Slow	P013D	This DTC determines if	The EWMA of the	1) B1S2 EWMA	No Active DTC's	TPS_ThrottleAuthorityDefault	Frequency:	1 trips
Response Lean		the post catalyst O2	Post O2 sensor	normalized integral		ed	Once per trip	Type A
to Rich Bank 2		sensor has Slow	normalized integral	value > 32.0 units			Note: if	EWMA
Sensor 2		Response in a	value is greater than				NaPOPD_b_Res	
1		predefined Lean to	the threshold.	OR			etFastRespFunc=	
1		Rich voltages range					FALSE for the	
1		during Lean to Rich	OR	2) Accumulated air			given Fuel Bank	
1		transition. The		flow during slow lean		ECT Sensor FA		
·		diagnostic is an						

Component/ Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
	increases the delivered A/F ratio to achieve the required rich threshold.	monitored during the Slow Response Test (between the lower	grams (lower threshold is 350 mvolts and upper threshold is 650 mvolts)	B2S2 Failed this key cycle System Voltage Learned heater resistance ICAT MAT Burnoff delay Green O2S Condition Low Fuel Condition Diag Post fuel cell DTC's Passed DTC's Passed DTC's Passed DTC's Passed DTC's Passed	MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013C, P014A, P014B, P2272 or P2273 10.0 volts < system voltage< 32.0 volts = Valid = Not Valid, See definition of Green Sensor Delay Criteria (B2S2) in Supporting Tables tab. = False = enabled = P2270 (and P2272 (if applicable)) = P013E (and P014A (if applicable)) = P013A (and P013C (if applicable)) = P2271 (and P2273 (if applicable)) = P2271 (and P2273 (if applicable)) = P013F (and P014B (if	NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
		Description	Criteria	Value	Parameters	Conditions	Required	illum.
System	P013E	Description This DTC determines if the post catalyst O2 sensor has an initial delayed response to	Post O2 sensor cannot go below the threshold voltage. AND The Accumulated mass air flow monitored during the		No Active DTC's	Conditions TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013A, P013B, P013F, P2270 or P2271 10.0 volts < system voltage< 32.0 volts = Valid = Not Valid, See definition of Green Sensor Delay Criteria (B1S2) in Supporting Tables tab. = False = enabled = P2270 and P2272 (if		

SystemCodeO2 SensorP013F		Malfunction		•			MIL
	_ `			Parameters			illum.
Delayed Response Lean to Rich Bank 1 Sensor 2	the post catalyst O2 sensor has an initial delayed response to	Post O2 sensor cannot go above the threshold voltage. AND The Accumulated mass air flow monitored during the Delayed Response	Threshold Value 1) Post O2S signal < 350 mvolts AND 2) Accumulated air flow during lean to rich test > 380 grams.	Parameters No Active DTC's B1S2 Failed this key	Conditions TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013A, P013B, P013E, P2270 or P2271 10.0 volts < system voltage < 32.0 volts = Valid = Not Valid, See definition of Green Sensor Delay Criteria (B1S2) in Supporting Tables tab.	Required	MIL illum. 2 trips Type B

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
		·			DTC's Passed	= P013A (and P013C (if applicable)) = P2271 (and P2273 (if applicable))	·	
						onditions are met: n mode entered.		
O2S Circuit Insufficient Activity Bank 1	P0140	This DTC determines if the O2 sensor circuit is open.		410 mvolts < Oxygen Sensor signal < 490 mvolts	No Active DTC's	TPS_ThrottleAuthorityDefault ed	590 failures out of 740 samples.	2 trips Type B
Sensor 2					System Voltage	MAF_SensorFA EthanolCompositionSensor_F A 10.0 volts < system voltage < 32.0 volts	Minimum of 0 delta TPS changes required to report fail. Delta TPS is incremented when the TPS % change >= 0.0 %	
					Heater Warm-up delay Predicted Exhaust Temp	■	100msec loop Frequency: Once per trip for post	
						<= 87 % Ethanol	sensors	
O2S Heater Performance Bank 1 Sensor 2	P0141	This DTC determines if the O2 sensor heater is functioning properly by monitoring the	Measured Heater Current.	Measured Heater current < 0.3 amps -OR- Measured Heater	No Active DTC's System Voltage	ECT_Sensor_FA 10.0 volts < system voltage< 32.0 volts	8 failures out of 10 samples	2 trips Type B
		current through the heater circuit.		current > 2.9 amps	Heater Warm-up delay		Frequency: 1 tests per trip 5 seconds delay between tests and 1 second	
					B1S2 O2S Heater Duty Cycle	> zero	execution rate	

Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				All of the	above met for	1	
P014A	the post catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode	cannot go below the threshold voltage. AND The Accumulated mass air flow monitored during the	1) Post O2S signal > 450 mvolts AND 2) Accumulated air flow during stuck rich test > 50 grams.	B2S2 Failed this key cycle System Voltage Learned heater resistance ICAT MAT Burnoff delay Green O2S Condition	ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013C, P013D, P014B, P2272 or P2273 10.0 volts < system voltage< 32.0 volts = Valid = Not Valid, See definition of Green Sensor Delay Criteria (B2S2) in Supporting Tables tab.	Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR	2 trips Type B
	Code	P014A This DTC determines if the post catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required	P014A This DTC determines if the post catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. Post O2 sensor cannot go below the threshold voltage. AND The Accumulated mass air flow monitored during the Delayed Response Test is greater than	P014A This DTC determines if the post catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. Post O2 sensor cannot go below the threshold voltage. 450 mvolts AND AND AND 2) Accumulated air flow during stuck rich test > 50 grams. The Accumulated mass air flow monitored during the Delayed Response Test is greater than	Post O2 sensor has an initial delayed response to an AF change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. Post O2 sensor has an initial delayed response to an AF change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. Post O2 sensor cannot go below the threshold voltage. AND AND AND AND AND AND AND And cumulated mass air flow monitored during the Delayed Response Test is greater than the threshold. Post O2S signal > No Active DTC's AND AND AND AND AND AND And cumulated air flow during stuck rich test > 50 grams. Post O2S Failed this key ovice System Voltage Learned heater resistance ICAT MAT Burnoff delay Green O2S Condition	Corde Description Criteria Value Parameters Conditions	Code Description Criteria Value Parameters Conditions Required

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Post fuel cell DTC's Passed	= P2270 and P2272 (if		
					DFCO mo	onditions are met: ode is entered iated pedal input).		
O2 Sensor Delayed Response Lean to Rich Bank 2 Sensor 2	P014B	This DTC determines if the post catalyst O2 sensor has an initial delayed response to an A/F change from Lean to Rich. The diagnostic is an intrusive test which increases the delivered A/F ratio to achieve the required rich threshold.	cannot go above the threshold voltage. AND The Accumulated mass air flow monitored during the Delayed Response	1) Post O2S signal < 350 mvolts AND 2) Accumulated air flow during lean to rich test > 380 grams.	B2S2 Failed this key cycle System Voltage Learned heater resistance ICAT MAT Burnoff delay	ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013C, P013D, P014A, P2272 or P2273 10.0 volts < system voltage < 32.0 volts = Valid	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Low Fuel Condition Diag Post fuel cell DTC's Passed DTC's Passed DTC's Passed DTC's Passed	= enabled = P2270 (and P2272 (if applicable)) = P013E (and P014A (if applicable)) = P013A (and P013C (if applicable)) = P2271 (and P2273 (if		
						onditions are met: n mode entered.		
O2S Circuit Low Voltage Bank 2 Sensor 1	P0151	This DTC determines if the O2 sensor circuit is shorted to low.		Oxygen Sensor signal is < 50 mvolts	AIR intrusive test Fuel intrusive test Idle intrusive test EGR intrusive test	MAP_SensorFA AIR System FA Ethanol Composition Sensor FA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA = Not active = Not active = Not active = Not active 10.0 volts < system voltage< 32.0 volts = Not active = Not active = Not active = Not active	380 failures out of 475 samples Frequency: Continuous in 100 milli - second loop	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					AIR Device Control	= Not active		
					Low Fuel Condition Diag			
					Favirolanas Datia	0.9922 ≤ equiv. ratio ≤ 1.0137		
					Equivalence Ratio	3 % <= Throttle <= 70 %		
					Fuel Control State			
					Closed Loop Active			
					All Fuel Injectors for			
					active Cylinders			
						Ethanol <= 87%		
						DFCO not active		
					All of the	above met for		
					Time	> 2.0 seconds		
O2S Circuit High	P0152	This DTC determines if		Oxygen Sensor	No Active DTC's	TPS_ThrottleAuthorityDefault		
Voltage Bank 2		the O2 sensor circuit is	Sensor Signal.	signal is > 1050		ed	125 samples	Type E
Sensor 1		shorted to high.		mvolts		MAP_SensorFA		
						MAF_SensorFA	Frequency: Continuous in	
						EvapPurgeSolenoidCircuit_F	100 milli - second	
						A	loop	
						EvapFlowDuringNonPurge_F		
						A		
						EvapVentSolenoidCircuit_FA		
						EvapSmallLeak_FA		
						EvapEmissionSystem_FA		
						FuelTankPressureSnsrCkt_F		
						Α		
						FuelInjectorCircuit_FA		
					AIR intrusive test	= Not active		
					Fuel intrusive test			
					Idle intrusive test			
					EGR intrusive test			
					Cyatam Valtaga	10.0 volts < system voltage<		
					System Voltage EGR Device Control			
					Idle Device Control			
				1				
					Fuel Device Control	= Not active		

Component/	Fault		Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Closed Loop Active All Fuel Injectors for active Cylinders Fuel State	0.9922 ≤ equiv. ratio ≤ 1.0137 0.0 % <= Throttle <= 70.0 % = Closed Loop not = Power Enrichment = TRUE		
					All of the	above met for		
					Time	> 2 seconds		
O2S Slow Response Bank 2 Sensor 1	P0153	This DTC determines if the O2 sensor response time is degraded.	The average response time is caluclated over the test time, and compared to the threshold. Refer to "P0153 - O2S Slow Response Bank 2 Sensor 1" Pass/Fail Threshold table in the Supporting Tables tab.		Bank 2 Sensor 1 DTC's	ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA EthanolCompositionSensor_F A EngineMisfireDetected_FA	Sample time is 60 seconds Frequency: Once per trip	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary		Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						10.0 volts < system voltage<		
					System Voltage	32.0 volts		
					EGR Device Control	= Not active		
					Idle Device Control	= Not active		
					Fuel Device Control	= Not active		
					AIR Device Control			
					Low Fuel Condition Diag	= False		
						= Not Valid, See definition of		
						Green Sensor Delay Criteria		
						(B2S1) in Supporting Tables		
					Green O2S Condition			
					O2 Heater on for			
					Learned Htr resistance			
					Engine Coolant			
						> -40 °C		
					Engine Run Time			
					Time since any AFM			
						> 0.0 seconds		
					Time since Purge On to			
						> 0.0 seconds		
					Time since Purge Off to			
						> 0.0 seconds		
						>= 0 % duty cycle		
					l ange daily eyers	15 gps <= engine airflow <=		
					Engine airflow			
						1000 <= RPM <= 3000		
						< 87 % Ethanol		
						> 70 kpa		
					Throttle Position			
					1	3 /3		
					Low Fuel Condition Diag	= False		
					Fuel Control State			
					Closed Loop Active			
					LTM fuel cell			
					Transient Fuel Mass			
						= Not Defaulted		
						not = Power Enrichment		
						DFCO not active		
					Commanded Proportional			
						>= 0.0 %		
	1		1		Gain	>= U.U %		1

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
System	Code	Description	Criteria	value		above met for	Required	illulli.
						> 3.0 seconds		
					Time	3.0 seconds		
O2S Circuit Insufficient Activity Bank 2	P0154	This DTC determines if the O2 sensor circuit is open.		350 mvolts < Oxygen Sensor signal < 550 mvolts	No Active DTC's	TPS_ThrottleAuthorityDefault ed	400 failures out of 500 samples.	2 trips Type B
Sensor 1		Japan.				MAF_SensorFA		
							Minimum of 0 delta TPS	
						EthanolCompositionSensor_F	changes required to report fail.	
							Delta TPS is incremented when the TPS %	
					System Voltage	10.0 volts < system voltage < 32.0 volts = All Cylinders active	change >= 0.0 %	
					Heater Warm-up delay		Frequency: Continuous	
					Predicted Exhaust Temp	■		
					Engine Run Time	> 300 seconds <= 87 % Ethanol	100msec loop	
O2S Heater	P0155	This DTC determines if	Measured Heater	Measured Heater	No Active DTC's		8 failures out of	2 trips
Performance	1. 0.00	the O2 sensor heater	Current.	current < 0.3 amps	1107101110 2100	ECT_Sensor_FA	10 samples	Type B
Bank 2 Sensor 1		is functioning properly by monitoring the		-OR- Measured Heater	System Voltage	10.0 volts < system voltage< 32.0 volts		,,,,
		current through the heater circuit.		current > 3.1 amps	Heater Warm-up delay		Frequency: 1 tests per trip	
							5 seconds delay between tests and 1 second	
					B2S1 O2S Heater Duty		execution rate	
					O2S Heater device			
				= Not active				
						above met for		
					Time	> 120 seconds		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
O2S Circuit Low Voltage Bank 2 Sensor 2	P0157	This DTC determines if the O2 sensor circuit is shorted to low.		Oxygen Sensor signal is < 50 mvolts	AIR intrusive test Fuel intrusive test Idle intrusive test EGR intrusive test EGR Device Control Idle Device Control Fuel Device Control AIR Device Control AIR Device Control Cow Fuel Condition Diag Equivalence Ratio Throttle Position Fuel Control State Closed Loop Active All Fuel Injectors for active Cylinders Fuel Condition Fuel State All of the	ed MAP_SensorFA AIR System FA Ethanol Composition Sensor FA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA = Not active = Thotalite <= 70 % = Closed Loop = TRUE	430 failures out of 540 samples Frequency: Continuous in 100 milli - second loop	2 trips Type B

SystemCodeDescriptionCriteriaValueParametersConditionsRequiredillumO2S Circuit HighP0158This DTC determines if Measure OxygenOxygen SensorNo Active DTC'sTPS_ThrottleAuthorityDefault100 failures out of2 tri	Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
Voltage Bank 2 Sensor circuit is shorted to high. Sensor Signal. Signal is > 1050 mvolts MAP_SensorFA Frequency: Continuous in 100 mill - second loop EvapPourgeSolenoidCircuit_FA EvapPourgeSolenoidCi						-			illum.
All of the above met for Time > 2 seconds	Voltage Bank 2		the O2 sensor circuit is		signal is > 1050	AIR intrusive test Fuel intrusive test Idle intrusive test Idle intrusive test EGR intrusive test EGR Device Control Idle Device Control Fuel Device Control AIR Device Control AIR Device Control AIR Device Control AIR Device Control Low Fuel Condition Diag Equivalence Ratio Throttle Position Fuel Control State Fuel Control State Fuel Control State Closed Loop Active All Fuel Injectors for active Cylinders Fuel State Fuel Condition All of the	ed MAP_SensorFA MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA = Not active = Talse 0.9922 ≤ equiv. ratio ≤ 1.0137 3.0 % <= Throttle <= 70.0 % = Closed Loop not = Power Enrichment = TRUE Enabled (On) DFCO not active Ethanol <= 87%	125 samples Frequency: Continuous in 100 milli - second	2 trips Type B

O2 Sensor Delayed Response Rich to Lean Bank 1 Sensor 1 P015A This DTC determines if the pre catalyst O2 sensor nas an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. P015A This DTC determines if the pre catalyst O2 sensor normalized R2L time delay value > 0.40 EWMA (sec) No Active DTC's TPS_ThrottleAuthorityDefault ed Once per trip Note: if NaESPD_b_FastI nitResplsActive = TRUE for the given Fuel Bank OR NaESPD_b_Brapi dResponse Test (Gross failure). AND Pre O2 sensor > 550 mvolts	Component/	Fault	Monitor Strategy	Malfunction	Threshold		Enable	Time	MIL
Delayed Response Rich to Lean Bank 1 Sensor 1 the pre catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response. O2 sensor normalized R2L time delay value O3 sensor normalized R2L time delay value O4 SEWMA (sec) R2L time delay value O5 sensor normalized R2L time delay value O6 SEWMA (sec) R2L time delay value O7 sensor normalized R2L time delay value O7 sensor Note: if NaESPD_b_Fastl nitResplsActive = TRUE for the given Fuel Bank OR NaESPD_b_Rapi dResponselsActive = TRUE, NaESPD_b_Rapi dResponselsActive = TRUE, Mare Price of the given Fuel Bank OR NaESPD_b_Rapi dResponselsActive = TRUE, Mare Price of the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE, Mare Price of the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE, Mare Price of the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE, Mare Price of the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Rapi dResponselsActive = TRUE for the given Fuel Bank OR NaESPD_b Sample for the given Fuel Bank OR NaESPD_b Sample for the given Fuel Bank OR NaESPD_b Sample for the given Fuel Bank OR NaES				Criteria	Value		Conditions	Required	illum.
FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA FuelTrimSystemB1_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EthanolCompositionSensor_F A EngineMisfireDetected_FA P0131 P0132 P0134 System Voltage EGR Device Control Idle Device Control Idle Device Control AIR Device Control AIR Device Control AIR Device Control Fuel Device Control AIR Device Control For Not active Low Fuel Condition Diag Green O2S Condition Low Fuel Condition Diag Green Sensor Delay Criteria for the following locations: B1S1, B2S1 (if applicable) and B1S2 in Supporting	System O2 Sensor Delayed Response Rich to Lean Bank 1	Code	Description This DTC determines if the pre catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required	Criteria The EWMA of the Pre O2 sensor normalized R2L time delay value OR [The Accumulated time monitored during the R2L Delayed Response Test (Gross failure). AND	> 0.40 EWMA (sec) ≥ 4.00 Seconds > 550 mvolts	System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Diag Green O2S Condition	TPS_ThrottleAuthorityDefault ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_FA EvapFlowDuringNonPurge_F A EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelTrimSystemB1_FA FuelTrimSystemB2_FA EthanolCompositionSensor_F A EngineMisfireDetected_FA P0131 P0132 P0134 10.0 < Volts < 32.0 = Not active = Not active = Not active = Not active = False = Not Valid, See definition of Green Sensor Delay Criteria for the following locations: B1S1, B2S1 (if applicable)	Required Frequency: Once per trip Note: if NaESPD_b_FastI nitRespIsActive = TRUE for the given Fuel Bank OR NaESPD_b_Rapi dResponseIsActi ve = TRUE, multiple tests per	
O2 Heater (pre sensor)	¶ ,					O2 Heater (pre sensor)			

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Learned Htr resistance	= Valid		
					Engine Coolant	t > 55 °C		
						> -40 °C		
					Engine run Accum	> 120 seconds		
					Engine Speed to initially			
						t 1050 ≤ RPM ≤ 2600		
					Engine Speed range to			
					keep test enabled (after			
					initially enabled)			
					, i	1000 ≤ RPM ≤ 2750		
					Engine Airflow			
					Vehicle Speed to initially			
						t 42.3 ≤ MPH ≤ 80.8		
					Vehicle Speed range to			
					keep test enabled (after			
					initially enabled)			
					initially chasica,	37.3 ≤ MPH ≤ 83.9 mph		
					Closed loop integral	0.74 ≤ C/L Int ≤ 1.08		
					Closed Loop Active			
						not in control of purge		
						I not in estimate mode		
					Post fuel cell			
					Fost idei celi	- enabled		
					CCD Intrucive diagnostic	- not cativo		
					EGR Intrusive diagnostic			
					All post sensor heater	= not active		
					delays	- Hot active		
					026 Haatar (naat aanaar)			
					O2S Heater (post sensor)	00.0000		
						e ≥ 80.0 sec		
					Predicted Catalyst temp	0 600 ≤ °C ≤ 900		
					Fuel State	e = DFCO possible		
					Fuel State	e = DFCO possible		
						l	┪	
						at least 0.5 seconds, and then		
					the Force Cat Rich in	trusive stage is requested.	4	
					Pre O2S voltage B1S1 at			
					end of Cat Rich stage			
					Fuel State	= DFCO active	1	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Number of fueled			
					cylinders	≤ 7 cylinders		
					After above condition	ns are met: DFCO Mode	1	
						r initiated pedal input).		
							1	
O2 Sensor	P015B	This DTC determines if	The FWMA of the Pre		No Active DTC's	TPS_ThrottleAuthorityDefault	Frequency:	1 trips
Delayed	1 0 100	the pre catalyst O2	O2 sensor normalized		NO ACTIVE DIGG	led	Once per trip	Type A
Response Lean		sensor has an initial	L2R time delay value			MAP_SensorFA	Note: if	EWMA
to Rich Bank 1		delayed response to	LZIV time delay value	0.40 EVVIVI/ ((300)		IAT SensorFA	NaESPD_b_FastI	
Sensor 1		an A/F change from	OR			ECT_Sensor_FA	nitRespIsActive =	
0011301 1		Lean to Rich. The	Oit			AmbientAirDefault	TRUE for the	
		diagnostic is an	[The Accumulated				given Fuel Bank	
		intrusive test which	time monitored during			MAF_SensorFA	OR	
		runs in an enriched	the L2R Delayed			EvapPurgeSolenoidCircuit_F	NaESPD b Rapi	
		fuel mode to achieve		≥ 4.00 Seconds		A	dResponselsActi	
		the required response.	(Gross failure).	- 1.00 00001100		EvapFlowDuringNonPurge_F	ve = TRUE,	
		The required reopenies.	(Grood randro).			A	multiple tests per	
			AND				trip are allowed	
			71142			EvapVentSolenoidCircuit_FA	inp are anowed	
			Pre O2 sensor	< 350 myolts		EvapSmallLeak_FA		
			voltage is below]	- coo mivono		EvapEmissionSystem_FA		
			voltage to below]			FuelTankPressureSnsrCkt_F		
			OR			Α		
			011			FuelInjectorCircuit_FA		
			At end of Cat Rich			AIR System FA		
			stage the Pre O2	< 700 myolts		FuelTrimSystemB1 FA		î
			sensor output is			FuelTrimSystemB2_FA		
						EthanolCompositionSensor F		
						Α		
						EngineMisfireDetected FA		
						P0131		
						P0132		
						P0134		
					System Voltage	10.0 < Volts < 32.0		
					EGR Device Control			
					Idle Device Control			
					Fuel Device Control			
					AIR Device Control	- Not active		
					Low Fuel Condition Diag	= False		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					O2 Heater (pre sensor) on for Learned Htr resistance Engine Coolant IAT Fuel State Number of fueled cylinders	= Not Valid, See definition of Green Sensor Delay Criteria for the following locations: B1S1, B2S1 (if applicable) and B1S2 in Supporting Tables tab. ≥ 40 seconds = Valid > 55 °C > -40 °C = DFCO inhibit		
1					During test: Engine			
					Airflow must stay			
					between:	0 ≤ gps ≤ 15	ļ	
O2 Sensor Delayed Response Rich to Lean Bank 2 Sensor 1	P015C	This DTC determines if the pre catalyst O2 sensor has an initial delayed response to an A/F change from Rich to Lean. The diagnostic is an intrusive test which runs in a DFCO mode to achieve the required response.	The EWMA of the Pre O2 sensor normalized R2L time delay value OR [The Accumulated time monitored during the R2L Delayed Response Test (Gross failure). AND	> 0.40 EWMA (sec)	No Active DTC's	TPS_ThrottleAuthorityDefault ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapVentSolenoidCircuit_FA	Frequency: Once per trip Note: if NaESPD_b_FastI nitRespIsActive = TRUE for the given Fuel Bank OR NaESPD_b_Rapi dResponseIsActi ve = TRUE, multiple tests per trip are allowed	1 trips Type A EWMA
			Pre O2 sensor voltage is above]			EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA FuelTrimSystemB1_FA		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						FuelTrimSystemB2_FA		
						EthanolCompositionSensor_F		
						Α		
						EngineMisfireDetected_FA		
						P0131		
						P0132		
						P0134		
					System Voltage	e 10.0 < Volts < 32.0		
					EGR Device Contro			
					Idle Device Contro			
					Fuel Device Contro			
					AIR Device Contro			
					7 \ 201130 3011110			
					Low Fuel Condition Diag	= False		
						n = Not Valid, See definition of		
						Green Sensor Delay Criteria		
						for the following locations:		
						B1S1, B2S1 (if applicable)		
						and B1S2 in Supporting		
						Tables tab.		
					O2 Heater (pre sensor			
						r ≥ 40 seconds		
					Learned Htr resistance			
					Engine Coolan			
						T > -40 °C		
					Engine run Accun			
					Engine Speed to initially			
						y st 1050 ≤ RPM ≤ 2600		
					Engine Speed range to			
					keep test enabled (afte			
					initially enabled			
					E Airg.	1000 ≤ RPM ≤ 2750		
						y 3 ≤ gps ≤ 20		
					Vehicle Speed to initially			
						t 42.3 ≤ MPH ≤ 80.8		
					Vehicle Speed range to			
					keep test enabled (afte			
					initially enabled			
						$37.3 \le MPH \le 83.9 \text{ mph}$		
						0.74 ≤ C/L Int ≤ 1.08		
					Closed Loop Active			
					Eva	not in control of purge		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Ethanol Post fuel cell	not in estimate mode = enabled		
					EGR Intrusive diagnostic			
					O2S Heater (post sensor) on Time Predicted Catalyst temp	: ≥ 80.0 sec		
					All of the above met for a	at least 0.5 seconds, and then trusive stage is requested.		
					Number of fueled	≥ 700 mvolts = DFCO active		
						ns are met: DFCO Mode er initiated pedal input).		
O2 Sensor Delayed Response Lean to Rich Bank 2 Sensor 1		This DTC determines if the pre catalyst O2 sensor has an initial delayed response to an A/F change from Lean to Rich. The diagnostic is an intrusive test which runs in an enriched fuel mode to achieve the required response.	O2 sensor normalized L2R time delay value OR [The Accumulated time monitored during the L2R Delayed	> 0.40 EWMA (sec)	No Active DTC's	TPS_ThrottleAuthorityDefault ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F	Frequency: Once per trip Note: if NaESPD_b_FastI nitRespIsActive = TRUE for the given Fuel Bank OR NaESPD_b_Rapi dResponseIsActi ve = TRUE,	1 trips Type A EWMA
			AND Pre O2 sensor			EvapVentSolenoidCircuit_FA EvapSmallLeak_FA EvapEmissionSystem_FA	multiple tests per trip are allowed	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
System		Безсприон	OR At end of Cat Rich stage the Pre O2 sensor output is		System Voltage EGR Device Control Idle Device Control Fuel Device Control AIR Device Control Low Fuel Condition Diag Green O2S Condition O2 Heater (pre sensor) on for Learned Htr resistance Engine Coolant IAT Fuel State Number of fueled cylinders When above of Fuel Enrich mode During test: Engine Airflow must stay	FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EthanolCompositionSensor_F A EngineMisfireDetected_FA P0131 P0132 P0134 10.0 < Volts < 32.0 = Not active = Not Valid, See definition of Green Sensor Delay Criteria for the following locations: B1S1, B2S1 (if applicable) and B1S2 in Supporting Tables tab. ≥ 40 seconds = Valid > 55 °C > -40 °C = DFCO inhibit ≥ 2 cylinders conditions are met: entered (Test begins)	required	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System			Criteria	Value	Parameters	Conditions	Required	illum.
O2S Circuit Insufficient Activity Bank 2 Sensor 2		This DTC determines if the O2 sensor circuit is open.		410 mvolts < Oxygen Sensor signal < 490 mvolts	No Active DTC's	TPS_ThrottleAuthorityDefault ed MAF_SensorFA	590 failures out of 740 samples. Minimum of 0	2 trips Type B
						EthanolCompositionSensor_F A	delta TPS changes required to report fail. Delta TPS is	
					System Voltage AFM Status	10.0 volts < system voltage< 32.0 volts = All Cylinders active	incremented when the TPS % change >= 0.0 %	
					Heater Warm-up delay Predicted Exhaust Temp	= Complete	100msec loop	
					Engine Run Time Fuel	> 300 seconds <= 87 % Ethanol	Frequency: Once per trip for post sensors	
O2S Heater Performance Bank 2 Sensor 2		is functioning properly	Measured Heater Current.	Measured Heater current < 0.3 amps -OR-	No Active DTC's	10.0 volts < system voltage<	8 failures out of 10 samples	2 trips Type B
		by monitoring the current through the heater circuit.		Measured Heater current > 2.9 amps	System Voltage Heater Warm-up delay	32.0 volts = Complete	Frequency: 1 tests per trip 5 seconds delay	
					O2S Heater device	> zero	between tests and 1 second execution rate	
						above met for > 120 seconds		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
	Code		Criteria		Engine speed BARO Coolant Temp MAP Inlet Air Temp MAF Fuel Level Long Term Fuel Trim data accumulation:	Conditions 375 <rpm< 7000=""> 70 kPa -40 <°C< 150 10 <kpa< 255<="" td=""><td>Frequired Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97% % of the H2778EPAIII drive cycle. This</td><td></td></kpa<></rpm<>	Frequired Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97% % of the H2778EPAIII drive cycle. This	
					Long-Term Fu Sometimes, certai Cells are not u diagnosis. Plea: Tables" Tab for for d	real-world drivi however value will vary (high or lower) base a list of cells utilized agnosis. Is also typical real-world drivi however value will vary (high or lower) base on the actua conditions present durin		
					Closed Loop Long Term FT	ntrol Status Enabled Enabled Please see "Closed Loop Enable Criteria" and "Long Term FT Enable Criteria" in Supporting Tables.		
					Catalyst Monitor Ir Post O2 Diag. Int Device Co	> 0.3 liters of fuel consumed after a fuel fill event ("Virtual Flex Fuel Sensor applications only) trusive Test Not Active trusive Test Not Active rusive Test Not Active ntrol Not Active pull down" Not Active		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters		Required	illum.
System System	Code	Description	Criteria	Value	Parameters IA N EvapP EvapF EvapN E Eval FuelTank Ethanol Fu Engi EGR EMAP An	Conditions No active DTCs: C_SystemRPM_FA MAP_SensorFA MAF_SensorFA IAF_SensorTFTKO AIR System FA urgeSolenoidCircuit_FA lowDuringNonPurge_FA /entSolenoidCircuit_FA exapSmallLeak_FA DEmissionSystem_FA PressureSensorCircuit_FA I Composition Sensor FA ellnjectorCircuit_FA neMisfireDetected_FA ValvePerformance_FA GRValveCircuit_FA _EngineVacuumStatus nbientAirDefault_NA	Required	MIL illum.
Fuel System Too Rich Bank 1	P0172	Determines if the fuel control system is in a rich condition, based on the filtered long-term fuel trim metric. There are two methods to determine a Rich fault. They are Passive and Intrusive. The Intrusive test is described below:	The filtered Non- Purge Long Term Fuel Trim metric (a Passive Test decision cannot be made when Purge is enabled)	e Test: <= Non Purge Rich Limit Table ve Test: <= Purge Rich Limit Table ND	O2S_	Secondary Parameters and Enable Conditions are identical to those for P0171, with the exception that fuel level is not considered.	Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97 % of the EPAIII drive cycle. This is also typical of real- world driving, however values will vary (higher or lower) based	2 Trip(s) Type B

Component/	Fault		Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
							conditions	
		Intrusive Test:	Segment Def'n:				present during	
		When the filtered	Segments can last up				the drive cycle.	
			to 30 seconds and					
		trim metric is <= Purge	are separated by the					
		Rich Limit Table,	lesser of 20 seconds					
			of purge-on time or					
		determine if excess	enough time to purge					
		purge vapor is the	16 grams of vapor.					
		cause of the rich						
			A maximum of 5					
		If the filtered Purge-on	completed segments					
		Long Term fuel trim >	or 20 attempts are					
		Purge Rich Limit	allowed for each					
		Table the test passes	intrusive test.					
		without checking the						
		filtered Non-Purge	After an intrusive test					
		Long Term fuel trim	report is completed,					
		metric.	another intrusive test					
			cannot occur for 300					
		Performing intrusive	seconds to allow					
		tests too frequently	sufficient time to					
		may also affect EVAP	purge excess vapors					
		and EPAIII emissions,	from the canister.					
		and the execution	During this period,					
		frequency of other	fuel trim will pass if					
		diagnostics.	the filtered Purge-on					
			Long Term fuel trim >					
			Purge Rich Limit					
			Table for at least 200					
			seconds, indicating					
			that the canister has					
			been purged.					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
-	Code		Criteria		Engine speed BARO Coolant Temp MAP Inlet Air Temp MAF Fuel Level Long Term Fuel Trim data accumulation: fuel trim diagnos Long-Term Fu Sometimes, certain Cells are not u diagnosis. Pleas Tables" Tab for	Conditions 375 <rpm< 7000=""> 70 kPa -40 <°C< 150 10 <kpa< 255<="" td=""><td>Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97 % of the EPAIII drive cycle. This is also typical of real- world driving, however values will vary (higher or lower) based on the actual conditions</td><td></td></kpa<></rpm<>	Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97 % of the EPAIII drive cycle. This is also typical of real- world driving, however values will vary (higher or lower) based on the actual conditions	
					Long-Term Fu Sometimes, certain Cells are not u diagnosis. Pleas Tables" Tab for d	el Trim Cell Usage n Long-Term Fuel Trim tilized for control or se see "Supporting a list of cells utilized	world driving, however values will vary (higher or lower) based on the actual	
				Catalyst Monitor Ir Post O2 Diag. Int Device Co	Intrusive Test Not Active strusive Test Not Active rusive Test Not Active strol Not Active strol Not Active strol down" Not Active			

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					IAC_Sy MAF MAF MAF_S AIR EvapPurgeS EvapFlowDo EvapVentS EvapEmis FuelTankPress Ethanol Com FuelInje EngineMis EGRValve EGRVal MAP_Engi Ambien	retive DTCs: restemRPM_FA P_SensorFA P_SensorFA P_SensorFA P_SensorFTFTKO P_System FA P_SolenoidCircuit_FA P_Sole		
Fuel System Too Rich Bank 2	P0175	Determines if the fuel control system is in a rich condition, based on the filtered long-term fuel trim metric. There are two methods to determine a Rich fault. They are Passive and Intrusive. The Intrusive test is described below:	Passive The filtered Non- Purge Long Term Fuel Trim metric (a Passive Test decision cannot be made when Purge is enabled) Intrusiv The filtered Purge Long Term Fuel Trim metric AN The filtered Non- Purge Long Term Fuel Trim metric	<= Non Purge Rich Limit Table /e Test: <= Purge Rich Limit Table		Secondary Parameters and Enable Conditions are identical to those for P0174, with the exception that fuel level is not considered.	Frequency: 100 ms Continuous Loop Development data indicates that the Fuel Adjustment System Diagnostic (FASD) is typically enabled during 97 % of the EPAIII drive cycle. This is also typical of real- world driving, however values will vary (higher or lower) based on the actual	2 Trip(s) Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
							conditions	
		Intrusive Test:	Segment Def'n:		1		present during	
		When the filtered	Segments can last up				the drive cycle.	
		Purge Long Term fuel	to 30 seconds and				ĺ	
		trim metric is <= Purge	are separated by the					
		Rich Limit Table,	lesser of 20 seconds					
		purge is ramped off to	of purge-on time or					
		determine if excess	enough time to purge					
		purge vapor is the	16 grams of vapor.					
		cause of the rich						
		condition.	A maximum of 5					
		If the filtered Purge-on	completed segments					
		Long Term fuel trim >	or 20 attempts are					
		Purge Rich Limit	allowed for each					
		Table the test passes	intrusive test.					
		without checking the						
		filtered Non-Purge	After an intrusive test					
		Long Term fuel trim	report is completed,					
		metric.	another intrusive test					
			cannot occur for 300					
		Performing intrusive	seconds to allow sufficient time to					
		tests too frequently	purge excess vapors					
		may also affect EVAP	from the canister.					
		and EPAIII emissions,	During this period,					
		and the execution	fuel trim will pass if					
		frequency of other	the filtered Purge-on					
		diagnostics.	Long Term fuel trim >					
			Purge Rich Limit					
			Table for at least 200					
			seconds, indicating					
			that the canister has					
			been purged.					
			Joon pargoan					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Fuel Composition Sensor Circuit Low	P0178	Detects Out of Range Low Frequency Signal	Flex Fuel Sensor Output Frequency	< 45 Hertz	Powertrain Relay	> 11.0 Volts < 32.0 Volts	50 failures out of 63 samples 100 ms loop Continuous	2 trip(s) Type B
Fuel Composition Sensor Circuit High	P0179	Detects Out of Range High Frequency Signal	Flex Fuel Sensor Output Frequency	> 155 Hertz <= 185 Hertz	Powertrain Relay	> 11.0 Volts < 32.0 Volts	50 failures out of 63 samples 100 ms loop Continuous	2 trip(s) Type B
Injector 1	P0201	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 2	P0202	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 3	P0203	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match			11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 4	P0204	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match			11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds		2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Injector 5	P0205	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 6	P0206	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 7	P0207	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
Injector 8	P0208	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control ciruit do not match		Powertrain Relay Voltage within range and stable according to Enable Conditions Engine Running	11 volts ≤ Voltage ≤ 32 volts greater than 5 seconds	20 failures out of 25 samples 250 ms /sample Continuous	2 trips Type B
TPS2 Circuit	P0220	Detects a continuous or intermittent short or open in TPS2 circuit on the secondary processor but sensor is in range on the primary processor	Secondary TPS2 Voltage < or Secondary TPS2 Voltage >	0.25		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	Trips: 1 Type: A MIL: YES

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
TPS2 Circuit Low	P0222	Detects a continuous or intermittent short or open in TPS2 circuit on both processors or just the primary processor		0.25		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the primary processor	Trips: 1 Type: A MIL: YES
			Secondary TPS2 Voltage <			No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
TPS2 Circuit High	P0223	Detects a continuous or intermittent short in TPS1 circuit on both processors or just the primary processor	Primary TPS2 Voltage >	4.59		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	79 / 159 counts; 57 counts continuous; 3.125 ms /count in the primary processor	Trips: 1 Type: A MIL: YES
			Secondary TPS2 Voltage >	4.59		No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
Fuel Pump Primary Circuit (ODM)	P0230	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Engine Speed	11 volts ≤ Voltage ≤ 32 volts ≥ 0 RPM	8 failures out of 10 samples 250 ms /sample	2 trips Type B

		Monitor Strategy	Malfunction	Threshold	,	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
							Continuous	
Supercharger Intercooler Coolant Pump Control Circuit	P023A	Electrical Integrity of Supercharger Intercooler Coolant Pump Control Circuitry	ECM detects that commanded and actual states of output driver do not match		Ignition Voltage Ignition Voltage Engine Speed	>= 11.00 Volts <= 32.00 Volts > 0		Type B 2 trips
Random Misfire	P0300	These DTC's will	Deceleration index vs.	(>Idle SCD AND	Engine Run Time	> 2 crankshaft revolutions	Emission	2 Trips
Detected Cylinder 1 Misfire Detected		determine if a random or a cylinder specific misfire is occurring by monitoring crankshaft velocity	Engine Speed Vs Engine load	> Idle SCD ddt Tables) OR (>SCD Delta AND > SCD Delta ddt	ECT If ECT at startup	-7 °C < ECT < 125 °C < -7 °C	Exceedence = any (5) failed 200 rev blocks out of (16) 200 rev block tests	Type B
Cylinder 2 Misfire Detected	P0302		to specific veh.	Tables) OR (>Idle Cyl Mode AND			Failure reported for (1)	Catalyst Damagin g Misfire)
Cylinder 3 Misfire Detected	P0303		that are not max of range. Undetectable region at a given	> Idle Cyl Mode ddt Tables) OR	ECT	21 °C < ECT < 125 °C	Exceedence in 1st (16) 200 rev block tests, or (4)	,
Cylinder 4 Misfire Detected	P0304		speed/load point is where all tables are max of range point.	(>Cyl Mode AND > Cyl Mode ddt Tables)	System Voltage + Throttle delta	9.00 <volts< 32.00<br="">< 40.00 % per 25 ms</volts<>	Exceedences thereafter.	
Cylinder 5 Misfire Detected	P0305		see Algorithm Description Document	OR (>Rev Mode Table) OR	- Throttle delta	< 40.00 % per 25 ms		
Cylinder 6 Misfire Detected	P0306			(> AFM Table in Cyl Deact mode)			any Catalyst Exceedence = (1) 200 rev block as	
Cylinder 7 Misfire Detected	P0307						data supports for catalyst damage.	
Cylinder 8 Misfire Detected	P0308			≥ 1.05 % P0300 ≥ 1.05 % emission			Failure reported with (1 or 3) Exceedences in FTP, or (1)	
			Threshold				Exceedence outside FTP.	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Misfire Percent Catalyst Damage	>"Catalyst Damaging Misfire Percentage" Table whenever	Engine Speed Engine Load Misfire counts	> 800 rpm AND > 25 % load AND < 180 counts on one cylinder		
				secondary conditions are met.	(at low speed/loads, one cylinder may not cause cat damage)			
			When engine speed and load are less than the FTP cals (3) catalyst damage exceedences are allowed.	≤ 0 FTP rpm AND ≤ 0 FTP % load				
					Engine Speed	500 < rpm < (Engine Speed Limit) - 400	Continuous 4 cycle delay	
						Engine speed limit is a function of inputs like Gear and temperature		
						typical Engine Speed Limit = xxxx rpm		
				disable conditions:	No active DTCs:	TPS_FA EnginePowerLimited MAF_SensorTFTKO MAP_SensorTFTKO IAT_SensorTFTKO ECT_Sensor_Ckt_TFTKO 5VoltReferenceB_FA CrankSensorTestFailedTKO CrankSensorFaultActive CrankIntakeCamCorrelationFA CrankExhaustCamCorrelationICrankCamCorrelationTFTKO	FA	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						AnyCamPhaser FA		
						AnyCamPhaser_TFTKO		
						_		
						If Monitor Rough Road=1		
						and		
						RoughRoadSource="TOSS"		
						Trans_Gear_Defaulted(TCM)		
						(Auto Trans only)		
						Clutch Sensor FA (Manual		
						Trans only)		
						Trans_Gear_Defaulted(TCM)		
						(Auto Trans only)		
						<u>'</u>		
					P0315 & engine speed	> 1000 rpm		
					Fuel Level Low	LowFuelConditionDiagnostic	500 cycle delay	
					Cam and Crank Sensors	in sync with each other	4 cycle delay	
						, , , , , , , , , , , , , , , , , , , ,		
					Misfire requests TCC	Not honored because	4 cycle delay	
					unlock	Transmission in hot mode		
					Fuel System Status	≠ Fuel Cut	4 cycle delay	
					Active Fuel Management	Transition in progress	7 cycle delay	
					Undetectable engine	invalid speed load range in	4 cycle delay	
					speed and engine load	decel index tables		
					region			
					Abusive Engine Over	> 7600 rpm	1250 cycle delay	
					Speed		' '	
					Below zero torque	<" Zero torque engine load" in	4 cycle delay	
					(except CARB approved	Supporting Tables tab		
					3000 rpm to redline			
					triangle.)			
					Below zero torque:		4 cycle delay	
					TPS (area)	≤ 0 %		
					Veh Speed	> 30 mph		
					EGR Intrusive test	Active	0 cycle delay	
					Manual Trans	Clutch shift	4 cycle delay	
					Throttle Position	> 95.00 %	0 cycle delay	
					AND Automatic			
		1	1		transmission shift			1

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Driveline Ring Filter active After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early. Filter Driveline ring: Stop filter early:	7 engine cycles after misfire 3 Engine cycles after misfire		
					Abnormal engine speed oscillations: (Rough road etc) Off Idle, number of consecutive decelerating cylinders after accelerating;: (Number of decels can vary with misfire detection equation) TPS Engine Speed Veh Speed			
					SCD Cyl Mode Rev Mode	> 3 % > 1000 rpm > 3 mph = 4 consecutive cyls = 4 consecutive cyls = 4 consecutive cyls		
					Rough Road Section: Monitor Rough Road RoughRoadSource	1 (1=Yes) FromABS		

Component/		Monitor Strategy		Threshold	Secondary	Enable		MIL
System		Description	Criteria	Value	Parameters	Conditions	Required	illum.
					IF Rough Road is			
					monitored, then ONE of			
					the following Rough Road			
					Sources will be used:			
					Rough Road Source =			
					"TOSS"			
					Rough Road			
					Rough Road	detected		
						detected		
					Rough Road Source =			
					"WheelSpeedInECM"			
					VVIIcolopecumicolvi			
					ABS/TCS system			
					RoughRoad			
						active		
					VSES			
						detected		
						active		
						active		
					Rough Road Source =			
					"FromABS"			
					ABS/TCS system			
					RoughRoad	active		
					1/050			
					VSES	detected		
						active		
						active		
Outside of	D0045	Manitantanusiid	0	> 4.0040	ODD Manufactures		0.50	A Tains
Crankshaft Position System	P0315	Monitor for valid crankshaft error	Sum of Compensation factors	≥ 4.0040 OR ≤ 3.9960	OBD Manufacturer Enable Counter	0	0.50 seconds	1 Trips
Variation Not		compensation factors	Iaciois	U088.6 ≤ AU	Lilable Coullel		Frequency	Type A
Learned		oomponsation lactors					Frequency Continuous	
							100 msec	
							100 111000	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Knock Sensor (KS) Module Performance E38 & E67 controllers	P0324	This diagnostic will detect a failed internal ECM component associated with knock control	Any Cylinder's Avg Gain Signal or All Cylinder's Raw Signals	> 4.50 Volts ≤ 0.20 Volts	Engine Speed Cylinder Air Mass No Active DTC's Engine Speed	> 50 milligrams KS_Ckt_Perf_B1B2_FA ≥ 400 RPM	·	Type: B MIL: YES Trips: 2
Knock Sensor	P0325	This diagnostic checks		. 401/18	Cylinder Air Mass Diagnostic Enabled	> 50 milligrams	50 Failures out of	Туре: В
(KS) Circuit Bank 1 E38 & E67 controllers		for an open in the knock sensor circuit	Gated Low Pass Filter Voltage	> 4.0 Volts or < 1.24 Volts	(1 = Enabled) Engine Speed ECT Enginer Run Time	= 1 ≥ 400 RPM ≥ -40 deg. C ≥ 2 seconds	63 Samples	MIL: YES Trips: 2
Knock Sensor (KS) Circuit Bank	P0325	This diagnostic checks for an open in the	Gated FFT Output	< OpenCircuit Thresh	Power Take Off Diagnostic Enabled (1 = Enabled)		50 Failures out of 63 Samples	Type: B MIL:
1 E37 controllers		knock sensor circuit		See Supporting Tables for OpenCircuit Thresh	Engine Speed ECT Engine Run Time No Active DTC's	≥ 1800 RPM ≥ -40 deg. C ≥ 1 seconds KS_Ckt_Perf_B1B2_FA	·	YES Trips: 2
Knock Sensor (KS) Performance Bank 1		This diagnostic checks for an overactive knock sensor caused by excessive knock or		> (FastRtdMax + 4.0) degrees spark See Supporting	Power Take-Off Diagnostic Enabled (1 = Enabled) Knock Detection Enabled	= 1	·	Type: B MIL: YES Trips: 2
E38 & E67 controllers		noisy engine components		Tables for FastRtdMax	Triock Detection Enabled	Knock Detection Enabled is calculated by multiplying the	100 msec rate	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
oystem	Ode	Description	Onteria	Value	Engine Speed MAP Power Take Off	following three factors: FastAttackRate FastAttackCoolGain FastAttackBaroGain (see Supporting Tables) ≥ 400 RPM ≥ 10 kPa = Not Active	required	
Knock Sensor (KS) Performance Bank 1 E37 controllers	P0326	This diagnostic checks for an overactive knock sensor caused by excessive knock or noisy engine components		> (FastRtdMax + 5.0 degrees spark See Supporting Tables for FastRtdMax	Diagnostic Enabled (1 = Enabled) Knock Detection Enabled Engine Speed MAP No Active DTC's Power Take-Off	= 1 Nock Detection Enabled is calculated by multiplying the following three factors: FastAttackRate FastAttackCoolGain FastAttackBaroGain (see Supporting Tables) ≥ 400 RPM ≥ 10 kPa GetTPSR_ThrotAuth Default = Not Active	50 Failures out of 63 Samples 100 msec rate	Type: B MIL: YES Trips: 2
Knock Sensor (KS) Circuit Low Bank 1 E38 & E67 controllers	P0327	This diagnostic checks for an out of range low knock sensor signal	Sensor Input Signal Line or Sensor Return Signal Line	> 2.86 Volts < 1.48 Volts	ECT Engine Run Time Valid Oil Temp Required? (1= Yes, 0 = No) If Yes: Engine Oil Temp	≥ -40 deg. C ≥ 2 seconds = 0 < 256 deg. C	50 Failures out of 63 Samples 100 msec rate	Type: B MIL: YES Trips: 2

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					and ValidOilTemp Model	EngOilModeledTemp Valid		
					or No OilTemp Sensor DTC's	EngOilTempSensor CircuitFA		
					If No: No Eng Oil Temp enable criteria			
Knock Sensor (KS) Circuit Low Bank 1	P0327	This diagnostic checks for an out of range low knock sensor signal	Sensor Input Signal Line	< ShortLow ThreshSig (Volts)	ECT Enginer Run Time	≥ -40 deg. C ≥ 1 seconds	50 Failures out of 63 Samples	Type: B MIL: YES Trips: 2
E37 controllers			Sensor Return Signal Line	< ShortLow ThreshRet (Volts)	Valid Oil Temp Required? (1= Yes, 0 = No)	= 1	100 msec rate	
				See Supporting Tables for ShortLow ThreshSig	If Yes: Engine Oil Temp	< 150 deg. C		
				and ShortLow ThreshRet	and ValidOilTemp Model or	EngOilModeledTemp Valid		
					No OilTempSensor DTC's	EngOilTempSensorCircuitFA		
					<u>If No:</u> No Eng Oil Temp enable criteria			
Knock Sensor (KS) Circuit High	P0328	This diagnostic checks for an out of range	Line	< 2.02 Volts	ECT Enginer Run Time	≥ -40 deg. C ≥ 2 seconds	50 Failures out of 63 Samples	Type: B MIL:
Bank 1 E38 & E67 controllers		high knock sensor signal	or Sensor Return Signal Line	> 3.76 Volts	Valid Oil Temp Required? (1= Yes, 0 = No)	= 0	100 msec rate	YES Trips: 2

Component/		Monitor Strategy		Threshold	-	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					If Yes: Engine Oil Temp and ValidOilTemp Model or No OilTempSensor DTC's	< 256 deg. C EngOilModeledTemp Valid EngOilTempSensor CircuitFA		
					If No: No Eng Oil Temp enable criteria			
Knock Sensor	P0328	This diagnostic checks	Sensor Input Signal	> ShortHi	ECT	≥ -40 deg. C	50 Failures out of	Type: B
(KS) Circuit High Bank 1		for an out of range high knock sensor signal		ThreshSig (Volts)			63 Samples	MIL: YES Trips: 2
E37 controllers			or				100 msec rate	
			Sensor Return Signal Line	> ShortHi ThreshRet (Volts)	Valid Oil Temp Required? (1= Yes, 0 = No)	= 1		
				See Supporting Tables for ShortHi ThreshSig and ShortHi ThreshRet	If Yes: Engine Oil Temp and ValidOilTemp Model or No OilTempSensor DTC's	< 150 deg. C EngOilModeledTemp Valid EngOilTempSensorCircuitFA		
					<u>If No:</u> No Eng Oil Temp enable criteria			

		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Knock Sensor (KS) Circuit Bank 2 E38 & E67 controllers	P0330	This diagnostic checks for an open in the knock sensor circuit	Gated Low Pass Filter Voltage	> 4.0 Volts or < 1.24 Volts	Diagnostic Enabled (1 = Enabled) Engine Speed ECT Enginer Run Time Power Take Off	= 1 ≥ 400 RPM ≥ -40 deg. C ≥ 2 seconds = Not Active	63 Samples	Type: B MIL: YES Trips: 2
Knock Sensor (KS) Circuit Bank 2 E37 controllers		This diagnostic checks for an open in the knock sensor circuit		< OpenCircuit Thresh See Supporting Tables for OpenCircuit Thresh	ECT Engine Run Time	= 1 ≥ 1800 RPM ≥ -40 deg. C ≥ 1 seconds KS_Ckt_Perf_B1B2_FA = Not Active		Type: B MIL: YES Trips: 2
Knock Sensor (KS) Circuit Low Bank 2 E38 & E67 controllers		This diagnostic checks for an out of range low knock sensor signal	Sensor Input Signal Line or Sensor Return Signal Line	> 2.86 Volts < 1.48 Volts	Enginer Run Time Valid Oil Temp Required? (1= Yes, 0 = No) If Yes: Engine Oil Temp and ValidOilTemp Model or No OilTempSensor DTC's	< 256 deg. C EngOilModeledTemp Valid		Type: B MIL: YES Trips: 2

•			Malfunction	Threshold	Secondary	Enable		MIL
System		Description	Criteria	Value	Parameters	Conditions		illum.
Knock Sensor (KS) Circuit Low Bank 2 E37 controllers	P0332	This diagnostic checks for an out of range low knock sensor signal	Sensor Input Signal Line or	< ShortLow ThreshSig (Volts)	ECT Engine Run Time	≥ -40 deg. C ≥ 1 seconds		Type: B MIL: YES Trips: 2
			Sensor Return Signal Line	< ShortLow ThreshRet (Volts)	Valid Oil Temp Required? (1= Yes, 0 = No)	= 1		
				See Supporting Tables for ShortLow ThreshSig and ShortLow	If Yes: Engine Oil Temp and	< 150 deg. C		
				ThreshRet	ValidOilTemp Model or No OilTempSensor DTC's	EngOilModeledTemp Valid EngOilTempSensorCircuitFA		
					<u>If No:</u> No Eng Oil Temp enable criteria			
Knock Sensor (KS) Circuit High Bank 2	P0333	This diagnostic checks for an out of range high knock sensor	Sensor Input Signal Line or	< 2.02 Volts	ECT Engine Run Time	≥ -40 deg. C ≥ 2 seconds		Type: B MIL: YES
E38 & E67 controllers		signal	Sensor Return Signal Line	> 3.76 Volts	Valid Oil Temp Required? (1= Yes, 0 = No)	= 0	100 msec rate	Trips: 2
					If Yes: Engine Oil Temp and ValidOilTemp Model	< 256 deg. C EngOilModeledTemp Valid		
					or No OilTempSensor DTC's	EngOilTempSensor CircuitFA		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					If No: No Eng Oil Temp enable criteria			
Knock Sensor (KS) Circuit High Bank 2	P0333	This diagnostic checks for an out of range high knock sensor signal	Sensor Input Signal Line	> ShortHi ThreshSig (Volts)	ECT Engine Run Time	≥ -40 deg. C ≥ 1 seconds	·	Type: B MIL: YES Trips: 2
E37 controllers			or Sensor Return Signal Line	> ShortHi ThreshRet (Volts)	Valid Oil Temp Required? (1= Yes, 0 = No)	= 1	100 msec rate	
				See Supporting Tables for ShortHi ThreshSig and ShortHi ThreshRet	If Yes: Engine Oil Temp and ValidOilTemp Model or No OilTempSensor DTC's	< 150 deg. C EngOilModeledTemp Valid EngOilTempSensorCircuitFA		
					<u>If No:</u> No Eng Oil Temp enable criteria			
Crankshaft Position (CKP) Sensor A Circuit	P0335	Determines if a fault exists with the crank position sensor signal	Engine-Cranking Crankshaft Test:		Engine-Cranking Crankshaft Test:		Engine-Cranking Crankshaft Test:	Type B 2 trips
			Time since last crankshaft position sensor pulse received	>= 4.0 seconds	Starter engaged AND (cam pulses being received OR (DTC P0101	= FALSE	Continuous every 100 msec	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Time-Based Crankshaft Test: No crankshaft pulses received Event-Based Crankshaft Test: No crankshaft pulses received	>= 0.3 seconds	AND DTC P0102 AND DTC P0103 AND Engine Air Flow Time-Based Crankshaft Test: Engine is Running Starter is not engaged No DTC Active: Event-Based Crankshaft Test: Engine is Running OR Starter is engaged No DTC Active:	= FALSE = FALSE > 3.0 grams/second)) 5VoltReferenceB_FA 5VoltReferenceB_FA 90340 P0341	Time-Based Crankshaft Test: Continuous every 12.5 msec Event-Based Crankshaft Test: 2 failures out of 10 samples One sample per engine revolution	
Crankshaft Position (CKP) Sensor A Performance	P0336	Determines if a performance fault exists with the crank position sensor signal	Crank Re- synchronization Test: Time in which 25 or more crank re- synchronizations occur Time-Based Crankshaft Test:	< 20.0 seconds	Crank Re-synchronization Test: Engine Air Flow Cam-based engine speed No DTC Active: Time-Based Crankshaft Test:	>= 3.0 grams/second	Crank Re- synchronization Test: Continuous every 250 msec Time-Based Crankshaft Test:	Type E 2 trips

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			No crankshaft synchronization gap		Engine is Running		Continuous every 12.5 msec	
			found	>= 0.4 seconds	Starter is not engaged			
					No DTC Active:	5VoltReferenceB_FA		
			Engine Start Test during Crank:		Engine Start Test during Crank:		Engine Start Test during Crank:	
			Time since starter engaged without detecting crankshaft synchronization gap	>= 1.5 seconds	Starter engaged AND (cam pulses being received		Continuous every 100 msec	
					OR (DTC P0101 AND DTC P0102 AND DTC P0103 AND Engine Air Flow	= FALSE = FALSE = FALSE > 3.0 grams/second))		
			Event-Based Crankshaft Test:		Event-Based Crankshaft Test:		Event-Based Crankshaft Test:	
			Crank Pulses received in one engine revolution OR	< 51 seconds	Engine is Running OR Starter is engaged		8 failures out of 10 samples	
			Crank Pulses received in one engine revolution	> 65 seconds	No DTC Active:	5VoltReferenceA_FA 5VoltReferenceB_FA P0340 P0341	One sample per engine revolution	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Camshaft	P0340	Determines if a fault	Engine Cranking		Engine Cranking		Engine Cranking	Туре В
Position (CMP)		exists with the cam	Camshaft Test:		Camshaft Test:		Camshaft Test:	2 trips
Sensor Circuit		position bank 1 sensor						
Bank 1 Sensor A		A signal	Time since last		Starter engaged		Continuous every	
			camshaft position				100 msec	
			sensor pulse received		AND			
				>= 5.5 seconds	(cam pulses being			
			OR		received			
			Time that starter has		OR			
			been engaged without		(DTC P0101	= FALSE		
			a camshaft sensor		AND DTC P0102	171202		
			pulse	>= 4.0 seconds	7448 81010102	= FALSE		
			7 - 4.0 300011d3	AND DTC P0103	- I ALGE			
				ANDBIGTOTOS	= FALSE			
				AND	- I ALOL			
				Engine Air Flow	> 3.0 grams/second))			
				Lingine All 1 low	5.0 grams/second))			
			Time-Based		Time-Based Camshaft		Time-Based	
			Camshaft Test:		Test:		Camshaft Test:	
			Camsnait TCst.		1031.		Carrisnait 1Cst.	
			Fewer than 4		Engine is Running		Continuous every	
			camshaft pulses		Lingine is ixunining		100 msec	
			received in a time	> 3.0 seconds	Starter is not engaged		100 msec	
			l'eceiveu iii a tiiile	2 3.0 Seconds	Starter is not engaged			
					No DTC Active:	5VoltReferenceA FA		
					No DTC Active.	SVOILREIEIEIICEA_FA		
			Fast Event-Based		Fast Event-Based		Fast Event-Based	
			Camshaft Test:		Camshaft Test:		Camshaft Test:	1
			Carristiant Test.		Carristiant Test.		Camsnait rest.	
			No comphaft nulses		Crankshaft is		Continuous avenu	
			No camshaft pulses				Continuous every MEDRES event	
			received during first 24 MEDRES events		synchronized		INIEDRES event	
			Z4 MEDUES EAGINS		Ctartar much ha and and			
					Starter must be engaged			
			(to enable the diagnostic,			
			(There are 24		but the diagnostic will not			
			MEDRES events per		disable when the starter			
			engine cycle)		is disengaged			
					No DTC Active:	5VoltReferenceA_FA		
						5VoltReferenceB_FA		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Slow Event-Based Camshaft Test: The number of camshaft pulses received during 100 engine cycles	= 0	Slow Event-Based Camshaft Test: Crankshaft is synchronized No DTC Active:	CrankSensor_FA 5VoltReferenceA_FA 5VoltReferenceB_FA CrankSensor_FA	Slow Event-Based Camshaft Test: 8 failures out of 10 samples Continuous every engine cycle	
Camshaft Position (CMP) Sensor Performance Bank 1 Sensor A	P0341	Determines if a performance fault exists with the cam position bank 1 sensor A signal	Fast Event-Based Camshaft Test: The number of camshaft pulses received during first 24 MEDRES events is less than 2 or greater than 8 (There are 24 MEDRES events per engine cycle) Slow Event-Based Camshaft Test: The number of camshaft pulses received during 100 engine cycles OR	< 398 > 402	Fast Event-Based Camshaft Test: Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active: Slow Event-Based Camshaft Test: Crankshaft is synchronized No DTC Active:	5VoltReferenceA_FA 5VoltReferenceB_FA CrankSensor_FA 5VoltReferenceA_FA 5VoltReferenceB_FA CrankSensor_FA	Fast Event-Based Camshaft Test: Continuous every MEDRES event Slow Event- Based Camshaft Test: 8 failures out of 10 samples Continuous every engine cycle	2 trips

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
IGNITION CONTROL #1 CIRCUIT	P0351	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 1 (Cylinders 1 and 4 for V6 with waste spark)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts	63 Samples	Type: B MIL: YES Trips: 2
IGNITION CONTROL #2 CIRCUIT	P0352	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 2 (Cylinders 2 and 5 for V6 with waste spark)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage			Type: B MIL: YES Trips: 2
IGNITION CONTROL #3 CIRCUIT	P0353	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 3 (Cylinders 3 and 6 for V6 with waste spark)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts	·	Type: B MIL: YES Trips: 2
IGNITION CONTROL #4 CIRCUIT	P0354	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 4 (if applicable)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts	·	Type: B MIL: YES Trips: 2

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
IGNITION CONTROL #5 CIRCUIT	P0355	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 5 (if applicable)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts	63 Samples	Type: B MIL: YES Trips: 2
IGNITION CONTROL #6 CIRCUIT	P0356	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 6 (if applicable)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts		Type: B MIL: YES Trips: 2
IGNITION CONTROL #7 CIRCUIT	P0357	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 7 (if applicable)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts	63 Samples	Type: B MIL: YES Trips: 2
IGNITION CONTROL #8 CIRCUIT	P0358	This diagnostic checks the circuit for electrical integrity during operation. Monitors EST for Cylinder 8 (if applicable)	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Engine running Ignition Voltage	> 5.00 Volts		Type: B MIL: YES Trips: 2
Camshaft Position (CMP) Sensor Circuit Bank 1 Sensor B	P0365	Determines if a fault exists with the cam position bank 1 sensor B signal	Engine Cranking Camshaft Test: Time since last camshaft position sensor pulse received OR	>= 5.5 seconds	Engine Cranking Camshaft Test: Starter engaged AND (cam pulses being received			Type B 2 trips

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Time that starter has been engaged without a camshaft sensor		OR (DTC P0101 AND DTC P0102	= FALSE		
			pulse	>= 4.0 seconds	AND DTC P0103	= FALSE = FALSE		
					AND Engine Air Flow	> 3.0 grams/second))		
			Time-Based Camshaft Test:		Time-Based Camshaft Test:		Time-Based Camshaft Test:	
			Fewer than 4 camshaft pulses received in a time	> 3.0 seconds	Engine is Running Starter is not engaged		Continuous every 100 msec	
			received in a time	2 3.0 Seconds	No DTC Active:	5VoltReferenceA_FA		
			Fast Event-Based Camshaft Test:		Fast Event-Based Camshaft Test:		Fast Event-Based Camshaft Test:	-
			No camshaft pulses received during first 10 MEDRES events		Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not		Continuous every MEDRES event	
			(There are 10 MEDRES events per engine cycle)		disable when the starter is disengaged			
					No DTC Active:	5VoltReferenceA_FA 5VoltReferenceB_FA CrankSensor_FA		
			Slow Event-Based Camshaft Test:		Slow Event-Based Camshaft Test:		Slow Event- Based Camshaft Test:	
			The number of camshaft pulses received during 100 engine cycles	= 0	Crankshaft is synchronized No DTC Active:	5VoltReferenceA_FA 5VoltReferenceB_FA	8 failures out of 10 samples	

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	_	illum.
						CrankSensor_FA	Continuous every	
							engine cycle	
Camshaft	P0366	Determines if a	Fast Event-Based		Fast Event-Based		Fast Event-Based	Type B
Position (CMP)	1 0300	performance fault	Camshaft Test:		Camshaft Test:		Camshaft Test:	2 trips
Sensor		exists with the cam	Odmonait Toot.		<u>Garrisrian Test.</u>		Cambrialt Test.	2 1103
Performance		position bank 1 sensor	The number of		Crankshaft is		Continuous every	
Bank 1 Sensor B		B signal	camshaft pulses		synchronized		MEDRES event	
			received during first		Starter must be engaged			
			10 MEDRES events is		to enable the diagnostic,			
			less than 3 or greater		but the diagnostic will not			
			than 11		disable when the starter			
					is disengaged			
			(There are 10					
			MEDRES events per					
			engine cycle)		No DTC Active:	5VoltReferenceA FA		
			crigine cycle)		No DTC Active.	5VoltReferenceB FA		
						CrankSensor FA		
						Orankochsol_i A		
			Slow Event-Based		Slow Event-Based		Slow Event-	
			Camshaft Test:		Camshaft Test:		Based Camshaft	
							Test:	
			The number of		Crankshaft is		8 failures out of	
			camshaft pulses		synchronized		10 samples	
			received during 100		No DTC Active:	5VoltReferenceA FA		
			engine cycles	< 398		5VoltReferenceB_FA		
			OR	> 402		CrankSensor_FA	Continuous every	
							engine cycle	
Secondary AIR	P0411	Detects an insufficient	System Pressure		BARO	> 60 kPa	Phase 1	
Incorrect Airflow		flow condition.	Error (vs. predicted		Inlet Air Temp		Conditional test	2 trip(s)
Single Valve			System Pressure)	> 5.0 kPa	Coolant Temp		weight > 4.0	
Systems		This test is run during			i i	< 60.0 deg C.	seconds	Туре В
		Phase 1 (AIR pump	OR	< -5.0 kPa	Engine off time	> 3600.0 seconds	\neg	
		commanded On, Valve			System Voltage	> 10.0 OR < 32.0 Volts		
		commanded Open).	OR the following			< 20 kPa for 2.0 sec.	Total 'String	
			String Length (SL)		Engine Speed		Length'	
			Test:			> 50 gm/s for 3.0 sec.	accumulation	
			System Pressure		SL Stability time	> 3.0 seconds Bank 1	time:	
			Error	> 5.0 kPa				

•	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		Leaks downstream of the valve are detected via an evaluation of both pressure error and average pressure "String Length" (SL) – a term that represents the absolute pressure delta accumulated every 6.25ms, then averaged over the duration of the test. Low SL values are indicative of downstream leaks or blockages.	AND the Average String Length	< -2.0 kPa < SL Threshold Bank 1 Table	SL RPM range Conditional test weight the follow Phase 1 Baro Phase 1 MAF Phase 1 System W Phase 1 Ambient Te (see Supp No active DTCs:	rpm < 5600 or > 6400 is calculated by multiplying wing Factors: Test Weight Factor Test Weight Factor (olt Test Weight Factor emp Test Weight Factor emp Test Weight Factor orting Tables) AIRSystemPressureSensor FA AIRValveControlCircuit FA AIRPumpControlCircuit FA AIRPumpControlCircuit FA AMAF_SensorFA ECT_SensorFA ECT_Sensor_FA EngineMisfireDetected_FA CatalystSysEfficiencyLoB1_FA CatalystSysEfficiencyLoB2_FA ControllerProcessorPerf_FA 5VoltReferenceA_FA IgnitionOutputDriver_FA FuelInjectorCircuit_FA	> 10 sec Bank1 Frequency: Once per trip when AIR pump commanded On	inum.
Solenoid Control Circuit	P0412	This DTC checks the AIR solenoid circuit for electrical integrity	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		System Voltage	> 10.0 Volts < 32.0 Volts	50 failures out of 63 samples 250 ms loop Continuous	2 trip(s) Type B
Secondary AIR Pump Control Circuit	P0418	This DTC checks the AIR Pump circuit for electrical integrity	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		System Voltage	> 10.0 Volts < 32.0 Volts	50 failures out of 63 samples 250 ms loop Continuous	2 trip(s) Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Catalyst System Low Efficiency Bank 1	P0420	Oxygen Storage	Normalized Ratio OSC Value (EWMA filtered)	< 0.335	<u>Valid Idle</u>	Period Criteria	1 test attempted per valid idle period	Type A 1 Trip(s)
		The catalyst washcoat	contains Cerium Oxide.		Throttle Position	< 1.00 %		
		Cerium Oxide reacts wi	th NO and O2 during		Vehicle Speed		Minimum of 1 test	
		lean A/F excursions to			Engine speed	> 1100 RPM for a minimum of	per trip	
			Oxide reacts with CO stored oxygen (I.e.			5 seconds since end of last idle period.	Maximum of 8 tests per trip	
	and H2 to release this stored oxygen (I.e. Cerium Reduction). This is referred to as th Oxygen Storage Capacity, or OSC. CatMostrategy is to "measure" the OSC of the catalyst through forced Lean and Rich A/F excursions. Normalized Ratio OSC Value Calculation		ity, or OSC. CatMon's 'the OSC of the		Engine run time	MinimumEngineRunTime, This is a function of Coolant Temperature, please see Supporting Tables	Frequency: Fueling Related : 12.5 ms OSC	
	Normalized Ratio OSC Value Calculation Information and Definitions = 1. Raw OSC Calculation = (post cat O2 Restime - pre cat O2 Resp time) 2. BestFailing OSC value from a calibration table (based on temp and exhaust gas flow)	ons =		Tests attempted this trip	< 255	Measurements: 100 ms		
		time - pre cat O2 Resp 2. BestFailing OSC valu	time) ue from a calibration		, ,	nas not yet completed for the rent trip.	Temp Prediction: 1000ms	
		3. WorstPassing OSC v			Catalyst Idle Co.	nditions Met Criteria		
		and exhaust gas flow) Normalized Ratio Calcu			General Ena Valid Idle Pe			
		A Normalized Ratio of 1	l essentially represents		Green Converter Delay	Not Active	+	1
		a good part and a ratio				-20 < ° C < 250	1	
	ŭ	represents a very bad p	part.		Intrusive test(s): Fueltrim Post O2 EVAP			
					EGR		l	
					RunCrank Voltage			
		The Order of March	an Tankin de contra		Ethanol Estimation			
		The Catalyst Monitoria				45 < ° C < 140	l	
		idle. Several conditions must be meet in order to execute this test. These conditions and their related values are listed in the secondary parameters area of this document.			Barometric Pressure Idle Time before going intrusive is	< 50 Seconds		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				* and G	Short Term Fuel To Vehicle specified catalyst ter (refer to "So Engine Airflow > MinAi (refer to "So (Based on enging WarmedUpEvent of at least 15 seconds seconds consecutive involves having the To Valid Idle Performent of the Also, in order to incompart to counter (counter must vehicle speed must executed in the Also in the Als	d if < 1.24 MPH and the throttle position < 1.00 % as identified in the Valid Idle Period Criteria section. Tim 0.90 < ST FT < 1.10 Timp > MinCatTemp table (degC) Timpporting Tables" tab) AND Timporting Tables" tab) Timporting Tables table (g/s) Timporting Tables table		
					Closed lo	op fueling Enabled	┨	
						oop Enable Criteria" section of g Tables" tab for details.	,	
						PRNDL	-	
					is in Drive Range on	an Auto Transmission vehicle.		
						:: Must hold true from after itions Met to the end of test	1	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						MAF 5.00 < g/s < 15.00		
					Predicted ca	talyst < 710 degC		
					temper	ature		
					Engine Fueling Cr	iteria at Beginning of Idle Period		
					The following fueli	ng related must also be met from	1	
					between 4 and 7	seconds after the Catalyst Idle		
					Conditions Met Cr	iteria has been met for at least 4		
	1				seconds prior	to allowing intrusive control		
						-		
	1							
						re-O2 >= 2 grams/second		
						tches		
					Short Term Fuel Trin	n Avg 0.960 < ST FT Avg < 1.040		
							_	
						onse (RSR) feature will initiate		
						multiple tests:		
						ween current EWMA value and the		
						lized Ratio value is > 0.550 and the		
					current OSC No	rmalized Ratio value is < 0.260		
	1							
	1				M. 10. 10170	21	_	
					Maximum of 24 RSF	R tests to detect failure when RSR i	S	
	1					enabled.		
	1				Cross C	anyartar Dalay Critaria	-	
					Green C	onverter Delay Criteria		
	1							
	1				This is part of the ob	eck for the Catalyst Idle Conditions	\exists	
						et Criteria section	' [
	1				IVI	Ci Ontena Section		
					The diagnostic will be	ot be enabled until the following ha		
					The diagnostic will h	been met:	° [
						DOGIT HIEL.		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Parameters Predicted catalyst te no Note: this feature is new and car F G I Am IAT CO2S_Ba O2S_Ba O2S_Ba O2S_Ba Fuel	Conditions emperature > 0 ° C for 0 seco on-continuously. only enabled when the vehicle onto be enabled in service PTO Not Active eneral Enable OTC's Not Set MAF_SensorFA bPresDfltdStatus _SensorCircuitFA CT_Sensor_FA ank_1_Sensor_1_FA ank_1_Sensor_2_FA ank_2_Sensor_1_FA ank_2_Sensor_2_FA TrimSystemB1_FA	Required nds	
					Fuel Tengine EvapPur IAC EGRVa EGR C Crank	TrimSystemB1_FA TrimSystemB2_FA MisfireDetected_FA GeSolenoidCircuit_FA SystemRPM_FA AlvePerformance_FA RValveCircuit_FA CamSensor_FA KSensorFaultActive Performance_FA ginePowerLimited		
Catalyst System Low Efficiency Bank 2		Oxygen Storage	Normalized Ratio OSC Value (EWMA filtered)	< 0.335	Vehicl <u>Valid Idle Period</u> <u>Criteria</u>	eSpeedSensor_FA	1 test attempted per valid idle period Minimum of 1 te per trip Maximum of 8 tests per trip	1 Trip(s

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
							_	
							Frequency:	
							Fueling Related :	
							12.5 ms	
							000	
							OSC	
							Measurements:	
							100 ms	
							Town Dradiation	
							Temp Prediction:	
							1000ms	
			<u> </u>					
			contains Cerium Oxide.			ition < 1.00 %		
			vith NO and O2 during			peed < 1.24 MPH	l	
			to store the excess		Engine speed	> 1100 RPM for a minimum of		
			oxidation). During rich			5 seconds since end of last		
			n Oxide reacts with CO			idle period.		
		and H2 to release th						
		Cerium Reduction). The	his is referred to as the					
		Oxygen Storage Capac	city, or OSC. CatMon's		Engine run time	≥ MinimumEngineRunTime,	1	
		strategy is to "meas	ure" the OSC of the		Engine run ume	This is a function of		
		catalyst through force	ed Lean and Rich A/F					
			rsions			Coolant Temperture, please		
						see Supporting Tables		
		Normalized Ratio OS	SC Value Calculation					
		Information an	d Definitions =					
			on = (post cat O2 Resp				l	
		time - pre cat			Tests attempted this	s trip < 255		
			alue from a calibration				l	
		table (based on temp			The catalyst diagnosti	c has not yet completed for the		
		WorstPassing OSC			current trip.			
			st gas flow)					
		and exhaus	ot gas now)		Catalyst Idle Condition	ons	1	
		Normalized Patio Cal	culation = (1-2) / (3-2)		Met Criteria			
		Normalized Natio Cal	culation = (1-2)7 (3-2)					
		A Normalized Ratio of	1 essentially represents		Genera	I Enable met and the	1	
			atio of 0 essentially			e Period Criteria met		
		represents a						
		represents a	vory bad part.					
					Green Converter Dela	y Not Active	l	
					Orcen Conventer Dela	y Trochouve		-
					Induction	n Air -20 < ° C < 250	l	
					induction	1711-20 \ 0 \ 200		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Intrusive test(s): Fueltrim Post O2 EVAP EGR	=Not Active		
					RunCrank Voltage	> 10.90 Volts	-	
					Ethanol Estimation	NOT in Progress		
			oring Test is done during	1		45 < ° C < 140	_	
		to execute this test	ons must be meet in order These conditions and re listed in the secondary		Barometric Pressure	> 70 KPA	_	
		•	ea of this document.		Idle Time before going intrusive is	< 50 Seconds		
					Idle time is incremented if Vehicle speed	< 1.24 MPH and the throttle position < 1.00 % as identified in the Valid Idle Period Criteria section.		
					Short Term Fuel Trim	0.90 < ST FT < 1.10	-	
					(refer to "Supplement of the Control	> MinCatTemp table (degC) porting Tables" tab) AND powToWarmCatalyst table (g/s) porting Tables" tab) coolant at the time the ts counter resets to 0.)	-	
					seconds consecutively involves having the TPS	vith a closed throttle time < 90 (closed throttle consideration S < the value as stated in the od Criteria Section).		
					counter (counter must exvehicle speed must exceed TPS must exceed the TPS	ment the WarmedUpEvents (ceed 15 cal value), either the ed the vehicle speed cal or the S cal as stated in the Valid Idle ria section above.		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Closed	l loop fueling Enabled		
						d Loop Enable Criteria" section	or	
					the "Suppor	ting Tables" tab for details.		
						PRNDL		
					is in Drive Range	on an Auto Transmission vehicle		
						eria :: Must hold true from after		
					Catalyst Idle Co	onditions Met to the end of test		
						MAF 5.00 < g/s < 15.00		
					Predicted cataly			
					temperature			
					Engine Fueling Co	riteria at Beginning of Idle Perio	d	
						ing related must also be met fro		
						' seconds after the Catalyst Idle riteria has been met for at least		
						r to allowing intrusive control	"	
					3ccond3 prior	to anowing marasive control		
					Number of p	re-O2 >= 2		
						itches		
					Short Term Fuel Tri	m Avg 0.96 < ST FT Avg < 1.04		
					Daniel Ota - Daniel	(DOD) for down will it is it is	_	
						oonse (RSR) feature will initiate		
						multiple tests:		
					If the difference be	tween current EWMA value and th	ne	
						alized Ratio value is > 0.550 and t		
					current OSC No	ormalized Ratio value is < 0.290		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Maximum of 24 RSI	R tests to detect failure when RSR is		
						enabled.		
					Green Converter D	Delay		
					Criteria			
					This is part of the ch	heck for the Catalyst Idle Conditions		
					N	let Criteria section		
]	
					The diagnostic will n	not be enabled until the following has		
						been met:		
					Predicted catalyst	temperature > 0 ° C for 0 seconds	1	
						non-continuously.		
					Note: this feature	is only enabled when the vehicle is		
						annot be enabled in service		
]	
						PTO Not Active		
						General Enable		
						DTC's Not Set		
						MAF_SensorFA		
						mbPresDfltdStatus		
						T_SensorCircuitFA		
						ECT_Sensor_FA		
						Bank_1_Sensor_1_FA		
						Bank_1_Sensor_2_FA		
						Bank_2_Sensor_1_FA		
						Bank_2_Sensor_2_FA	1	
						elTrimSystemB1_FA		
						elTrimSystemB2_FA		
						neMisfireDetected_FA		
						urgeSolenoidCircuit_FA		
						C_SystemRPM_FA		
						/alvePerformance_FA		
						GRValveCircuit_FA		
						CamSensor_FA		
						nkSensorFaultActive		
						S_Performance_FA		
						nginePowerLimited		
					Vehi	icleSpeedSensor_FA	1	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		This DTC will detect a small leak (≥ 0.020") in the EVAP system between the fuel fill cap and the purge solenoid. The engine off natural vacuum method (EONV) is used. EONV is an evaporative system leak detection diagnostic that runs when the vehicle is shut off when enable conditions are met. Prior to sealing the system and performing the diagnostic, the fuel volatility is analyzed. In an open system (Canister Vent Solenoid [CVS] open)	Criteria The total delta from peak pressure to peak vacuum during the test is normalized against a calibration pressure threshold table that is based upon fuel level and ambient temperature. (See P0442: EONV Pressure Threshold Table on Supporting Tables Tab). The normalized value is calculated by the following equation: 1 - (peak pressure - peak vacuum) / pressure threshold. The normalized value is entered into EWMA (with 0= perfect pass and 1= perfect fail).	Value	Parameters Fuel Level Drive Time Drive length ECT Baro Odometer Time since last complete test if normalized result and EWMA is passing OR Time since last complete test if normalized result or EWMA is failing			1 trip Type A EWMA Average run
			When EWMA is , the DTC light is	> 0.62 (EWMA Fail Threshold)	Conditions for Estimate of Ambient Air Temperature to be valid:			

Component/ Fau		• • • • • • • • • • • • • • • • • • • •		Threshold	Secondary	Enable		MIL
System Cod	le De		Criteria	Value	Parameters	Conditions	Required	illum.
	ch so Af cloup the (p properties of the coordinate of the coordina	fter the volatility neck, the vent blenoid will close. fter the vent is osed, typically a build o of pressure from he hot soak begins hase-1). The ressure typically will	The DTC light can be turned off if the EWMA is and stays below the EWMA fail threshold for 2 additional consecutive trips.	≤ 0.35 (EWMA Re-Pass Threshold)	1. Cold Start Startup delta deg C (ECT-IAT) OR 2. Short Soak and Previous EAT Valid Previous time since engine off OR 3. Not a Cold Start and Previous EAT Valid and between Short and Long Soak Previous time since engine off AND Must expire Estimate of Ambient Temperature Valid Conditioning Time. "P0442: Estimate of Ambient Temperature Valid Conditioning Time" in Supporting Tables Tab.	≤ 8 °C ≤ 7200 seconds 7200 seconds < Time < 25200 seconds Vehicle Speed ≥ 29.2 mph AND Mass Air Flow ≥ 0 g/sec		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					OR 4. Not a Cold Start and Previous EAT Not Valid and less than Long Soak			
					Previous time since engine off AND Must expire maximum value in Estimate of Ambient Temperature Valid Conditioning Time. Please see "P0442: Estimate of Ambient Temperature Valid Conditioning Time" in Supporting Tables Tab.	< 25200 seconds Vehicle Speed ≥ 29.2 mph AND Mass Air Flow ≥ 0 g/sec		
				Abort Conditions:	OR 5. Long Soak Previous time since engine off 1. High Fuel Volatility]	
					During the volatility phase, pressure in the fuel tank is integrated vs. time. If the integrated pressure is	< -5		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					then test aborts and			
					unsuccessful attempts is			
					incremented.			
					OR			
					2. Vacuum Refueling			
					Detected			
					20100104			
					See P0454 Fault Code for			
					information on vacuum			
					refueling algorithm.			
					refacility digoritims.			
					OR			
					3. Fuel Level Refueling			
					Detected			
					See P0464 Fault Code for			
					information on fuel level			
					refueling.			
					OR			
					4. Vacuum Out of			
					Range and No Refueling			
					See P0451 Fault Code for			
					information on vacuum			
					sensor out of range and			
					P0464 Fault Code for			
					information on fuel level			
					refueling.			
	1							

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					OR 5. Vacuum Out of			
					Range and Refueling			
					Detected			
					See P0451 Fault Code for			
					information on vacuum			
					sensor out of range and			
					P0464 Fault Code for			
					information on fuel level			
					refueling.			
					OR			
					6. Vent Valve Override			
					Failed			
					Davisa control voice on			
					Device control using an off-board tool to control			
					the vent solenoid, cannot			
					exceed			
					during the EONV test			
						0.50 seconds		
					OD			
					OR 7. Key up during EONV			
					test			
					No active DTCs:	FuelLevelDataFault		
						MAF_SensorFA		
						ECT_Sensor_FA		
						IAT_SensorFA VehicleSpeedSensor_FA		
						IgnitionOffTimeValid		
						AmbientAirDefault		
			1			P0443	1	I

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					1	P0446		
						P0449		
						P0452		
						P0453		
						P0455		
						P0496	ł	
Evaporative Emission (EVAP)	P0443	This DTC checks the circuit for electrical	The ECM detects that the commanded state		PT Relay Voltage	11 volts ≤ Voltage ≤ 32 volts	20 failures out of 25 samples	2 trips Type B
Canister Purge		integrity during	of the driver and the				25 samples	Турев
Solenoid Valve Circuit (ODM)		operation.	actual state of the control circuit do not				250 ms / sample	
			match.					
							Continuous with	
							solenoid	
							operation	
Evaporative	P0446	This DTC will	Vent Restriction Prep		Fuel Level	10 ≤ Percent ≤ 90	Once per Cold	2 trips
Emission (EVAP)		determine if a	Test:		System Voltage	11 volts ≤ Voltage ≤ 32 volts	Start	Type B
Vent System		restriction is present in	Vented Vacuum	< -623 Pa	System voltage	Tr voits = voitage = 62 voits	Otart	I ypc B
Performance		the vent solenoid, vent	venteu vacuum	< -023 Fa	Startup IAT	1 °C < Tomporatura < 20 °C		
Chomianoc		filler, vent hose or	OD		Startup IAT	4 °C ≤ Temperature ≤ 30 °C		
		EVAP canister.	OR		l	1		
		EVAF Carlister.			Startup ECT	≤ 35 °C		
		This toot work with	Vented Vacuum	> 1245 Pa	BARO	≥ 70 kPa	Time is	
		This test runs with	for 60 seconds		No active DTCs:		dependent on	
		normal purge and vent				MAP_SensorFA	driving conditions	
		valve is open.	Vent Restriction Test:			TPS_FA		
						VehicleSpeedSensor_FA		
			Tank Vacuum	> 2989 Pa		·		
			for 5 seconds			IAT_SensorCircuitFA		
			BEFORE			ECT_Sensor_FA		
				> 6 litoro				
			Purge Volume	≥ 6 liters		AmbientAirDefault	Mandania	
						EnginePowerLimited	Maximum time	
			After setting the DTC			P0443	before test abort	
			for the first time, 2			P0449	is 1000 seconds	
			liters of fuel must be			P0452		
			consumed before			P0453		
			setting the DTC for			P0454		
			the second time.					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Evaporative Emission (EVAP) Vent Solenoid Control Circuit (ODM)	P0449	This DTC checks the circuit for electrical integrity during operation. If the P0449 is active, an intrusive test is performed with the vent solenoid commanded closed for 15 seconds.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Run/Crank voltage goes to 0 volts at key off	11 volts ≤ Voltage ≤ 32 volts	20 failures out of 25 samples 250 ms / sample Continuous with solenoid operation	2 trips Type B
Fuel Tank Pressure (FTP) Sensor Circuit Performance	P0451	The DTC will be set if the fuel tank vacuum sensor is out of range when it tries to re-zero prior to the phase-1 or phase-2 portions of the engine-off natural vacuum small leak test.	volts) Upper voltage threshold (voltage addition above the nominal voltage) Lower voltage threshold (voltage subtraction below the nominal voltage)	0.2 volts	This test will execute whenever the engine-off natural vacuum small leak test (P0442) executes		This test is executed during an engine-off natural vacuum small leak test. The number of times that it executes can range from zero to two per engine-off period.	1 trip Type A EWMA Average run length: 6
			The difference between tank vacuum sensor voltage and the nominal offset voltage is then normalized against the appropriate threshold listed above to produce a ratio between 0.0 and 1.0. This normalized rezero ratio is then				The length of the test is determined by the refueling rationality test, which can take up to 600 seconds to complete.	code clear or non- volatile reset

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			filtered with a EWMA (with 0= perfect pass and 1=perfect fail).					
			When EWMA is	> 0.73 (EWMA Fail Threshold)				
			, the DTC light is illuminated.	,				
			The DTC light can be turned off if the EWMA is	≤ 0.40 (EWMA Re-Pass				
			and stays below the EWMA fail threshold for 2 additional consecutive trips.	Threshold)				
Fuel Tank Pressure (FTP) Sensor Circuit Low Voltage	P0452	This DTC will detect a fuel tank pressure sensor signal that is too low out of range.	Fuel tank pressure sensor signal	< 0.15 volts (3 % of Vref or ~ 1681 Pa)	Time delay after sensor power up for sensor warm-up		80 failures out of 100 samples	2 trips Type B
Ū		, and the second	The normal operating range of the fuel tank pressure sensor is 0.5 volts (~1245 Pa) to		ECM State ≠ crank	is 0.10 seconds	100 ms / sample	
			4.5 volts (~ -3736 Pa).		Stops 6.0 seconds after key-off		Continuous	
Fuel Tank Pressure (FTP) Sensor Circuit High Voltage	P0453	This DTC will detect a fuel tank pressure sensor signal that is too high out of range.		> 4.85 volts (97% of Vref or ~ -4172 Pa)	Time delay after sensor power up for sensor warm-up		80 failures out of 100 samples	2 trips Type B
3			The normal operating range of the fuel tank pressure sensor is 0.5		ECM State ≠ crank	is 0.10 seconds	100 ms / sample	

Component/	Fault	•	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			volts (~1245 Pa) to 4.5 volts (~ -3736 Pa).		Stops 6.0 seconds after key-off		Continuous	
Fuel Tank Pressure (FTP) Sensor Circuit Intermittent	P0454	intermittent tank vacuum sensor signals that would have caused the engine-off natural vacuum small leak test to abort due to an apparent re- fueling event.	If an abrupt change in tank vacuum is detected the engine-off natural vacuum test is aborted due to an apparent refueling event. Subsequent to the abort, a refueling rationality test is executed to confirm that a refueling event occurred. If a refueling is confirmed, then the test sample is considered passing. Otherwise, the sample is considered failing indicating an intermittent signal problem.		This test will execute whenever the engine-off natural vacuum small leak test (P0442) executes		This test is executed during an engine-off natural vacuum small leak test. The test can only execute up to once per engine-off period. The length of the test is determined by the refueling rationality test, which can take up to 600 seconds to complete.	1 trips Type A
			An abrupt change is defined as a change in vacuum: in the span of 1.0 seconds. But in 12.5 msec.	> 112 Pa < 249 Pa			The test will report a failure if 2 out of 3 samples are failures.	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				of 10 %			Continuous when vent solenoid is closed.	
			for 30 seconds.					
Evaporative Emission (EVAP) System Large Leak Detected	P0455	This DTC will detect a weak vacuum condition (large leak or purge blockage) in the EVAP system. Purge valve is controlled (to allow purge flow) and vent valve is commanded closed.	Purge volume while Tank vacuum After setting the DTC for the first time, 2 liters of fuel must be consumed before setting the DTC for the second time. Weak Vacuum Follow- up Test (fuel cap replacement test) Weak Vacuum Test	> 11 liters ≤ 2740 Pa	Fuel Level System Voltage BARO No active DTCs:	10 % ≤ Percent ≤ 90 % 11 volts ≤ Voltage ≤ 32 volts ≥ 70 kPa MAP_SensorFA TPS_FA VehicleSpeedSensor_FA IAT_SensorCircuitFA ECT_Sensor_FA AmbientAirDefault EnginePowerLimited P0443 P0449 P0452 P0453	Once per cold start Time is dependent on driving conditions Maximum time before test abort is 1000 seconds	2 trips Type B
			Passes if tank	≥ 2740 Pa		P0454	Weak Vacuum Follow-up Test	
			Note: Weak Vacuum Follow-up Test can only report a pass.		Cold Start Test If ECT > IAT, Startup temperature delta (ECT-IAT): Cold Test Timer Startup IAT Startup ECT Weak Vacuum Follow-up Test This test can run following	≤8 °C ≤ 1000 seconds 4 °C ≤ Temperature ≤ 30 °C ≤ 35 °C	With large leak detected, the follow-up test is limited to 1300 seconds. Once the MIL is on, the follow-up test runs indefinitely.	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					a weak vacuum failure or			
					on a hot restart.			
Fuel Level	P0461	This DTC will detect a	Delta Fuel Volume		Engine Running		250 ms / sample	2 trips
Sensor 1		fuel sender stuck in	change	< 3 liters				Type B
Performance		range in the primary			No active DTCs:			
-		fuel tank.	over an accumulated			VehicleSpeedSensor_FA	Continuous	
(For use on vehicles with a			148 miles.					
single fuel tank)								
onigio raor taritty								
Fuel Level	P0461	This DTC will detect a			Engine Running		250 ms / sample	2 trips
Sensor 1		fuel sender stuck in						Туре В
Performance		range in the primary			No active DTCs:			
. -		fuel tank.				VehicleSpeedSensor_FA	Continuous	
(For use on vehicles with							_	
mechanical			Fuel Level in Primary Tank Remains in an					
transfer pump			Unreadable Range					
dual fuel tanks)			too Long					
			If fuel volume in					
			primary tank is	>= 28.5 liters				
			AND					
			Fuel volume in	4 C O litoro				
			secondary tank and remains in this	< 6.0 liters				
			condition for	124 miles.				
			OR					
			After Refuel Event				7	
			If the secondary fuel		The shutdown primary			
			volume changes by		tank volume + 3.0 liters			
			10.0 liters from		must be			
			engine "off" to engine "on" the primary			< 28.5 liters		
			volume should					
			change by 3.0 liters.					
			OR					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Distance Traveled without a Primary					
			Fuel Level Change	1				
			Delta Fuel Volume	. 0.111				
			change	< 3 liters				
			over an accumulated					
Frield evial	D0464	This DTC will detect a	50 miles.		Engine Dunning		050 mg / comple	O trime
Fuel Level Sensor 1	P0461	This DTC will detect a fuel sender stuck in			Engine Running		250 ms / sample	2 trips
Performance		range in the primary			No active DTCs:			Type B
l		fuel tank.			No active DTCs:	Vahiala Chand Canaar TA	Continuous	
(For use on		ruci tarik.				VehicleSpeedSensor_FA	Continuous	
vehicles with			Fuel Level in Primary			1	\dashv	
electric transfer			and Secondary Tanks					
pump dual fuel			Remains in an					
tanks)			Unreadable Range					
			too Long					
			If fuel volume in					
			primary tank is	>= 99.0 liters				
			AND					
			Fuel volume in					
			secondary tank	< 0.0 liters				
			and remains in this					
			condition for	200 miles.				
			OR					
			During Fuel Transfer					
			During fuel transfer,		Transfer Pump is		┪	
			when the enable		commanded on			
			conditions are met, at					
			least 3.0 liters of fuel		No device control for the			
			will be transferred		transfer pump			
			from the secondary					
			tank and 3.0 liters of		Fuel Volume in			
			fuel will be transfered		Secondary Tank			
			into the primary tank			< 43 liters		
			within 180 seconds.		Vehicle Speed	< 0 mph		
			There is a short delay		<u> </u>	·		
			of 20 seconds to allow					
	I	1	fuel slosh to settle	I	1	1	I	I

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			before the fail timer					
			begins. If the					
			secondary tank					
			volume does					
			decrease by the cal					
			amount but the					
			primary volume does					
			not increase by the					
			cal amount after the					
			fail timer has expired,					
			then P0461 sets.					
			OD					
			OR Distance Traveled				_	
			without a Primary					
			Fuel Level Change					
			1 doi 20voi Oriango					
			Delta Fuel Volume	I			-	
			change	< 3 liters				
			over an accumulated					
			98 miles.					
Fuel Level	P0462	This DTC will detect a	Fuel level Sender %		Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	100 failures out of	2 trips
Sensor 1 Circuit		fuel sender stuck out	of 5V range	< 10 %			125 samples	Type B
Low Voltage		of range low in the						
		primary fuel tank.			Run/Crank voltage goes			
					to 0 volts at key off		100 ms / sample	
							Continuous	
Fuel Level	P0463	This DTC will detect a	Fuel level Sender %		Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	100 failures out of	
Sensor 1 Circuit		fuel sender stuck out	of 5V range	> 60 %			125 samples	Туре В
High Voltage		ofrange high in the						
		primary fuel tank.			Run/Crank voltage goes			
					to 0 volts at key off		100 ms / sample	

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
							Continuous	
Fuel Level	P0464	This DTC will detect	If a change in fuel		This test will execute		This test is	1 trips
Sensor 1 Circuit		intermittent fuel level	level is detected, the		whenever the engine-off		executed during	Type A
Intermittent		sensor signals that	engine-off natural		natural vacuum small		an engine-off	
		would have caused the			leak test (P0442)		natural vacuum	
		engine-off natural	aborted due to an		executes		small leak test.	
		vacuum small leak test to abort due to an					The test can only	
		apparent re-fueling	event. Subsequent to the abort, a refueling				execute up to once per engine-	
		event.	rationality test is				off period.	
		event.	executed to confirm				on penou.	
			that an actual					
			refueling event					
			occurred. If a					
			refueling event is					
			confirmed, then the					
			test sample is					
			considered passing.				The length of the	
			Otherwise, the				test is determined	
			sample is considered				by the refueling	
			failing indicating an				rationality test,	
			intermittent signal				which can take	
			problem.				up to 600	
							seconds to	
							complete.	
			An intermintant				The test will	
			change in fuel level is				report a failure if	
			defined as:				2 out of 3	
			The fuel level				samples are	
				by 10 %			failures.	
			and does not remain					
				> 10 %				
			for 30 seconds during				100 ms / sample	
			a 600 second					
			refueling rationality					
I			test.					
I								

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Cooling Fan 1 Relay Control Circuit (ODM)	P0480	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Engine Speed	11 volts ≤ Voltage ≤ 32 volts ≥ 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous with fan operation	2 trips Type B Not used on systems with Mechani cal Fan)
Cooling Fan 2 Relay Control Circuit (ODM)	P0481	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Engine Speed	11 volts ≤ Voltage ≤ 32 volts ≥ 400 RPM	20 failures out of 25 samples 250 ms / sample Continuous with fan operation	2 trips Type B Not used on systems with Mechani cal Fan)
Evaporative Emission (EVAP) System Flow During Non- Purge	P0496	This DTC will determine if the purge solenoid is leaking to engine manifold vacuum. This test will run with the purge valve closed and the vent valve closed.	Tank Vacuum for 5 seconds BEFORE Test time	> 2491 Pa ≥ refer to "P0496: Purge Valve Leak Test Engine Vacuum Test Time (Cold Start) as a Function of Fuel Level table" in Supporting Tables Tab.	Fuel Level System Voltage BARO Startup IAT Startup ECT Engine Off Time No active DTCs:	10 % ≤ Percent ≤ 90 % 11 volts ≤ Voltage ≤ 32 volts ≥ 70 kPa 4 °C ≤ Temperature ≤ 30 °C ≤ 35 °C ≥ 28800.0 seconds MAP_SensorFA TPS_FA VehicleSpeedSensor_FA IAT_SensorCircuitFA ECT_Sensor_FA AmbientAirDefault EnginePowerLimited	Once per cold start Cold start: max time is 1000 seconds	2 trips Type B

Component/		0,5	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						P0443		
						P0449		
						P0452		
						P0453		
						P0454		
Transmission Output Speed	P0502	No activity in the TOSS circuit	TOSS Raw Speed	<= 60 RPM	Maximum Engine Torque	<= 8191.9 N-m	>= 4.50 sec	Type E 2 trips
Sensor (TOSS)					Minimum Engine Torque	>= 68.0 N-m		
						<= 8191.9 N-m		
					in Park or Neutral			
					Minimum Engine Torque in Park or Neutral	>= 90.0 N-m		
					Minimum Throttle opening	>= 3.5 %		
					Minimum Engine Speed when there is a Brake DTC: P0572, P0573, P0703. **Cald Out by matched threshold with below. **	>= 1500 RPM		
					Minimum Engine Speed when there is no Brake DTC :P0572, P0573, P0703. **Cald Out by Maximum Engine Speed	>= 1500 RPM <= 6500 RPM		
					Minimum Transmission Fluid Temperature	>= -40.0 ° C.		
					Disable P0502 if PTO Active	Enabled		
					Engine Speed	<= 7500 RPM >= 200 RPM		
						for >= 5.0 sec		
					Vehicle Speed	<= 318 MPH		

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						for >= 5.0 sec		
					Ignition Voltage	<= 32.0 volts		
					Ignition Voltage	>= 11.0 volts		
					No Active DTCs:	EngineTorqureInaccurate		
						AcceleratorEffectivePstnValid		
						P0503 Active this Key On		
Transmission	P0503	TOSS Signal	Loop-to-Loop change	>= 350 RPM	Disable P0502 if PTO	Enabled	>= 3.25 sec	Type B
Output Speed		Intermittent	in TOSS		Active		0.20 000	2 trips
Sensor (TOSS)					Engine Speed	<= 7500 RPM		
					Engine opeca	>= 200 RPM		
						for >= 5.0 sec	}	
					Vahiala Craad			
					Vehicle Speed	<= 318 MPH		
						for >= 5.0 sec		
					Ignition Voltage	<= 32.0 volts		
					Ignition Voltage	>= 11.0 volts		
					Time since Selected Gear	>= 6 sec		
					Range Change			
					Time since 4WD Range	>= 6 sec		
					change			
					Loop-to-Loop Input	<= 500 RPM For >= 2 Sec.		
					Speed Change	000 TKI WI T 01		
					Raw Output Speed	> 300 RPM for >= 2 Sec.		
					Output Speed change	<= 150 RPM for >= 2 Sec.		
					Output Speed change	- 150 KFW 101 >= 2 Sec.		
					Disabled	ShiftSolenoidFaults (TCM)		
					For Following			
					DTCS:			
Low Engine	P0506	This DTC will	Filtered Engine Speed	< 91 00 rpm	Baro		Diagnostic runs in	2 trips
Speed Idle		determine if a low idle	Error	- 01.00 ipiii	Baro		Blagilloons rano in	Type B
System		exists				> 70 kPa		1 ypc B
Cyclom		CAISIS	filter coefficient	0.003	Coolant Temp	> 60 °C and < 123 °C	every 12.5 ms loop	n
			Inter coefficient	0.003	Ooolant Temp	00 0 and 125 0	[CVCIY 12.5 III5 100]	Ρ
					Engine run time		Diagnostic reports	;
						32 ≥ volts ≥ 11	pass or fail in	
					Time since gear change	≥ 3 sec	10 sec	
				Time	e since a TCC mode change		once all enable	
						> -20 °C	conditions are met	t
					Vehicle speed			
					Commanded RPM delta			

Component/	Fault		Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					For manual			
					transmissions:			
					Clutch Pedal TOT			
					Threshold			
						> 88.00 pct		
					Clutch Pedal BOT	ου.ου ρει		
						< 16.00 pct		
						PTO not active		
						Transfer Case not in 4WD		
						LowState		
						Off-vehicle device control		
						(service bay control) must not		
						be active.		
					No active DTCs	AmbientAirDefault		
						ECT_Sensor_FA		
						EGRValveCircuit_FA		
						EGRValvePerformance FA		
						IAT SensorCircuitFA		
						EvapFlowDuringNonPurge_FA	\	
						FuelTrimSystemB1_FA		
						FuelTrimSystemB2_FA		
					<u> </u>	FuelInjectorCircuit_FA		
						MAF SensorFA		
						EngineMisfireDetected_FA		
						IgnitionOutputDriver_FA		
						EnginePowerLimited		
						TPS FA		
						TPS_Performance_FA		
						VehicleSpeedSensor_FA		
						FuelLevelDataFault		-
						LowFuelConditionDiagnostic		
						Clutch Sensor FA		
					All of the above met			
					for Idle time			
High Engine	P0507		Filtered Engine Speed	> -182.00 rpm	Baro		Diagnostic runs in	
Speed Idle		determine if a high idle	Error					Type B
System		exists				> 70 kPa		
			filter coefficient	0.003	Coolant Temp	> 60 °C and < 123 °C	every 12.5 ms loo	p
					Engine run time	≥ 60 sec	Diagnostic reports	3

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Ignition voltage	32 ≥ volts ≥ 11	pass or fail in	
					Time since gear change		10 sec	
				7	Time since a TCC mode change	> 3 sec	once all enable	
					IAT	> -20 °C	conditions are me	et
					Vehicle speed	≤ 1.24 mph		
					Commanded RPM delta			
					For manual			
					transmissions:			
					Clutch Pedal TOT			
					Threshold			
					or	> 88.00 pct		
					Clutch Pedal BOT			
					Threshold	< 16.00 pct		
						PTO not active		1
						Transfer Case not in 4WD		
						LowState		
						Off-vehicle device control		
						(service bay control) must not		
						be active.		
					No active DTCs	AmbientAirDefault		
						ECT_Sensor_FA		
						EGRValveCircuit_FA		
						EGRValvePerformance_FA		
						IAT_SensorCircuitFA		
						EvapFlowDuringNonPurge_FA	\	
						FuelTrimSystemB1_FA		
						FuelTrimSystemB2_FA		
						FuelInjectorCircuit_FA		
						MAF_SensorFA		
						EngineMisfireDetected_FA		
						IgnitionOutputDriver_FA		
						EnginePowerLimited		
						TPS_FA		
						TPS_Performance_FA		
						VehicleSpeedSensor_FA		
						FuelLevelDataFault		
						LowFuelConditionDiagnostic		
I						Clutch Sensor FA		
I					All of the above met			
					for Idle time	> 10 sec		

		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Engine Oil Pressure (EOP) Sensor Performance	Pressure (EOP) Sensor (Determines if the Engine Oil Pressure (EOP) Sensor is stuck or biased in range	To fail a currently passing test: The filtered, weighted difference between measured EOP and predicted EOP (a function of engine speed and engine oil temp.):	< -50.0 kPa OR > 47.0 kPa	Filtered engine oil pressure test weighting (function of engine speed, engine oil temperature, predicted oil pressure,	Enabled Present >= 0.30 weighting	Performed every 100 msec	2 trip(s) Type B
			To pass a currently failing test: The filtered, weighted difference between measured EOP and predicted EOP (a function of engine speed and engine oil temp.):	> -47.0 kPa AND < 44.0 kPa	and engine load stability). Details on Supporting Tables Tab (P0521 Section)			
					No active DTC's	Fault bundles: CrankSensorFA ECT_Sensor_FA MAF_SensorFA IAT_SensorFA EOPCircuit_FA		
Engine Oil Pressure (EOP) Sensor Circuit Low Voltage	P0522	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too low	(Engine Oil Pressure Sensor Circuit Voltage) / 5 Volts	< 5 percent	Engine Running Ignition Voltage Sensor Present Diagnostic enabled/ disabled	= True <= 32.0 V and >= 11.0 V Yes Enabled	50 failures out of 63samples Performed every 100 msec	2 trip(s) Type B
Engine Oil Pressure (EOP) Sensor Circuit High Voltage	P0523	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too high	(Engine Oil Pressure Sensor Circuit Voltage) / 5 Volts	> 85 percent	Engine Running Ignition Voltage Sensor Present Diagnostic enabled/ disabled	= True <= 32.0 V and >= 11.0 V Yes Enabled	220 failures out of 255 samples Performed every 100 msec	2 trip(s) Type B

•		Monitor Strategy	Malfunction	Threshold	Secondary		Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Brake Booster Pressure Sensor Performance	P0556	Determines if the Brake Booster Vacuum Sensor is stuck or	Engine vs brake booster vacuum sensor values are		Throttle Area (with idle included) for time period of	<= 1 Percent for > 3 seconds		
		skewed within the normal operating range by comparing	compared when % throttle < value for a time period. When		Ignition Voltage	<= 32.0 V and >= 11.0 V	Pass counter incremented when enable	2 trip(s)
		the engine vacuum to the brake booster	throttle once again > calibrated value, min		BrkBoostVacDiff For time period of	>= 0.2 Seconds	conditions are met, pass	Type B
		vacuum when the engine is producing a large amount of	and max vacuum sensor values are normalized and		AND	>= 6.0 kPa	achieved when counter >= 8	,
		vacuum	subtracted from a 1st order lag filter value of 1. A properly operating vacuum sensor would have a normalized result of 1 or greater. If the normalized result is greater than 1 it is considered 1. The 1st order lag filter value would be 0 in a passing system.		Diagnostic enabled/ disabled No active DTC's	Enabled Fault bundles: MAP_SensorFA TPS_FA	Performed every 100 msec	
			1 st order lag fail threshold 1 st order lag re-pass threshold	> 0.5 < 0.6				
Brake Booster Pressure Sensor Circuit Low Voltage		Determines if the Brake Booster Pressure Sensor circuit voltage is too	(Brake Booster Pressure Sensor Voltage) / 5 Volts	< 2.0 percent	Brake booster diagnostic enabled/ disabled		320 failures out of 400samples	2 trip(s) Type B
· shage		low			Brake booster pressure sensor present		Performed every 12.5 msec	
						Yes		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
Brake Booster Pressure Sensor Circuit High Voltage	P0558	Determines if the Brake Booster Pressure Sensor circuit voltage is too high	(Brake Booster Pressure Sensor Voltage) / 5 Volts	> 87.0 percent	Brake booster diagnostic enabled/ disabled Brake booster pressure sensor present	Enabled	2000 failures out of 2400 samples Performed every 12.5 msec	2 trip(s) Type B
Cruise Control Mutil-Functon Switch Circuit	P0564	Detect when cruise control multi-function switch circuit (analog) voltage is in an illegal range	Cruise Control analog circuit voltage must be in an "illegal range" for greater than a calibratable period of time for cruise switch states that are received over serial data		CAN cruise switch diagnostic enable in ECM	TRUE -1	fail continuously for greater than 0.500 seconds	Type: C MIL: NO Trips: 1
Cruise Control Resume Circuit	P0567	Detects a failure of the cruise resume switch in a continously applied state	Cruise Control Resume switch remains applied for greater than a calibratable period of time for architecture where cruise switch states are received over serial data		CAN cruise switch diagnostic enable in ECM	TRUE -1	fail continuously for greater than 90.000 seconds	C MIL: NO Trips:

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
Cruise Control Set Circuit			Cruise Control Set switch remains applied for greater than a calibratable period of time for architecture where cruise switch states are received over serial data		CAN cruise switch diagnostic enable in ECM	TRUE -1	fail continuously for greater than 90.000 seconds	Type: C MIL:
								NO
							fail continuously for greater than 90.000 seconds	Trips:
	D0575		16 6 11:			TDUE 4	140 / 40	1
Cruise Control Input Circuit	P0575	Detects rolling count or protection value errors in Cruise Control Switch Status serial data signal	protection value faults occur, disable cruise for duration of fault		Cruise Control Switch Serial Data Error Diagnostic Enable	TRUE -1	10 / 16 counts	Type:
								MIL: NO Trips:
Brake Pedal Position Sensor Circuit Low	P057C	Detects low circuit failure when brake pedal position is below calibratable value	If x of y faults occur, default brake pedal position to zero for duration of fault	0.25	Brake Pedal Position Diagnostic Enable	TRUE -1	20 / 32 counts	1 Type:
								B MIL: YES Trips: 2

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Brake Pedal Position Sensor Circuit High	P057D	failure when brake pedal position is above	If x of y faults occur, default brake pedal position to zero for duration of fault	4.75	Brake Pedal Position Diagnostic Enable	TRUE -1	20 / 32 counts	Type: B MIL: YES
								Trips:
Control Module Read Only Memory (ROM)	P0601	This DTC will be stored if the calibration check sum is incorrect	Output state invalid		PCM State	= crank or run	Diagnostic runs continuously in the background Diagnostic	Type A 1 trips
							reports a fault if 1 failure occurs on the first pass.	
							Diagnostic reports a fault if 5 failures occur after the first pass is complete.	
Control Module Not Programmed	P0602	This DTC will be stored if the PCM is a service PCM that has not been programmed.	Output state invalid		PCM State	= crank or run PCM is identified through calibration as a Service PCM	Diagnostic runs at powerup	Type A 1 trips
Control Module Long Term Memory Reset	P0603	Non-volatile memory checksum error at controller power-up	Checksum at power- up does not match checksum at power- down				Diagnostic runs at powerup Diagnostic reports a fault if 1 failure occurs	Type A 1 trips

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System		Description	Criteria	Value	Parameters	Conditions	Required	illum.
ECM RAM Failure	P0604	Indicates that the ECM is unable to correctly read data from or write data to RAM	data pattern written	1 count if found on first memory scan. 5 counts if found on subsequent scans.			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously	Trips: 1 Type: A MIL: YES
			Secondary processor battery backed RAM failed checksum twice for original values at power up and the defaulted values				Completion at intilization, <500 ms	
			Secondary processor copy of calibration area to RAM failed for a count >	2 counts			Completion at intilization, <500 ms	
			Secondary Processor data pattern written doesn't match the pattern read consecutive times				Will finish within 30 seconds at all engine conditions.	
			Secondary Processor TPS or APPS minimum learned values fail compliment check continuously				0.0625 sec continuous	
ECM Processor	P0606	Indicates that the ECM has detected an internal processor integrity fault	When drag is active Secondary processor detects Primary's calculated throttle position is greater > than Secondary Processor calculated Throttle Position by	46.98 %.		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.1875 sec in the secondary processor	Trips: 1 Type: A MIL: YES

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum
			Secondary processor detects Primary's calculated throttle position is greater > than Secondary's calculated Throttle Position when driver is commanding the throttle from APP by	5.82 %.		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions		
			Secondary processor detects Primary's calculated throttle position is greater > than Secondary's calculated Throttle Position when reduce engine power is active by	39.26 %.		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions		
			Software tasks on the Primary Processor in the 12.5 ms loop were not executed or were not executed in the correct order.	continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.0625 sec continuous	
			Software tasks on the Primary Processor in the 25 ms loop were not executed or were not executed in the correct order.	0.1250 sec continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.1250 sec continuous	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Software tasks on the Primary Processor in the 50 ms loop were not executed or were not executed in the correct order.	0.5000 sec continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.5000 sec continuous	
			Software tasks on the Primary Processor in the 100 ms loop were not executed or were not executed in the correct order.	1.0000 sec continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	1.0000 sec continuous	
			Software tasks on the Primary Processor in the 250 ms loop were not executed or were not executed in the correct order.	2.5000 sec continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	2.5000 sec continuous	
			The first completion of the RAM diagnostic on the Primary Processor was completed > the amount of time	360.0000 sec continuous		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	360.0000 sec continuous	
			The first completion of the ROM diagnostic on the Primary Processor was completed > the amount of time			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	360.0000 sec continuous	

omponent/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum
			Software tasks on the	Two Consecutive		Run/crank voltage or	25 ms	
			Secondary Processor	Loops (12.5ms * 2)		Powertrain relay voltage >		
			were not executed or	25ms		6.00 and reduced power is		
			were not executed in			false, else the failure will be		
			the correct order.			reported for all conditions		
			Loss or invalid			Run/crank voltage or	In the primary	1
			message of SPI			Powertrain relay voltage >	processor, 159 /	
			communication from			6.00 and reduced power is	400 counts	
			the Secondary			false, else the failure will be	intermittent or 15	
			Processor at			reported for all conditions	counts	
			initialization detected			reported for all cortainors	continuous; 39	
			by the Primary				counts	
							continuous @	
			Processor or loss or				initialization	
			invalid message of				Imilianzation	
			SPI communication					
			from the Secondary					
			Processor after a					
			valid message was					
			recieved by the					
			Primary Processor					
			Loss or invalid			Run/crank voltage or	In the secondary	1
			message of SPI			Powertrain relay voltage >	processor 0.4750	
			communication from			6.00 and reduced power is	sec at	
			the Primary Processor			false, else the failure will be	initialization,	
			at initialization			reported for all conditions	0.1750 sec	
			detected by the				continuous or 20 /	,
			Secondary Processor				200 intermittent.	
			or loss or invalid				200 intermittent.	
			message of SPI communication from					
			the Primary Processor					
			after a valid message					
			was recieved by the					
		1	Secondary Processor					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum
			Primary processor check of the secondary processor by verifing the hardware line toggle between the two processors toggles within the threshold values	9.3750 ms and 15.6250 ms		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	9 counts continuous at initialization or 9 counts continuous; 12.5 ms /count in the primary processor	
			Primary Processor TPS or APP minimum learned values fail compliment check			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.1000 sec continuous	
			The ocillator failed for the Primary processor where the clock is outside the threshold			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	100 ms continuous	-
			The secondary check of the ALU failed to compute the expected result			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5 ms continuous	
			Secondary processor failed configuration check of the registers.			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5 ms continuous	
			Secondary processor checks stack beginning and end point for pattern written at initialization.			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5ms continuous	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Secondary processor check that the Primary processor hasen't set a select combination of internal processor faults			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5ms continuous	
			The primary processor check of the ALU failed to compute the expected result	Two Consecutive Times		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5ms continuous	
			Primary processor failed configuration check of the registers.			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	12.5ms continuous	
Main & MHC state of health fault	P0607		Primary state of health (SOH) discrete line is not toggling between the two processors for a time >	0.4875 sec		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	0.4875 sec continuous	Trips: 1 Type: C MIL: NO
Vehicle Speed Output Circuit 2 (128kPPM)	P0609	Determines if the Vehicle Speed Output Circuit 2 (128kPPM) is faulted	commanded and actual states of the output driver do not match because the output has either an open circuit, short to ground, or short to	100 failures out of 120 samples	Vehicle speed output (128kPPM) circuit diagnostic enabled	<= 32.0 V and >= 11.0 V	100 failures out of 120 samples	2 Trip(s) Type B
Control Module Accelerator Pedal Position (APP) System Performance		Verify that the indicated accelerator pedal position calculation is correct	PPS sensor switch fault - When the APP sensor 2 is shorted to ground, the sensor value is >	41	range	Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	250 msec Consecutive checks within 200ms or 2 / 2 counts; 175 ms/count	Trips: 1 Type: A MIL: YES

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						Engine Running TPS minimum learn is not active No Pedal related errors or diagnostic faults. Diagnostic is enabled (Only applicable for Legacy		
			Difference between primary processor indicated accelerator pedal position and secondary indicated accelerator pedal position is >	5		accelerator pedals) Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	44 / 40 counts or 39 counts continuous; 12.5 ms/count in the secondary processor	
						Primary processor Pedal Sync Error is FALSE		
Control Module EEPROM Error	P062F	Indicates that the NVM Error flag has not been cleared			Ignition State	= unlock/accesory, run, or crank	1 test failure Diagnostic runs once at powerup	Type A 1 trips
5 Volt Reference #1 Circuit	P0641	Detects a continuous or intermittent short on th 5 volt reference circuit #1	or Primary Processor Vref1 > or the difference between Primary filtered Vref1 and	4.875 5.125 0.049		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be	19 / 39 counts or 0.1875 continuous; 12.5 ms/count in primary processor	Trips: 1 Type: A MIL: YES
			or Secondary	4.875 5.125		reported for all conditions	19 / 39 counts or 15 counts continuous; 12.5 ms/count in secondary processor	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM)	P0650	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the		Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	20 failures out of 25 samples	2 trip Type B
			control circuit do not match.		Remote Vehicle Start is not active		250 ms / sample	NO MIL
							Continuous	
5 Volt Reference #2 Circuit	P0651	Detects a continuous or intermittent short on the 5 volt reference	Primary Processor Vref2 < or Primary Processor	4.875			19 / 39 counts or 0.1875 sec continuous; 12.5	Trips: 1 Type:
		circuit #2		5.125			ms/count in primary processor	A MIL: YES
			Primary Vref2 >	0.049		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be		
			or Secondary	4.875		reported for all conditions	19 / 39 counts or 15 counts continuous; 12.5	
			Processor Vref2 >	5.125			ms/count in secondary processor	
Powertrain Relay Control (ODM)	P0685	This DTC checks the circuit for electrical integrity during operation.	The ECM detects that the commanded state of the driver and the actual state of the		Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	8 failures out of 10 samples	2 trips Type B
		operation.	control circuit do not match.				250 ms / sample	
							Continuous	
Powertrain Relay	P0690	This DTC is a check to	PT Relay feedback		Powertrain relay		<u>. </u>	2 trips
Feedback Circuit High		determine if the Powertrain relay is functioning properly.	voltage is	≥ 18 volts	commanded "ON"		samples	Type B
			Stuck Test:		No active DTCs:	PowertrainRelayStateOn_FA	1 second / sample	
			PT Relay feedback voltage is	> 2.5 volts			Stuck Test: 100 ms/ sample	

•	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			when commanded					
ı			'OFF'					
							Continous	
							failures ≥ 4	
							seconds	
Fuel Pump Control Module	P069E	Monitors the FPCM	Fuel Pump Control			Time since power-up > 3	Continuous	1 trips
(FPCM)		MIL request line to determine when the	Module Emissions- Related DTC set			seconds		Type A (No MIL)
Requested MIL		FPCM has detected a	Theiated DTC Set					(IVO IVIIL
Illumination		MIL illuminating fault.						
Transmission	P0700	Monitors the TCM MIL	Transmission Control			Time since power-up > 3	Continuous	1 trips
Control Module		request line to	Module Emissions-			seconds		Type A
(TCM) Requested		determine when the	Related DTC set					(No MIL)
MIL Illumination		TCM has detected a						
		MIL illuminating fault.						
Clutch Pedal	P0806	Detects if Clutch Pedal	Filtored Clutch Bodel		N/V Ratio	Must match actual gear (i.e.	<u> </u>	
Position Sensor	F0000	Position Sensor is	Position Error	> 1 %	IN/V Ralio	vehicle in gear)	25 ms loop	1 Trip(s)
Circuit Range /	ange / Stuck in a range when the vel	when the vehicle is	1 70	Transfer Case	Not in 4WD Low range	Continuous	1 111p(3)	
Performance		indicative of a vehicle	determined to be in		vehicle speed	> 0.0 MPH		Type A
		NOT in gear, when the	gear		Engine Torque	> EngTorqueThreshold	7	7,70
		vehicle is determined				Table		
		to be in gear. Gear			Clutch Pedal Position			
		determination is made				< ResidualErrEnableLow		
		by verifying that engine RPM/ Vehicle Speed				Table	_	
		(N/V) ratio represents				OR	4	
		a valid gear.			Clutch Pedal Position			
						> ResidualErrEnableHigh		
					No A	Table ctive DTCs:	-	
						onSensorCktLo FA	┥	
						onSensorCktHi FA		
						nkSensorFA		
						peedSensor_FA		
<u> </u>						. <u>=</u>		
	P0807	Detects Continuous	Clutch Position		Engine Not Cranking		25 ms loop	
Position Sensor Circuit Low		Circuit Short to Low or	Sensor Circuit	< 4 % of Vref	System Voltage	> 9.0 Volts	Continuous	1 Trip(s)
Circuit LOW		Open	for	200 counts out of 250 samples				Type A
				250 Samples				Type A

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Clutch Pedal Position Sensor Circuit High	P0808	Detects Continuous Circuit Short to High	Clutch Position Sensor Circuit for	> 96 % of Vref 200 counts out of 250 samples	Engine Not Cranking System Voltage	> 9.0 Volts	25 ms loop Continuous	1 Trip(s) Type A
Clutch Pedal Position Not Learned	P080A	Monitor for Valid Clutch Pedal Fully Applied Learn Position values	Fully Applied Learn Position O Fully Applied Learn Position	< 9.0 % R > 36.0 %	OBD Manufacturer Enable Counter	= 0	250 ms loop Continuous	1 Trip(s) Type A
Skip Shift Solenoid Control Circuit Low (Manual Transmission Only)	P080C	This DTC checks for an open and shorted low circuit while the device is commanded off.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Engine Speed	11 volts ≤ Voltage ≤ 32 volts > 250 RPM	5 failures out of 6 samples 250 ms / sample Continuous with device off	2 trips Type B
Skip Shift Solenoid Control Circuit High (Manual Transmission Only)	P080D	This DTC checks for a shorted high circuit while the device is commanded on.	The ECM detects that the commanded state of the driver and the actual state of the control circuit do not match.		Run/Crank Voltage Engine Speed	11 volts ≤ Voltage ≤ 32 volts > 250 RPM	5 failures out of 6 samples 250 ms / sample Continuous with device on	2 trips Type B
Traction Control Torque Request Circuit	P0856	Determines if torque request from the EBTCM is valid	With GMLAN: Serial Communication 2's complement message - (\$140 for PPEI2 or \$1C7/\$1C9 for PPEI3 engine torque or \$1CA/\$1C6 for axle torque)	Message <> 2's complement of message	With GMLAN: Serial communication to EBTCM (U0108) Power Mode Engine Running	No loss of communication = Run = True	With GMLAN: Count of 2's complement values not equal >= 10 Performed every 25 msec.	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Serial Communication message (\$140 for PPEI2 or \$1C7/\$1C9 for PPEI3 engine torque or \$1CA/\$1C6 for axle torque) rolling count value	Message rolling count value <> previous message rolling count value	Status of traction in GMLAN message (\$380 for PPEI2 or \$4E9 for PPEI3)	= Traction Present	OR 6 rolling count failures out of 10 samples Performed every 25 msec.	1 trip(s)
				R Requested torque intervention type toggles from not increasing request to increasing request			>= 3 multi- transitions out of 5 samples. Performed every 200 msec.	Special Type C
			Torque request greater than allowed	> 650 Nm for engine based traction torque system			>= 10 out of 10 samples above 650 Nm Performed every 25 msec.	
			With PWM: PWM Duty cycle OR PWM Duty cycle	< 4 Pct > 96 Pct	With PWM: Traction Status for PWM (\$2B3C Class2 message) Engine Run Time	= Traction Present > 2 Seconds	With PWM: 3 failures out of 30 samples Performed every 50 msec	

System Code Description Criteria Value Parameters Conditions Required Illum. P1101 Parelimines if there are Filtered Throttle Multiple air induction problems affecting airflow and/or manifold pressure. P1101 Performance (naturally aspirated applications) AND ABS(Measured Flow - MAP Model 1) Filtered OR AND ABS(Measured MAP - MAP Model 2) Filtered SABS(Measured MAP - MAP Model 3) Modeled Air Flow multiplied by MAP Residual Weight Factor based on RPM MAP Model 1 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA	Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System performance (naturally applications) Performance (naturally applications) Model Error (ABS(Measured Flow AND Filtered OR ABS(Measured Flow ABS(Measured MAP ABS(Measured MAP AMP Model 1) Filtered AND ABS(Measured MAP AMP Model 2) Filtered AND Active DTCs: MAP_SensorCircuitFA	-	Code		Criteria	Value	Parameters	Conditions	Required	illum.
System Performance (naturally aspirated applications) Performance (naturally aspirated applications) Modeled Firor (AMD) AND AND ABS(Measured Flow - Map Model 1) Filtered AND ABS(Measured MAP - MAP Model 1) Filtered AND ABS(Measured MAP - MAP Model 2) Filtered AND AND ABS(Measured MAP - MAP Model 2) Filtered AND AND ABS(Measured MAP - MAP Model 2) Filtered AND AND ABS(Measured MAP - MAP Model 2) Filtered AND AND AND ABS(Measured MAP - MAP Model 2) Filtered AND AND ABS(Measured MAP - MAP Model 2) Filtered AND AND AND AND AND AND AND AN	Inlet Airflow	P1101	Determines if there are	Filtered Throttle		Engine Speed	>= 450 RPM	Continuous	Type B
airflow and/or manifold pressure. ABS(Measured Flow - Modeled Air Flow) Filtered AND	System		multiple air induction	Model Error	<= 250 kPa*(g/s)		<= 6700 RPM		2 trips
aspirated applications) ABS(Measured Flow - Modeled Air Flow) Filtered	Performance					Coolant Temp	> -7 Deg C		
applications) (ABS(Measured Flow – Modeled Air Flow) Filtered OR ABS(Measured MAP – MAP Model 1) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa) AND ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa) AND ABS(Measured MAP – MAP Model 2) Filtered AND ABS(Measured MAP – MAP Model 2) Filtered Throttle Model MAF Residual Weight Factor based on RPM MAP Model Air Flow multiplied by MAF Residual Weight Factor based on RPM MAP Model 1 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA			airflow and/or manifold	AND		Coolant Temp	< 125 Deg C		
- Modeled Air Flow) Filtered OR ABS(Measured MAP - MAP Model 1) Filtered AND ABS(Measured MAP - MAP Model 2) Filtered > 15.0 kPa > 15.0 kPa Minimum total weight factor (all factors multiplied together) >= 0.00 Filtered Throttle Model multiplied by TPS Residual Weight Factor based on RPM Modeled Air Flow multiplied by MAF Residual Weight Factor Based on RPM and MAF Residual Weight Factor Based on MAF Residual Weight Factor Based on RPM MAP Model 1 multiplied by MAP Residual Weight Factor Based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA			pressure.			Intake Air Temp	> -20 Deg C	12.5 msec	
Filtered OR ABS(Measured MAP - MAP Model 1) Filtered AND ABS(Measured MAP - MAP Model 2) Filtered AND ABS(Measured MAP - MAP Model 2) Filtered > 15.0 kPa > 15.0 kPa Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM Modeled Air Flow multiplied by MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP Residual Weight Factor Based on RPM MAP Model 1 multiplied by MAP Residual Weight Factor based on RPM MAP Model 1 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA	applications)					Intake Air Temp	< 125 Deg C		
OR ABS(Measured MAP - MAP Model 1) Filtered AND ABS(Measured MAP - MAP Model 2) Filtered > 15.0 kPa Titlered > 15.0 kPa ABS(Measured MAP - MAP Model 2) Filtered > 15.0 kPa Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM MAP Residual Weight Factor Based on MAF Residual Weight Factor Based on MAF Residual Weight Factor Based on RPM and MAF Residual Weight Factor Based on RPM MAP Model 1 multiplied by MAP It Residual Weight Factor Based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM See table "IFRD Residual Weight Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA									
ABS(Measured MAP – MAP Model 1) Filtered > 15.0 kPa) AND ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa Model 2) Filtered > 15.0 kPa Modeled Air Flow multiplied by TPS Residual Weight Factor based on RPM Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP It Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP Residual Weight Factor based on RPM See table "IFRD Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA					> 12 grams/sec				
- MAP Model 1) Filtered						multiplied together)			
Filtered > 15.0 kPa) AND ABS(Measured MAP - MAP Model 2) Filtered > 15.0 kPa > 15.0 kPa Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM									
Filtered Throttle Model multiplied by TPS Residual Weight Factor based on RPM ABS(Measured MAP – MAP Model 2) Filtered				· · · · · · · · · · · · · · · · · · ·			>= 0.00		
AND ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA				Filtered	> 15.0 kPa)				
ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa Weight Factor based on RPM Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
ABS(Measured MAP – MAP Model 2) Filtered > 15.0 kPa				AND					
- MAP Model 2) Filtered > 15.0 kPa							Weight Factor based on RPM		
Filtered > 15.0 kPa Modeled Air Flow multiplied by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA				`					
by MAF Residual Weight Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA				, , , , , , , , , , , , , , , , , , ,					
Factor based on RPM and MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weight Factors". No Active DTCs: MAP_SensorCircuitFA				Filtered	> 15.0 kPa				
MAF Residual Weight Factor Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
Based on MAF Estimate MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP Model 1 multiplied by MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							Based off WAF Estimate		
MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP1 Residual Weight Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							MAD Madal 4 secultivalised by		
Factor based on RPM MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							Factor based on Krivi		
MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
MAP2 Residual Weight Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							MAD Model 2 multiplied by		
Factor based on RPM See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
See table "IFRD Residual Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							Tactor based on the twi		
Weighting Factors". No Active DTCs: MAP_SensorCircuitFA									
Weighting Factors". No Active DTCs: MAP_SensorCircuitFA							See table "IFRD Residual		
No Active DTCs: MAP_SensorCircuitFA									
							Trongitting Factors .		
						No Active DTCs:	MAP SensorCircuitFA		
I I I I I I I I I I I I I I I I I I I						140 / 1001/0 101 103.	EGRValve_FP		
EGRValvePerformance_FA									
MAF_SensorCircuitFA									
CrankSensorFA									

Inlet Airflow System Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharged) Performance (supercharger Intake Plow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. Performance (supercharger Intake Plow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Pergine Speed Engine Speed Coolant Temp Coolant Temp (125 De Minimum total weight factor (all factors multiplied together) >= 0.00 Filtered Throttle	nsor_FA ensor_FP nsorFA nsorCircuitFP eSystemTFTKO RPM Continuous RPM G C eg C eg C 12.5 msec	Type E 2 trips
Inlet Airflow System Performance (supercharged) Pittered Throtttle Pagine Speed Engine Speed Coolant Temp Coolant Temp Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) Engine Speed Engine Speed Coolant Temp Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) Filtered Throttle	ensor_FP nsorFA nsorCircuitFP eSystemTFTKO RPM Continuous RPM G C eg C eg C performed every 12.5 msec	2 trips
IAT_Ser IAT_Ser IAT_Ser CylDeac Inlet Airflow System Performance (supercharged) Part Determines if there are multiple air induction problems affecting airflow and/or manifold pressure. See table "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Engine Speed Engine Speed Coolant Temp Coolant Temp Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) >= 0.00 Filtered Throttle	nsorFA nsorCircuitFP cSystemTFTKO RPM Continuous RPM g C eg C eg C performed every 12.5 msec	2 trips
Inlet Airflow System Performance (supercharged) Partial Determines if there are multiple air induction problems affecting airflow and/or manifold pressure. See table "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Engine Speed Engine Speed See table Engine Speed Coolant Temp Coolant Temp Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) Filtered Throttle	nsorCircuitFP cSystemTFTKO RPM Continuous RPM g C eg C eg C 12.5 msec	2 trips
CylDeac CylD	SSystemTFTKO RPM Continuous RPM Calculation are peg C peg C 12.5 msec	2 trips
Determines if there are multiple air induction problems affecting airflow and/or manifold pressure.	RPM Continuous RPM G C Calculation are performed every eg C 12.5 msec	2 trips
multiple air induction problems affecting airflow and/or manifold pressure. "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when "Supercharger Intake Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Engine Speed Coolant Temp Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) >= 0.00	RPM G C eg C eg C performed every 12.5 msec	2 trips
Performance (supercharged) problems affecting airflow and/or manifold pressure. Flow Rationality Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Flow Rationality Diagnostic Failure Coolant Temp (Coolant Temp) Intake Air Tem	g C Calculation are performed every eg C 12.5 msec	
Asupercharged) airflow and/or manifold pressure. Diagnostic Failure Matrix" for combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Coolant Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Intake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Minimum total weight factor (all factors multiplied together) > -20 De Note Temp Minimum total weight factor (all factors multiplied together)	eg C performed every 12.5 msec	
pressure. Matrix" for combinations of model failures that can set this DTC. TPS model fails when Matrix" for combinations of littake Air Temp > -20 De leading to the littake Air Temp Minimum total weight factor (all factors multiplied together) > -20 De leading to the littake Air Temp Air Temp Minimum total weight factor (all factors multiplied together) > -20 De leading to the littake Air Temp Air T	eg C 12.5 msec	
combinations of model failures that can set this DTC. TPS model fails when Filtered Throttle Intake Air Temp Minimum total weight factor (all factors multiplied together) >= 0.00	e e e e e e e e e e e e e e e e e e e	
model failures that can set this DTC. Minimum total weight factor (all factors multiplied together) TPS model fails when Filtered Throttle Filtered Throttle	eg C	
can set this DTC. factor (all factors multiplied together) TPS model fails when Filtered Throttle Filtered		
TPS model fails when Filtered Throttle Filtered		
TPS model fails when >= 0.00 Filtered Throttle		
Filtered Throttle Filtered		
Filtered Throttle Filtered	DDM	
	IXI IVI	
	Throttle Model	
TOURD TOUR TOUR TO ALLO KPA^(A/C) TO TAULITINIA	d by TPS Residual	
	Factor based on RPM	
The state of the s	actor bacca on the twi	
MAF model fails when		
· · · · · · · · · · · · · · · · · · ·	d Air Flow multiplied	
	Residual Weight	
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	ased on RPM and	
	sidual Weight Factor	
THE WATER CONTRACTOR OF THE PROPERTY OF THE PR	n MAF Estimate	
when when		
ABS(Measured MAP		
	odel 1 multiplied by	
	Residual Weight	
	ased on RPM and	
when Boost Re	esidual Weight Factor	
ABS(Measured MAP	n % of Boost	
– MAP Model 2)		
	odel 2 multiplied by	
MAR2 R	Residual Weight	
SCIAFT I llouder rails Factor b	ased on RPM and	
wnen Boost Po	esidual Weight Factor	
AB5(Measured hased or	n % of Boost	
SCIAP – SCIAP		
Model 1) Filtered > 14.0 kPa	ı	1

Component/		•	Malfunction	Threshold	Secondary		Time	MIL
System			Criteria	Value	Parameters	Conditions	Required	illum.
			SCIAP2 model fails when ABS(Measured SCIAP – SCIAP Model 2) Filtered	> 14.0 kPa		SCIAP Model 1 multiplied by SCIAP1 Residual Weight Factor based on RPM and Boost Residual Weight Factor based on % of Boost		
						SCIAP Model 2 multiplied by SCIAP2 Residual Weight Factor based on RPM and Boost Residual Weight Factor based on % of Boost		
						See table "IFRD Residual Weighting Factors".		
					No Active DTCs:	MAP_SensorCircuitFA EGRValve_FP EGRValvePerformance_FA MAF_SensorCircuitFA CrankSensorFA ECT_sensor_FA ECT_Sensor_FP IAT_SensorFA IAT_SensorCircuitFP CylDeacSystemTFTKO IAT2_SensorFA IAT2_SensorCircuitFP SCIAP_SensorCircuitFA SCIAP_SensorCircuitFP AmbientAirDefault_SC		
O2S Insufficient Switching Bank 1 Sensor 1	P1133	longer sufficiently switching.	present if Half Cycle L/R or R/L Switches are below the threshold. OR If Slope Time L/R or R/L Switches are	H/C L/R switches < Threshold, or H/C R/L switches < Threshold, (refer to table named "P1133 - O2S HC L to R Switches Limit Bank 1 Sensor 1" Pass/Fail Threshold table & "P1133 - O2S HC R to L Switches		ed MAP_SensorFA IAT_SensorFA	Sample time is 60 seconds Frequency: Once per trip	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				Limit Bank 1 Sensor		EvapFlowDuringNonPurge_F		
				1" Pass/Fail		Α		
				Threshold table in				
				Supporting tables		EvapVentSolenoidCircuit FA		
				tab)		EvapSmallLeak_FA		
				,		EvapEmissionSystem_FA		
				OR		FuelTankPressureSnsrCkt_F		
						A		
				S/T L/R switches < 3,		FuelInjectorCircuit_FA		
				or S/T R/L switches		AIR System FA		
				< 3		EthanolCompositionSensor_F		
						EngineMisfireDetected_FA		
					Bank 1 Sensor 1 DTC's	_		
						= P0131, P0132 or P0134		
					not active	10.0 volts < system voltage<		
					System Voltage			
					EGR Device Control			
					Idle Device Control			
					Fuel Device Control			
					AIR Device Control	= Not active		
					Low Fuel Condition Diag	= False		
					Green O2S Condition	= Not Valid, See definition of		
						Green Sensor Delay Criteria		
						(B1S1) in Supporting Tables		
						tab.		
					O2 Heater on for	>= 40 seconds		
					Learned Htr resistance	= Valid		
					Engine Coolant			
						> -40 °C		
					Engine Run Time			
					Time since any AFM			
						> 0.0 seconds		
					Time since Purge On to			
						> 0.0 seconds		
					Time since Purge Off to			
						> 0.0 seconds		
						>= 0 % duty cycle		
					i dige daty cycle	15 gps <= engine airflow <=		
					Engine airflow			
	1	1	1	I	I Engine speed	1000 <= RPM <= 3000	I	ı

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						< 87 % Ethanol > 70 kpa >= 5 %		
					Fuel Control State Fuel State Commanded Proportional Gain All of the	= Closed Loop = TRUE = Enabled		
O2S Insufficient Switching Bank 2 Sensor 1	P1153	This DTC determines if the O2 sensor is no longer sufficiently switching.	Fault condition present if Half Cycle L/R or R/L Switches are below the threshold. OR If Slope Time L/R or R/L Switches are below the threshold.	H/C L/R switches < Threshold, or H/C R/L switches < Threshold, (refer to table named "P1153 - O2S HC L to R Switches Limit Bank 2 Sensor 1" Pass/Fail Threshold table & "P1153 - O2S HC R to L Switches Limit Bank 2 Sensor 1" Pass/Fail Threshold table in Supporting tables tab) OR S/T L/R switches < 3, or S/T R/L switches < 3		TPS_ThrottleAuthorityDefault ed MAP_SensorFA IAT_SensorFA ECT_Sensor_FA AmbientAirDefault MAF_SensorFA EvapPurgeSolenoidCircuit_F A EvapFlowDuringNonPurge_F A EvapSmallLeak_FA EvapEmissionSystem_FA FuelTankPressureSnsrCkt_F A FuelInjectorCircuit_FA AIR System FA EthanolCompositionSensor_F A EngineMisfireDetected_FA	Sample time is 60 seconds Frequency: Once per trip	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Bank 2 Sensor 1 DTC's	6		
					not active	= P0151, P0152 or P0154		
						10.0 volts < system voltage<		
					System Voltage	32.0 volts		
					EGR Device Contro	= Not active		
					Idle Device Contro	l = Not active		
					Fuel Device Contro	l = Not active		
					AIR Device Contro	I = Not active		
					Low Fuel Condition Diag	ı = False		
						= Not Valid, See definition of		
						Green Sensor Delay Criteria		
	1					(B2S1) in Supporting Tables		
	1					tab.		
	1				O2 Heater on fo	r >= 40 seconds		
					Learned Htr resistance	e = Valid		
					Engine Coolan	t > 55 °C		
						「> -40 °C		
					Engine Run Time			
					Time since any AFM			
						> 0.0 seconds		
					Time since Purge On to			
						> 0.0 seconds		
					Time since Purge Off to			
						> 0.0 seconds		
						>= 0 % duty cycle		
						15 gps <= engine airflow <=		
					Engine airflow			
						1 1000 <= RPM <= 3000		
						I < 87 % Ethanol		
	1					> 70 kpa		
					Throttle Position			
					Low Fuel Condition Diag	I = False		
	1				Fuel Control State			
					Closed Loop Active			
	1				LTM fuel cel			
	1				Transient Fuel Mass			
	1					= Not Defaulted		
	1					not = Power Enrichment		
	1	1				DFCO not active		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
		·			Commanded Proportional Gair	>= 0.0 %		
					All of the	above met for		
					Time	> 3.0 seconds		
EngineMetal OvertempActive	P1258	The objective of the algorithm is to protect the engine in the event of engine metal overtemperature, mainly due to loss of coolant		≥ 132 °C ≥ 10 seconds	Engine Run Time If feature was active and it set the coolant sensor fault then feature will be enabled on coolant sensor fault pending on the next trip.	≥ 10 Seconds	Fault present for ≥ 0 seconds	1 trips Type A
ABS Rough Road malfunction	P1380	This diagnostic detects if the ABS controller is indicating a fault, and misfire is present. When this occurs, misfire will continue to run.	GMLan Message: "Wheel Sensor Rough Road Magnitude Validity"	= FALSE	Vehicle Speed Engine Speed Engine Load RunCrankActive Active DTC	VSS ≥ 5 mph rpm < 8192 load < 60 = TRUE P0300, MIL Request	40 failures out of 80 samples 250 ms /sample Continuous	1 Trips Type C "Special Type C"
ABS System Rough Road Detection Communication Fault	P1381	This diagnostic detects if the rough road information is no longer being received from the ABS controller, and misfire is present. When this occurs, misfire will continue to run.	Loss of GMLan Message: "Wheel Sensor Rough Road Magnitude"	= FALSE	Vehicle Speed Engine Speed Engine Load RunCrankActive Active DTC	VSS ≥ 5 mph rpm < 8192 load < 60 = TRUE P0300, MIL Request	40 failures out of 80 samples 250 ms /sample Continuous	1 Trips Type C "Special Type C"

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Cold Start Emissions Reduction System Fault	P1400	computes power from exhaust flow and thermal energy resulting from elevated idle speed and retarded spark advance. Detects if the cold start emission reduction system has failed resulting in the delivered power being out of range.	power - Average estimated accumulated exhaust power OR Average desired accumulated exhaust power - Average	< -32.00 KJ/s (high RPM failure mode) > 1.01 KJ/s (low RPM failure mode)	strategy is considered accommon of or Idle cat light off strategy is considered accommon of the cat light off strategy is considered. Spark and air per cylinder and engine run time) <= Idle CLO is considered exceeds a base RPM value. RPM offset. The amount catalyst light off is also a fund gear state. Refer to " Vehicle Speed OBD Manufacturer Enable Counter Throttle Position. A change in throttle position delay in the calculation of value. When the dela diagnostic will confuse. For Manual Transmission fully Clutch Peda. The clutch must Clutch Peda.	0	Runs once per trip when the cold start emission reduction strategy is active Frequency: 100ms Loop Test completes after 10 seconds of accumulated qualified data.	,
					Selle	. a. =.10010	J	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						TC's Not Set		
						AF_SensorFA		
						AP_SensorFA		
						SensorCircuitFA		
						SensorCircuitFA		
						T_Sensor_FA		
						SensorFaultActive		
					IAC_	SystemRPM_FA		
						TPS_FA		
						SpeedSensor_FA		
						/lisfireDetected_FA		
						nOutputDriver_FA		
						rProcessorPerf_FA		
						ReferenceA_FA		
						ReferenceB_FA		
						njectorCircuit_FA		
						ionEngagedState_FA		
						tch Sensor FA	_	
						oldStrt_IAC_SysPerf)		
						oldStrtlgnTmngPerf)		
Replicated Fransmission Dutput Speed	P150A	No activity in the RTOS Signal circuit	RTOS Sensor Raw Speed	<= 60 RPM	Transmission output Speed Angular Velocity	>= 1000 RPM	>= 4.50 Fail Time (Sec)	2 trips
RTOS) Sensor					Engine Speed	<= 7500 RPM		
					Engine Speed	>= 200 RPM		
					Vehicle Speed	for >= 5.0 sec <= 124 MPH	-	
					verlicie Speed	for >= 5.0 sec		
					Ignition Voltage	<= 32.0 volts		
					Ignition Voltage	>= 9.0 volts		
					Disabled For Following	VehicleSpeedSensor_FA P150B		
Replicated	P150B	RTOS Signal Circuit	RTOS Sensor Loop-to	o->= 350 RPM	DTCS: Raw Transmission Out	out > 300 RPM for >= 2 sec.	>= 3.25 Fail Time	Type F
ransmission Output Speed		Intermittent	Loop speed change	33374111	Speed	2 000.	(Sec)	2 trips
RTOS) Sensor					Output Speed change	<= 150 RPM for >= 2 sec.	↓	
					Engine Speed	<= 7500 RPM >= 200 RPM		

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
-						for >= 5.0 sec		
					Vehicle Speed	<= 124 MPH		
						for >= 5.0 sec		
					Ignition Voltage	<= 32.0 volts		
					Ignition Voltage	>= 9.0 volts		
					Disabled			
					For Following			
					DTCS:	VehicleSpeedSensor FA		
Transmission	P150C	Determines if engine	Serial Communication	± 1 from provious	Diagnostic enable bit	VerlicieSpeedSerisoi_FA	Diagnostic runs in	2 trine
Engine Speed	1500	speed request from the		\$19D message	Diagnostic enable bit		12.5 ms loop	Type B
Request Circuit		TCM is valid		(PTEI3)			'	''
,				,		1		
			Transmission engine	not equal to 2's	Engine run time			
			speed protection	complement of				
				transmission engine				
				speed request +				
				Transmission alive				
				rolling count				
						0.50 sec		
					# of Protect Errors	10 protect errors out of 10 samples		
					# of Alive Rolling Errors	6 rolling count errors out of 10 samples		
					No idle diagnostic 506/507 code	IAC_SystemRPM_FA		
					No Serial communication	(U0101)		
					loss to TCM			
					Engine Bunning	= TRUE		
					Engine Running Power mode	Run Crank Active		
Throttle Actuator	D1516	Detect a throttle	The throttle model		i owei illoue		0.1875 sec in the	Trips:
Control - Position		positioning error	and actual Throttle				secondary	111ps.
Performance		positioning entit	position differ by >	5.824 %.			processor	Type:
. Criominanoc			or	J.UZ4 /0.		false, else the failure will be	p. 0000001	Type: A
			The actual Throttle			reported for all conditions		MIL:
			position and throttle			- Sported for all containons		YES
			model differ by >		Engino Dunning or			153
			inoder direct by	5 924 %	Engine Running or Ignition Voltage >			
				5.824 %.	igililon vollage /			
						11		
	I	I	l		I	11	l	l

omponent/	Fault		Malfunction	Threshold	,	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					and Ignition Voltage >			
						5.4		
					and Throttle is being Controlled			
					Controlled			
			İ		and Communication Fault			
					(SPI is not set)			
					and TDO mainima and language			
					and TPS minimum learn is not active			
					is not delive			
					Ignition voltage failure is			
					false (P1682)			
		Detect throttle control	Thottle Position >	39.761 %.	(Throttle is being	Run/crank voltage or	0.1375 sec	_
		is driving the throttle in	Thouse Fosition >	39.701 /0.	Controlled and	Powertrain relay voltage >	continuous	
		the incorrect direction				6.00 and reduced power is		
					TPS minimum learn is	false, else the failure will be		
					active) or	reported for all conditions		
					Reduce Engine Power is			
					Active			
		Degraded Motor	Desired throttle			Run/crank voltage or	0.4875 sec	
			position is stable within 0.25 for 4.0000			Powertrain relay voltage > 6.00 and reduced power is	continuous on secondary	
			sec and the delta			false, else the failure will be	processor	
			between Indicated			reported for all conditions	ľ	
			throttle position and					
			desired throttle position in greater		Engine Running or			
			than 2.00 %		Ignition Voltage >			
						11		
					and Ignition Voltage >			
						5.4		
					and Throttle is being Controlled			
					Controlled			
					and Communication Fault			
					(SPI is not set)			

Component/	Fault		Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					and TPS minimum learn is not active Ignition voltage failure is false (P1682)			
Ignition Voltage Correlation	P1682	I and the second se	Run/Crank – PT Relay Ignition >	3.00 Volts	Powertrain commanded on and (Run/crank voltage > or PT Relay Ignition voltage > and Run/crank voltage >	Table, f(IAT). See supporting tables 5.5 5.5	14 / 14 counts or 0.1750 sec continuous; 12.5 msec/count in main processor	Trips 1 Type A MIL: YES
Fuel Level Sensor 2 Performance (For use on vehicles with electric transfer pump dual fuel tanks)	P2066	This DTC will detect a fuel sender stuck in range in the secondary fuel tank.	Fuel Level in Primary and Secondary Tanks Remains in an Unreadable Range too Long If fuel volume in primary tank is AND Fuel volume in secondary tank	>= 99.0 liters	Engine Running No active DTCs:	VehicleSpeedSensor_FA	250 ms / sample Continuous	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			and remains in this					
			condition for	200 miles				
			OR					
			During fuel tranfer		•			
			When the enable		Transfer Pump is			
			conditions are met,		commanded on			
			3.0 liters of fuel will be					
			transferred from the					
			secondary tank and		No device control for the			
			3.0 liters of fuel will be		transfer pump			
			transfered into the					
			primary tank within					
			180 seconds. There		Fuel Volume in			
			is a short delay of 20		Secondary Tank			
			seconds to allow fuel			< 43 liters		
			slosh to settle before					
			the fail timer begins.		Vehicle Speed	< 0 mph		
			If the secondary tank		Vollisio oposa	l s inpi.		
			volume does not					
			decrease by the cal					
			amount but the					
			primary volume does					
			increase by the cal					
			amount after the fail					
			timer has expired,					
			then P2066 sets.					
			0.0					
			OR					
			After a Refuel Event					
			If the primary fuel			T		
			volume changes by					
			45 liters from engine					
			"off" to engine "on" the					
			secondary volume					
			should change by 3					
			liters. Otherwise,					
			P2066 will set.					
			1. 2000 Will Oot.					
	1							

Component/	Fault	9,	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			OR Distance Traveled without a Secondary Fuel Level Change				-	
			If the vehicle is driven a distance of 100 miles without the secondary fuel level changing by 3 liters, then the sender must be stuck.		Volume in Secondary Tank and Volume in Secondary Tank	>= 3 liters < 43 liters		
			OR The secondary fuel sender is stuck in the deadband AND If the vehicle is driven a distance of 100 miles without the secondary fuel level changing by 3 liters, then the sender must be stuck.	> 43 liters.	Secondary Full Transfer Pump On Time	>= 600 seconds		
Fuel Level Sensor 2 Performance (For use on	P2066	This DTC will detect a fuel sender stuck in range in the secondary fuel tank.			Engine Running No active DTCs:	VehicleSpeedSensor_FA	250 ms / sample Continuous	2 trips Type B
vehicles with mechanical transfer pump dual fuel tanks)			Fuel Level in Secondary Tank Remains in an Unreadable Range too Long If fuel volume in primary tank is AND Fuel volume in	>= 28.5 liters				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			and remains in this					
			condition for	124 miles				
			OR					
			Fuel Level is in a	•	•		1	
			Readable Range for					
			both Primary and					
			Secondary Tanks too					
			Long					
			Volume in Primary		T	T	-	
				< 28 liters				
			AND	20 111.613				
			Volume in Secondary					
				> 6 liters				
			and remains in this					
				1800 seconds				
				1600 Seconds				
			OR Distance Traveled				4	
			without a Secondary Fuel Level Change					
			Fuel Level Change					
				T	T		1	
			If the vehicle is driven		Volume in Secondary			
			a distance of 62 miles		Tank			
			without the secondary			>= 6.0 liters		
			fuel level changing by					
			3 liters, then the					
			sender must be stuck.					
Fuel Level	P2067	This DTC will detect a	Fuel level Sender %		Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	100 failures out of	
Sensor 2 Circuit		fuel sender stuck out	of 5V range	< 10 %			125 samples	Type B
Low Voltage		of range low in the						
		secondary fuel tank.			Run/Crank voltage goes			
(For use on					to 0 volts at key off		100 ms / sample	
vehicles with dual								
fuel tanks)								
							Continuous	
<u> </u>	<u> </u>	<u> </u>	<u> </u>					

-	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Fuel Level Sensor 2 Circuit High Voltage (For use on vehicles with dual fuel tanks)	P2068	This DTC will detect a fuel sender stuck out of range low in the secondary fuel tank.	Fuel level Sender % of 5V range	> 60 %	Run/Crank Voltage Run/Crank voltage goes to 0 volts at key off	11 volts ≤ Voltage ≤ 32 volts	100 failures out of 125 samples 100 ms / sample	2 trips Type B
							Continuous	
Post Catalyst Fuel Trim System Low Limit Bank 1 (Too Rich)	P2096	catalyst O2 sensor based fuel control system has been unable to adapt to a	Rich Fail Counts: Note: If the fail count threshold is reached,	> 100 out of 2000 samples	The following must be true for: PTO: Intrusive diagnostic fuel control:	> 3.0 seconds NOT active FALSE (i.e. catalyst monitor diagnostic)	Frequency: Continuous Monitoring in 100ms loop	2 Trip(s) Type B
		rich exhaust gas condition that results in an emissions correlated failure.	report again until the next trip. If the sample count threshold is		Long Term Secondary Fuel Trim Enabled Please see "Long Term Secondary Fuel Trim Enable Criteria" in	Secondary Fuel Trim	-	
		is reported, a pass is		Ambient air pressure	>= 70 kPa			
			reported, the counters are reset to 0, and		Engine air flow	>= 0 g/s and <= 10000 g/s	- -	
			evaluation starts again.		Intake manifold air pressure	>= 0 kPa and <= 200 kPa		
					Induction air temperature	>= -20 °C and <= 200 °C		
					Start up coolant temperature	> -20 °C	1	
			•		NO AC	TIVE DTCs:		
					AIRS	AirDefault_NA System FA position Sensor FA		
					ECT_	Sensor_FA VeCircuit FA		
				EGRValvel	Performance_FA Sensor_FA			
					CamSns	srLctnAny_FA sionSystem_FA		
					EvapFlowDu	ringNonPurge_FA ureSensorCircuit_FA		
				EvapPurgeS				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						SmallLeak_FA		
						SolenoidCircuit_FA		
						jectorCircuit_FA		
						AF_SensorFA		
						_SensorTFTKO		
						<pre>\P_SensorFA gineVacuumStatus</pre>		
					_	ginevacuumStatus IisfireDetected_FA		
						nbalance Bank1		
						nk_1_Sensor_1_FA		
						nk_1_Sensor_2_FA		
					020_Bai	III_1_6611661_2_1 /\		
		Additional notes, stra	ategy and enable req	uirements:			1	
		If the post catalyst O2			will increment if:			
		voltage is outside a	The current post O2	? airflow mode is a se	elected cell:	See supporting tables:		
		control window, the	AND			Selected Cells]	
		integral offset is	Accumulated Cell C			See supporting tables: Cell		
		adjusted in an attempt	(**************************************	given cell while ena		Accum Min	<u> </u>	
		to move the voltage back inside the control	The above specifie	-				
		window. The offset	Filtered post O2 vol	tage is beyond the fa	ail threshold:	See supporting tables:		
		value is used to adjust				> O2 Rich Thresh		
		the front O2 sensor			for more than this many sour	to: Con aumoration tables: Out of	4	
		control to bias the bulk			for more than this many coun	ts: See supporting tables: Out of Window Count		
		average exhaust	AND			Window Count	J	
		air/fuel ratio either lear	The post catalyst O	2 integral offset is:		See supporting tables:	1	
		or rich. The integral		z integral onset is.		<= Integral Offset Min		
		offset value is retained		Note	- the Post O2 filter coefficient		†	
		between trips.		11010	the root of men document	O2 Filt Coefficient		
						OZ I III GOGINGIONI	1	
	I		_		Demo 440 of 254	4.0		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		Re-Pass Feature		•				•
		If a fault is active from a prior trip and the above fail threshold is not met on the current	Re-Pass sample counter is This counter will	>= 1000 counts	If neither a pass nor a fail can be reported before the sample counter reaches its threshold, no			
		trip, a Re-Pass sample counter must exceed a threshold in order for a pass to be reported.	the filtered post O2		report is made (indeterminate state).			
		High Vapor (HV) Delay	Feature					
		The diagnostic is at risk of reporting a false fail when excessively High Vapor (HV) conditions that impact	Canister purging is	<= 0.82 >= 5.0 seconds	Filtered post O2 voltage is outside the window defined by:	See supporting tables: HV Post Low and HV Post High	When these conditions are met, HV is detected and the diagnostic will	
		the fuel control system are present. This HV condition is indicated when the criteria to the			Integral offset is outside the window defined by:	See supporting tables: HV Integral Offset Low and HV Integral Offset High	temporarily stop evaluation.	
		right are met. In this situation, the diagnostic will	If HV has caused the diagnostic to stop evaluation, evaluation will resume when long					
		temporarily stop evaluation. When the HV condition subsides, evaluation will resume.	term fuel correction is for	> 0.85 >= 20.0 seconds		Note: When either the filtered post O2 voltage or the integral offset returns to the above defined windows, the		-
			If HV has caused the diagnostic to stop evaluation, evaluation will resume when the purge valve closes for			diagnostic will immediately resume evaluation.		
				>= 20.0 seconds				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL		
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.		
	P2097	Determines if the post catalyst O2 sensor based fuel control system has been unable to adapt to a lean exhaust gas condition that results in an emissions correlated failure.	Lean Fail Counts: Note: If the fail count threshold is reached, a fail is reported and the diagnostic will not report again until the next trip. If the sample count threshold is reached before a fail is reported, a pass is reported, the counters are reset to 0, and evaluation starts again.	> 100 out of 2000 samples	Same enable conditions for P2096, P2097, P2098, P2099 (see P2096 enable conditions)		Frequency: Continuous Monitoring in 100ms loop	2 Trip(s) Type B		
			al notes, strategy and enable requirements: st catalyst O2 The above specified Sample Counter will increment if:							
		voltage is outside a	The current post O2 air	flow mode is a selecte	ed cell:	See supporting tables:				
		control window, the integral offset is	AND	-4:44		Selected Cells				
		adjusted in an attempt	Accumulated Cell Cour		1)	See supporting tables: Cell				
		to move the voltage		iven cell while enabled	,	Accum Min				
		back inside the control			ement if the Sample Coun					
		window. The offset value is used to adjust	Filtered post O2 voltag	e is beyond the fall thr	esnoia:	See supporting tables: < O2 LeanThresh				
		the front O2 sensor control to bias the bulk average exhaust	AMB	for m	nore than this many counts:	See supporting tables: Out of Window Count				
		air/fuel ratio either lean	AND	(l . # (! .			Ī			
		or rich. The integral	The post catalyst O2 in	itegral offset is:		See supporting tables:				
		offset value is retained		Niete 4	Doot O2 filton coefficient in	>= Integral Offset Max				
		between trips.		Note - the	Post O2 filter coefficient is:	See supporting tables: Post O2 Filt Coefficient				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		Re-Pass Feature: san	ne for P2096, P2097, P	2098, P2099 (see P20	96 for details)			
		High Vapor (HV) Delay	/ Feature: same as ric	h fault for bank 1 (se	e P2096)			
Post Catalyst Fuel Trim System Low Limit Bank 2 (Too Rich)	P2098	Same as bank 1 rich fault (see P2096)	Rich Fail Counts: Note: Same as bank 1 rich fault (see	> 100 out of 2000 samples		ns for P2096, P2097, P2098, 96 enable conditions)	Frequency: Continuous Monitoring in 100ms loop	2 Trip(s) Type B
		Additional notes, stra	P2096)	rements: same as ba	replaced by: A/F Imb O2S_Bank	isted in the P2096 section are alance Bank2 2_Sensor_1_FA 2_Sensor_2_FA		
						,		
	Re-Pass Feature: same for P2096, P2097, P2098, P2099 (see P2096 for details) High Vapor (HV) Delay Feature							
		The diagnostic is at risk of reporting a false fail when excessively High Vapor (HV) conditions that impact the fuel control system are present. This HV condition is indicated when the criteria to the right are met. In this situation, the	fuel correction is for	<= 0.82 >= 5.0 seconds	Filtered post O2 voltage is outside the window defined by: Integral offset is outside the window defined by:	See supporting tables: HV Post Low and HV Post High See supporting tables: HV Integral Offset Low and HV Integral Offset High	When these conditions are met, HV is detected and the diagnostic will temporarily stop evaluation.	
		diagnostic will temporarily stop evaluation. When the HV condition subsides, evaluation will resume.	will resume when long term fuel correction is for If HV has caused the diagnostic to stop evaluation, evaluation will resume when the purge valve closes for	> 0.85 >= 20.0 seconds >= 20.0 seconds		Note: When either the filtered post O2 voltage or the integral offset returns to the above defined windows, the diagnostic will immediately resume evaluation.		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL illum.
	P2099	Same as bank 1 lean	Lean Fail Counts:	> 100 out of 2000	rarameters	Conditions		2
Post Catalyst Fuel Trim System High Limit Bank 2 (Too Lean)	fault (see P2097)			samples		s for P2096, P2097, P2098, 96 enable conditions)	Frequency: Continuous Monitoring in 100ms loop	Trip(s) Type B
					NOTE: The Bank1 faults li replaced by:	sted in the P2096 section are	-	
					O2S_Bank_	alance Bank2 _2_Sensor_1_FA _2_Sensor_2_FA		
		Additional notes stra	l tegy and enable requi	l romonte: eamo ae ha	ank 1 lean fault (see P2097			1
		Re-Pass Feature: san				1		
		High Vapor (HV) Delay						
Throttle Actuator	P2101	Detect a throttle	The throttle model			Run/crank voltage or	15 / 15 counts;	Trips:
Control - Position		positioning error	and actual Throttle			Powertrain relay voltage >	12.5 msec/count	1
Performance			position differ by >	5.824 %.		6.00 and reduced power is	in the primary	Type:
			or			false, else the failure will be	processor	Α
			The actual Throttle			reported for all conditions		MIL:
			position and throttle					YES
			model differ by >	5.824 %.	Engine Running or Ignition Voltage >			
						11		
					and Ignition Voltage >	11		
					and ignition voitage >	5.5		
					and Throttle is being Controlled			
					and Communication Fault (SPI is not set)			
					and TPS minimum learn is not active			
					Ignition voltage failure is false (P1682)			
		Detect throttle control is driving the throttle in	Thottle Position >	39.26 %.	TPS minimum learn is active		11 counts; 12.5 msec/count in the	1

Component/	1	Monitor Strategy	Malfunction	Threshold	Secondary			MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		the incorrect direction or exceed the reduced power limit				3 - 3	primary processor	
			Thottle Position >	39.06 %.	Reduce Engine Power is Active	false, else the failure will be reported for all conditions		
Throttle return to default	P2119	Throttle unable to return to default throttle position after de-energizing ETC motor.	TPS1 Voltage >	1.689	Throttle de-energized	No 5V reference error or fault for # 2 5V reference circuit (P0651)	0.4969 sec continuous	Trips:
			AND TPS2 Voltage > On the main processor	1.789	No TPS circuit faults			1 Type: C MIL:
			Or		PT Relay Voltage > 5.500			NO
			TPS1 Voltage > AND TPS2 Voltage > On the secondary processor	1.689 1.789				
APP1 Circuit	P2120	Detects a continuous or intermittent short or open in APP1 circuit on the secondary processor but sensor is in range on the primary processor	Secondary APP1 Voltage < or Secondary APP1 Voltage >	0.463		Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 msec/count in the secondary processor	Trips: 1 Type: A MIL: YES
						No 5 V reference #2 error No 5 V reference #2 DTC (P0651)		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
APP1 Circuit Low	P2122	Detects a continuous or intermittent short or open in APP1 circuit on both processors or just the primary processor	Primary APP1 Voltage <	0.463		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the primary processor	Trips: 1 Type: A MIL: YES
			Secondary APP1 Voltage <	0.463		No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
APP1 Circuit High	P2123	Detects a continuous or intermittent short in APP1 circuit on both processors or just the primary processor	Primary APP1 Voltage >	4.75		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the primary processor	Trips: 1 Type: A MIL: YES
			Secondary APP1 Voltage >			No 5 V reference #2 error No 5 V reference #2 DTC (P0651)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	
APP2 Circuit	P2125	Detects a continuous or intermittent short or open in APP2 circuit on the secondary processor but sensor is in range on the primary processor	Secondary APP2 Voltage < or Secondary APP2 Voltage >	0.325		Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 msec/count in the secondary processor	Trips: 1 Type: A MIL: YES

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						No 5 V reference #1 error No 5 V reference #1 DTC (P0641)		
APP2 Circuit Low F	P2127	Detects a continuous or intermittent short or open in APP2 circuit on both processors or just the primary processor	Primary APP2 Voltage <			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the primary processor	Trips 1 Type A MIL: YES
			Secondary APP2 Voltage <			No 5 V reference #1 error No 5 V reference #1 DTC (P0641)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	_
APP2 Circuit Low	P2128	Detects a continuous or intermittent short in APP2 circuit on both processors or just the primary processor	Primary APP2 Voltage >			Run/crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the primary processor	Trips 1 Type A MIL: YES
			Secondary APP2 Voltage >			No 5 V reference #1 error No 5 V reference #1 DTC (P0641)	19 / 39 counts or 14 counts continuous; 12.5 ms/count in the secondary processor	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Throttle Position (TP) Sensor 1-2 Correlation	P2135	Detects a continuous or intermittent correlation fault between TPS sensors #1 and #2 on primary or secondary processor	Difference between TPS1 displaced and TPS2 displaced >	min. throttle position		Run/Crank voltage or Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be	79 / 159 counts or 60 counts continuous; 3.125 ms/count in the primary processor	Trips: 1 Type: A MIL: YES
			Difference between (normalized min TPS1) and (normalized min TPS2) >			No TPS sensor faults (P0120, P0122, P0123, P0220, P0222, P0223) No 5V reference error or fault for # 2 5V reference circuit (P0651)		
			Difference between TPS1 displaced and TPS2 displaced >	min. throttle position		reported for all conditions	19 / 39 counts or 15 counts continuous; 12.5 ms/count in the secondary processor	
			Difference between (normalized min TPS1) and (normalized min TPS2) >			No TPS sensor faults (P0120, P0122, P0123, P0220, P0222, P0223) No 5V reference error or fault for # 2 5V reference circuit (P0651)		
Accelerator Pedal Position (APP) Sensor 1-2 Correlation	P2138	Detects a continuous or intermittent correlation fault between APP sensors #1 and #2 on primary or secondary processor	Difference between APP1 displaced and APP2 displaced >	min. pedal position		reported for all conditions	19 / 39 counts or 15 counts continuous; 12.5 ms/count in the primary processor	Trips: 1 Type: A MIL: YES
			Difference between (normalized min					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description		Value	Parameters	Conditions	Required	illum.
			APP1) and (normalized min APP2) >			No APP sensor faults (P2120, P2122, P2123, P2125, P2127, P2128) No 5V reference error or fault for #1 or #2 5V reference circuits (P0641, P0651)		
				min. pedal position		Powertrain relay voltage > 6.00 and reduced power is false, else the failure will be reported for all conditions	19 / 39 counts or 15 counts continuous; 12.5 ms/count in the secondary processor	
			Difference between (normalized min APP1) and (normalized min APP2) >			No APP sensor faults (P2120, P2122, P2123, P2125, P2127, P2128) No 5V reference error or fault for #1 or #2 5V reference circuits (P0641, P0651)		
Transfer Case Speed Sensor Output (TCSS)	P2160	No activity in the TCSS Signal circuit	TCSS Raw Speed	<= 50 RPM	Engine Torque Engine Torque Transmission Input speed Transmission Input speed Throttle Position Throttle Position Disabled For Following DTCS:	<= 8192 N-m >= 60 N-m <= 7500 RPM >= 1000 RPM <= 99.0 % >= 8.0 % TPS_FA EngineTorqureInaccurate TransTurbineSpeedValid(TCM	>= 5.00 Fail Time (Sec)	Type B 2 trips

Component/		9,	Malfunction	Threshold	Secondary		Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Transfer Case Speed Sensor Output (TCSS)		TCSS Circuit Signal Intermittent	Loop-to-Loop change	>= 225 RPM >= 475 RPM	Engine Torque Engine Torque	<= 8192 N-m >= 60 N-m		Type B 2 trips
					Transmission Input speed Transmission Input speed Throttle Position Throttle Position Engine Speed Number of Software Loops with TCSS =0	<= 7500 RPM >= 1000 RPM <= 99.0 % >= 8.0 % >= 1000 RPM < 10 counts		
				Disabled For Following DTCS:	TPS_FA EngineTorqureInaccurate TransTurbineSpeedValid(TCM P2160 Fault active CrankSensorFA)		
Minimum Throttle Position Not Learned		window after multiple	on the Primary processor, TPS	0.935			2.0 secs continuous	Trips: 1 Type: A MIL: YES
		Voltage >	0.935	No TPS circuit errors No TPS circuit faults P1682 is not active Minimum TPS learn active				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			and					
			Number of learn					
			attempts >	10 counts				
			AND					
			TPS2 Voltage >	1.789	Throttle de-energized			
			On the Primary					
			processor		No TPS circuit faults			
			OR					
			TPS1 Voltage >	1.689	PT Relay Voltage >			
			AND			5.5		
			TPS2 Voltage >	1.789				
			On the Secondary					
			processor					
Cooling System	P2181	This DTC detects	Engine Coolant Temp				30 failures out of	2 trips
Performance		thermostat malfunction					90 samples	Type B
		(i.e. stuck open)	temperature of 75					
			Deg C and				1 sec	
			normalized ratio is ≤				/sample	
			than 2. When above					
			is present for more					
			than 5 seconds, fail					
			counts start.					
					No Active DTC's	MAF_SensorFA		
						IAT_SensorFA		
			Engine total airgrams			_	Once per ignition	
			is accumulated when				key cycle	
			17 ≤ AirFlow ≤ 450					
			grams per second.					
						THMR_RCT_Sensor_Ckt_FA		
				Ī				
						THMR_ECT_Sensor_Ckt_FA		
			Ratio Definition:	Ì	Engine not run time	≥ 1800 seconds		
			Current temp					
			difference between					
			ECT and RCT minus					
			PwrUp difference					
			divided by total					
			airgrams.					
			Note: Minimum total					
			airgrams is 500.0					
			grams.		Engine run time	90 ≤ Time ≤ 1370 seconds		

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						Ethanol ≤ 87%		
					ECT at Power Up	-7.0 ≤ ECT ≤ 70.0 °C		
					IAT min	-7°C ≤ IAT ≤ 55°C.		
					Airflow	17.0 ≤ Airflow ≤ 450.0 GPS		
Air Fuel	P219A	Determines if the air-	Bank 1 Filtered	> 0.23	System Voltage	10 <= V <= 32 for >= 4	Frequency:	2
Imbalance Bank	(P1174	fuel delivery system is	Length Ratio variable			seconds	Continuous	Trip(s)
1	on	imbalanced by			ECT	> -20 oC	Monitoring of O2	Type E
	some	monitoring the pre and			Engine Run Time	·	voltage signal in	
	applicat	post catalyst O2			<u> </u>	425 <= rpm <= 3500	12.5ms loop	
	ions)	sensor voltage	0	R		15.0 <= g/s <= 510.0	1	
		characteristics.	Bank 1 AFM (DoD)	> 8192.00	Air Per Cylinder	260 <= mg/cylinder <= 2000	1	
			Filtered Length Ratio	0.102.00	7 iii 1 di dyiiiiddi	200 1119/07/11140/		
			variable (AFM		% Ethanol	<= 87 %	1	
			applications only)		Positive (rising) Delta O2	> 0.0 millivolts	The AFIM Filtered	
			7,		voltage during previous	2 0.0 11111111111111111	Length Ratio	
		To improve S/N, pre-	AN	ID.	12.5ms is		variable is	
		catalyst O2 voltages	Bank 1 Filtered Post	שא	OR		updated after	
		between 1000 and 0			Negative (falling) Delta		every 2.50	
		millivolts are ignored.	catalyst O2 voltage is	4000	regative (lailing) Belta		seconds of valid	
		This feature is enabled	NOT between	1000 and 0 millivolts	1 (5 11)) 5 11	OR	data.	
		at Air Per Cylinder	Note: If the first		Negative (falling) Delta	< 0.0 millivolts	data.	
		values <= 0	Note: If the first		O2 voltage during			
			voltage value is >=		previous 12.5ms is			
		mg/cylinder.	the second voltage value, this is an					
		Note: If the first voltage					The first report is	
		value is >= the second			For AFM (Cylinder	No AFM state change during	delayed for 45	
		voltage value, AND/OR	post catalyst O2 data		Deactivation) vehicles	current 2.50 second sample	seconds to allow	
		the Air Per Cylinder			only	period.	time for the AFIM	
		value is equal to zero,	diagnosis on this				Filtered Length	
		the feature is not used	application.		O2 sensor switches	>= 1times during current 2.50	Ratio variable to	
		on this application and				second sample period	saturate. This	
		the full pre-catalyst O2					minimizes the	
		voltage range is			Quality Factor	>= 0.70 in the current	possibility of	
		utilized.				operating region	reporting a pass	
		utilizeu.			No EngineMisfireDetected		before a potential	
					No MAP_SensorFA	_	failure could be	
					No MAF SensorFA		detected.	
					No ECT Sensor FA		1	
					No Ethanol Composition S	Sensor FA	1	
					No TPS ThrottleAuthority		1	
					No FuelInjectorCircuit FA		1	
					No AIR System FA		1	
	1			l	INO AIR SYSTEITI FA		_	I

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		Monitor Strategy Notes: The AFIM	The AFIM Filtered Length Ratio is the difference between the measured String Length and a 17x17 table lookup value,divided by the same lookup value, and finally multiplied by a Quality Factor (the latter ranges between 0 and 1, based on robustness to false diagnosis in the current operating region). The reason we use a ratio of the String Lengths is so that we can normalize the failure metric over various engine speed and load directly	The Quality Factor (QF) calibrations are located in a 17x17 lookup table versus engine speed and load (see Supporting Tables). A QF of "1" is an indication that we were able to achieve at least 4sigma/2sigma robustness in that speed/load region. QF values less than "1" indicate that we don't have 4sigma/2sigma robustness in that region. The quality of the data is determined via statistical analysis of String Length data. QF values less than 0.70 identify regions where diagnosis is not possible.	No O2S_Bank_1_Sensor_ No O2S_Bank_2_Sensor_ No EvapPurgeSolenoidCirc No EvapFlowDuringNonPi No EvapSmallLeak_FA No EvapEmissionSystem_ No FuelTankPressureSen Device Control Not Active Intrusive Diagnostics Not A Engine OverSpeed Protect Reduced Power Mode (ET PTO Not Active Traction Control Not Active Traction Fuel Co Closed Loop Long Term FT Cumulative (absolute) delta MAF during the current 2.50 second sample period is Note: This protects Data collection is suspended under the following circumstances:			

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Air Fuel	P219B	Determines if the air-	Bank 2 Filtered	> 0.50	System Voltage	10 <= V <= 32 for >= 4	Frequency:	2
Imbalance Bank		fuel delivery system is	Length Ratio variable			seconds	Continuous	Trip(s)
2		imbalanced by			ECT	> -20 oC	Monitoring of O2	Type E
		monitoring the pre and			Engine Run Time	>= 100 seconds	voltage signal in	
		post catalyst O2				425 <= rpm <= 3500	12.5ms loop	
		sensor voltage	0	R	Mass Airflow	15.0 <= g/s <= 510.0		
		characteristics.	Bank 2 AFM (DoD) Filtered Length Ratio	> 8192.00	Air Per Cylinder	260 <= mg/cylinder <= 2000		
			variable (AFM		% Ethanol	<= 87 %]	
			applications only)		Positive (rising) Delta O2	> 0.0 millivolts	The AFIM Filtered	
					voltage during previous		Length Ratio	
		To improve S/N, pre-	AN	ND	12.5ms is		variable is	
		catalyst O2 voltages	Bank 2 Filtered Post		OR		updated after	
		between 1000 and 0	catalyst O2 voltage is		Negative (falling) Delta		every 2.50	
		millivolts are ignored.	NOT between	1000 and 0 millivolts		OR	seconds of valid data.	
		This feature is enabled	N. 1511 C. 1		Negative (falling) Delta	< 0.0 millivolts		
		at Air Per Cylinder	Note: If the first		O2 voltage during			
		values <= 0	voltage value is >=		previous 12.5ms is			
	mg/cylinder.	the second voltage value, this is an						
	Note: If the first voltage					The first report is		
		value is >= the second	post catalyst O2 data		For AFM (Cylinder	No AFM state change during	delayed for 45	
		voltage value, AND/OR			Deactivation) vehicles	current 2.50 second sample	seconds to allow	
		the Air Per Cylinder	diagnosis on this		only	period.	time for the AFIM	
		value is equal to zero,	application.				Filtered Length	
		the feature is not used	арриоскоги.		O2 sensor switches	>= 1 times during current	Ratio variable to	
		on this application and				2.50 second sample period	saturate. This	
		the full pre-catalyst O2					minimizes the possibility of	
		voltage range is			Quality Factor	>= 0.70 in the current	reporting a pass	
		utilized.				operating region	before a potential	
					No EngineMisfireDetected	_FA	failure could be	
					No MAP_SensorFA		detected.	
					No MAF_SensorFA		dottottod.	
					No ECT_Sensor_FA			
					No Ethanol Composition S			
					No TPS_ThrottleAuthority[
				No FuelInjectorCircuit_FA				
					No AIR System FA		1	
					No O2S_Bank_1_Sensor_		1	
					No O2S_Bank_2_Sensor_	- -	1	
				No EvapPurgeSolenoidCir		1		
		Monitor Strategy	The AFIM Filtered	The Quality Factor	No EvapFlowDuringNonPu		_	
		Notes: The AFIM	Length Ratio is the	(QF) calibrations are	No EvapVentSolenoidCirc	uit_FA		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		Filtered Length Ratio is derived from the pre-O2 sensor voltage metric known as String Length. String Length is simply the curve length of the O2 sensor voltage over a fixed time period of 2.50 seconds. The reason we use String Length is because it comprehends both O2 signal frequency and amplitude in one metric. The busier the O2 voltage (an indication of	difference between the measured String Length and a 17x17 table lookup value, divided by the same lookup value, and finally multiplied by a Quality Factor (the latter ranges between 0 and 1, based on robustness to false diagnosis in the current operating region). The reason we use a ratio of the String Lengths is so that we can normalize the failure metric over various engine speed and load directly impact pre-O2 String Length, especially	located in a 17x17 lookup table versus engine speed and load (see Supporting Tables). A QF of "1" is an indication that we were able to achieve at least 4sigma/2sigma robustness in that speed/load region. QF values less than "1" indicate that we don't have 4sigma/2sigma robustness in that	No EvapSmallLeak_FA No EvapEmissionSystem No FuelTankPressureSen Device Control Not Active Intrusive Diagnostics Not Engine OverSpeed Protec Reduced Power Mode (E** PTO Not Active Traction Control Not Active Fuel Co Closed Loop Long Term FT	_FA lsorCircuit_FA Active ction Not Active TC DTC) Not Active		

Component/			Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions		illum.
Barometric Pressure (BARO) Sensor Performance	P2227	Detects a noisy or erratic barometric pressure input	Difference between the current Baro sensor reading and the previous Baro sensor reading	> 10.0 kPa	Ignition has been on Vehicle Speed No Active DTCs:	> 10.0 seconds < 62 MPH AmbientAirPressCktFA ECT_Sensor_FA IAT_SensorFA MAF_SensorFA AfterThrottlePressure_NA or AfterThrottlePressure_SC TPS_FA TPS_Performance_FA VehicleSpeedSensorError	5 failures out of 25 samples 1 sample every 250 msec	Type B 2 trips
Barometric Pressure(BARO) Sensor Circuit Low	P2228	Detects a continuous short to low or open in either the signal circuit or the BARO sensor.	BARO Voltage	< 40.0 % of 5 Volt Range (2.0 Volts = 50.9 kPa)	Continuous		20 failures out of 25 samples 1 sample every 12.5 msec	Type B 2 trips
Barometric Pressure(BARO) Sensor Circuit High	P2229	Detects an open sensor ground or continuous short to high in either the signal circuit or the BARO sensor.	BARO Voltage	> 90.0 % of 5 Volt Range (4.5 Volts = 115.0 kPa)	Continuous		20 failures out of 25 samples 1 sample every 12.5 msec	Type B 2 trips
Fuel Conductivity Out Of Range (water in fuel)	P2269	Detects Sensor Frequency Signal	Flex Fuel Sensor Output Frequency	> 185 Hertz	Powertrain Relay	> 11.0 Volts < 32.0 Volts	50 failures out of 63 samples 100 ms loop Continuous	2 trip(s) Type B
O2 Sensor Signal Stuck Lean Bank 1 Sensor 2	P2270	no longer be used for post oxygen sensor fuel control or for catalyst monitoring.	Post O2 sensor cannot achieve the rich threshold voltage. AND The Accumulated mass air flow monitored during the Stuck Lean Voltage	1) Post O2S signal < 700 mvolts AND 2) Accumulated air flow during stuck lean test > 200 grams.	No Active DTC's	TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR	2 trips Type B

Component/	Fault		Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		intrusive test (during	Test is greater than				NaPOPD_b_Rapi	
		coast) which increases					dResponseActive	
		the delivered fuel to	the above voltage				= TRUE, multiple	
			threshold is met.				tests per trip are	
		rich threshold.					allowed.	
						MAF_SensorFA		
						MAP_SensorFA		
						AIR System FA		
						FuelInjectorCircuit_FA		
						FuelTrimSystemB1_FA		
						FuelTrimSystemB2_FA		
						EngineMisfireDetected_FA		
						EthanolCompositionSensor F		
						Δ		
					R1S2 Failed this koy	P013A, P013B, P013E,		
						P013F, P2270 or P2271		
					Cycle	10.0 volts < system voltage<		
					System Voltage			
					ICAT MAT Burnoff delay			
						= Not Valid, See definition of		
						Green Sensor Delay Criteria		
						(B1S2) in Supporting Tables		
					Green O2S Condition	tab.		
					Low Fuel Condition Diag	= False		
					Engine Speed to initially			
						900 <= RPM <= 2300		
					Engine Speed range to			
					keep test enabled (after			
						850 <= RPM <= 2400		
						3 gps <= Airflow <= 20 gps		
						39.8 mph <= Veh Speed <=		
					enable test			
					Vehicle Speed range to	·		
						35.4 mph <= Veh Speed <=		
					initially enabled)			
						0.80 <= C/L Int <= 1.08		
					Closed Loop Active			
					· ·	not in control of purge		
						not in estimate mode		
					Post fuel cell			

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					O2S Heater on Time Predicted Catalyst temp Fuel State All of the above seconds, and then th	= not active		
O2 Sensor Signal Stuck Rich Bank 1 Sensor 2	P2271	, ,	Post O2 sensor cannot achieve the lean threshold voltage. AND The Accumulated mass air flow monitored during the Stuck Rich Voltage Test is greater than the threshold before the above voltage threshold is met.	1) Post O2S signal > 100 mvolts AND 2) Accumulated air flow during stuck rich test > 80 grams.	B1S2 Failed this key	TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013A, P013B, P013E, P013F or P2270 10.0 volts < system voltage < 32.0 volts	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed.	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
System	Code	респрион	Criteria	value	Green O2S Condition Low Fuel Condition Diag Engine Speed Engine Airflow Vehicle Speed Closed Ioop integral Closed Loop Active Evap Ethano Post fuel cell Power Take Off EGR Intrusive diagnostic All post sensor heater delays O2S Heater on Time Predicted Catalyst temp Fuel State DTC's Passed	= Not Valid, See definition of Green Sensor Delay Criteria (B1S2) in Supporting Tables tab. = False 900 <= RPM <= 2300 3 gps <= Airflow <= 20 gps 39.8 mph <= Veh Speed <= 80.8 mph 0.80 <= C/L Int <= 1.08 = TRUE not in control of purge not in estimate mode = enabled f = not active = not active = = not active >= 80.0 sec 500 °C <= Cat Temp <= 900		
					DFCO mo	conditions are met: de is continued tiated pedal input).		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
-	Code	Description	Post O2 sensor cannot achieve the rich threshold voltage. AND The Accumulated mass air flow monitored during the Stuck Lean Voltage Test is greater than		B2S2 Failed this key cycle System Voltage ICAT MAT Burnoff delay Green O2S Condition Low Fuel Condition Diag Engine Speed to initially enable test Engine Speed range to keep test enabled (after initially enabled) Engine Airflow	Conditions TPS_ThrottleAuthorityDefault ed ECT_Sensor_FA IAT_SensorFA MAF_SensorFA MAP_SensorFA AIR System FA FuelInjectorCircuit_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA EngineMisfireDetected_FA EthanolCompositionSensor_F A P013C, P013D, P014A, P014B, P2272 or P2273 10.0 volts < system voltage< 32.0 volts = Not Valid = Not Valid, See definition of Green Sensor Delay Criteria (B2S2) in Supporting Tables tab.		

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					initially enabled) Closed loop integral Closed Loop Active Evap Ethanol Post fuel cell Power Take Off EGR Intrusive diagnostic All post sensor heater delays O2S Heater on Time Predicted Catalyst temp Fuel State All of the above seconds, and the	35.4 mph <= Veh Speed <= 85.7 mph 0.80 <= C/L Int <= 1.08 = TRUE not in control of purge not in estimate mode = enabled = not active = not active		
O2 Sensor Signal Stuck Rich Bank 2 Sensor 2	P2273	This DTC determines if the post catalyst O2 sensor is stuck in a normal rich voltage range and thereby can no longer be used for post oxygen sensor fuel control or for catalyst monitoring. The diagnostic is an intrusive test which requests the DFCO mode to achieve the required lean threshold.	Post O2 sensor cannot achieve the lean threshold voltage. AND The Accumulated mass air flow monitored during the Stuck Rich Voltage Test is greater than the threshold before the above voltage threshold is met.	1) Post O2S signal > 100 mvolts AND 2) Accumulated air flow during stuck rich test > 80 grams.		ed ECT_Sensor_FA IAT_SensorFA	Frequency: Once per trip Note: if NaPOPD_b_Res etFastRespFunc= FALSE for the given Fuel Bank OR NaPOPD_b_Rapi dResponseActive = TRUE, multiple tests per trip are allowed.	2 trips Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						EngineMisfireDetected_FA		
						EthanolCompositionSensor_F		
						A		
					B2S2 Failed this key	P013C, P013D, P014A,		
						P014B or P2272		
						10.0 volts < system voltage<		
					System Voltage			
					ICAT MAT Burnoff delay			
						= Not Valid, See definition of		
						Green Sensor Delay Criteria		
						(B2S2) in Supporting Tables		
					Green O2S Condition			
					Low Fuel Condition Diag	 = False		
						900 <= RPM <= 2300		
						3 gps <= Airflow <= 20 gps		
						39.8 mph <= Veh Speed <=		
					Vehicle Speed			
						0.80 <= C/L Int <= 1.08		
					Closed Loop Active			
						not in control of purge		
					-	not in estimate mode		
					Post fuel cell			
					Power Take Of			
					1 OWEI TAKE OII	- not active		
					EGR Intrusive diagnostic	l = not active		
					All post sensor heater			
						= not active		
					O2S Heater on Time			
					O20 Heater on Time	500 °C <= Cat Temp <= 900		
					Predicted Catalyst temp			
						= DFCO possible		
						•		
					Dics Passed	= P2270 (and P2272 (if applicable))		
					DTOIs Decree			
					DICS Passed	= P013E (and P014A (if		
					DTOI- Days	applicable))		
					DIC's Passed	= P013A (and P013C (if		
						applicable))		
						I	4	
						conditions are met:		
						de is continued		
			1		(wo driver ini	tiated pedal input).		

Component/	Fault	0,	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Secondary AIR	P2430	This DTC detects a	Average Pressure	< 0.50 kPa	BARC) > 60 kPa	Stuck in range	
System Pressure		stuck in range	Error		Inlet Air Temp	> 5.0 deg C.	cumulative time >	2 trip(s)
Sensor Circuit		pressure sensor signal	A	ND	Coolant Temp	> 5.0 deg C.	5.0 seconds	
Bank 1		when the AIR pump is	Signal Variation	< 1.00 kPa		< 60.0 deg C.		Type B
		commanded on.			Engine off time	> 3600.0 seconds]	
					System Voltage	e > 10.0 OR < 32.0 Volts		
					MAP not	< 20 kPa for 2.0 sec.	Frequency: Once	
					Engine Speed		per trip when SAI	
						t > 50 gm/s for 3.0 sec.	pump	
					No active DTCs:	AIRValveControlCircuit FA	commanded On	
						AIRPumpControlCircuit FA		
						AIRSysPressSnsrB1CktLoFA		
						AIRSysPressSnsrB1CktHiFA		
						ControllerProcessorPerf FA		
						5VoltReferenceA FA		
						5VoltReferenceB FA		
						_		
Secondary AIR	P2431	This DTC detects a	Difference between		BARC) > 60 kPa	Skewed sensor	
System Pressure		skewed pressure	AIR pressure sensor		Inlet Air Temp	> 5.0 deg C.	cumulative test	2 trip(s)
Sensor		sensor signal via a	and BARO (Pump		Coolant Temp		weight > 5.0	
Performance		comparison of the AIR	Commanded Off)	> 20.0 kPa		< 60.0 deg C.	seconds	Type B
Bank 1		pressure sensor signal		< -20.0 kPa	Engine off time			
		and estimated BARO,		R		> 10.0 OR < 32.0 Volts		
		as well as an	Difference between			< 20 kPa for 2.0 sec.		
		evaluation of the quality of the	AIR pressure sensor		Engine Speed		Continuous	
		comparison.	and BARO (Pump			> 50 gm/s for 3.0 sec.	6.25ms loop	
		Companson.	Commanded On)	> 50.0 kPa		se not in 4WD Low		
					Run/c	crank active		
						Skewed sensor		
						cumulatative test weight is		
						based on distance from the		
						last Baro update. See Baro		
						Skewed Sensor Weight		
						Factor table.		
					No. C. PTO	AID//-I - O - 1 - IO: - 11 - IO:		
					No active DTCs:	AIRValveControlCircuit FA		
		1	l			AIRPumpControlCircuit FA	[

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
oystem	Oode	Description	Onteria	variae	Tarameters	AIRSysPressSnsrB1CktLoFA AIRSysPressSnsrB1CktHiFA MAF_SensorFA EngineMisfireDetected_FA ControllerProcessorPerf_FA 5VoltReferenceA_FA 5VoltReferenceB_FA	required	mum.
Secondary AIR System Pressure Sensor Circuit Low Voltage Bank 1	P2432	This DTC detects an out of range low AIR pressure sensor signal	AIR Pressure Sensor signal	< 5 % of 5Vref	No active DTCs:	ControllerProcessorPerf_FA 5VoltReferenceA_FA 5VoltReferenceB_FA	800 failures out of 1000 samples 6.25 ms loop Continuous	2 trip(s)
Secondary AIR System Pressure Sensor Circuit Hi Voltage Bank 1	P2433	This DTC detects an out of range high AIR pressure sensor signal	AIR Pressure Sensor signal	> 94 % of 5Vref	No active DTCs:	ControllerProcessorPerf_FA 5VoltReferenceA_FA 5VoltReferenceB_FA	800 failures out of 1000 samples 6.25 ms loop Continuous	2 trip(s) Type B
Secondary AIR System Shut-off Valve Stuck Open (Single Valve System)	P2440	This DTC detects if the AIR system control valve is stuck open This test is run during Phase 2 (Pump commanded On, valve commanded closed)		< Bank 1 Valve Pressure Error table > 32 kPa for either Bank	Inlet Air Temp Coolant Temp Engine off time System Voltage MAP not Engine Speed MAF not Stability Time AIR diagnosti Conditional test by multiplying to Phase 2 Baro Phase 2 MAF Phase 2 System N	> 5.0 deg C. < 60.0 deg C. > 3600.0 seconds > 10.0 OR < 32.0 Volts < 20 kPa for 2.0 sec.	Phase 2 Conditional test weight > 2.0 seconds Frequency: Once per trip when AIR pump commanded On	2 trip(s)

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					No active DTCs:	AIRSystemPressureSensor FA	\	
						AIRValveControlCircuit FA		
						AIRPumpControlCircuit FA		1
						MAF_SensorFA		
						AmbientAirDefault_NA		
						IAT_SensorFA		
						ECT_Sensor_FA		
						EngineMisfireDetected_FA		
						CatalystSysEfficiencyLoB1_FA	\ \	
						CatalystSysEfficiencyLoB2_FA	١	
						ControllerProcessorPerf_FA		
						5VoltReferenceA_FA		
						5VoltReferenceB_FA		
						IgnitionOutputDriver_FA		
						FuelInjectorCircuit_FA		
Secondary AIR	P2444	This DTC detects if the	AIR pressure error	> Bank 1 Pump		> 60 kPa	Phase 3	
System Pump		SAI pump is stuck On		Pressure Error table	Inlet Air Temp		Cumlatative test	1 trip(s)
Stuck On (Single					Coolant Temp		weight > 3.0	
Valve Systems)						< 60.0 deg C.	seconds	
			10	< -32 kPa	<u> </u>	> 3600.0 seconds		Type A
				either Bank	, , ,	> 10.0 OR < 32.0 Volts	_	
		This test is run during				< 20 kPa for 2.0 sec.	Frequency: Once	
		Phase 3 (Pump			Engine Speed		per trip when AIR	
		commanded Off, valve				> 50 gm/s for 3.0 sec.	pump	
		commanded closed)				> 6.0 seconds	commanded On	
						c Phase 1 passed		
						c Phase 2 passed		
						Phase 3 cumulatative test		
						weight is based on the		
						distance from the last Baro		
						update. See Baro Skewed Sensor Weight Factor table.		
						Sensor Weight Factor table.		
								1
					No active DTCs:	AIDSvotomDrossuraSons = 54		1
					INO active DTCs:	AIRSystemPressureSensor FA	\ 	1
						AIRValveControlCircuit FA		1
						AIRPumpControlCircuit FA		1
						MAF_SensorFA		1
						AmbientAirDefault_NA		1
						IAT_SensorFA		1
			l	1	l	ECT_Sensor_FA		1

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						EngineMisfireDetected_FA CatalystSysEfficiencyLoB1_F/ CatalystSysEfficiencyLoB2_F/ ControllerProcessorPerf_FA 5VoltReferenceA_FA 5VoltReferenceB_FA IgnitionOutputDriver_FA FuelInjectorCircuit_FA		
Transmission Control Torque Request Circuit	P2544	Determines if the torque request from the TCM is valid	Protect error - Serial Communication message - (\$199 - PTEI3)	Message <> two's complement of message	Diagnostic enabled/ disabled	Enabled	>= 16 Protect errors during key cycle. Performed every 25msec.	2 trip(s
			Rolling count error - Serial Communication	PR	Power Mode	= Run	>= 6 Rolling count errors out of ten samples.	Type B
			message (\$199 - PTEI3) rolling count value	Message <> previous message rolling	Engine Running	= True	Performed every 25msec.	
			C	count value + one	Run/Crank Active	> 0.50 Sec		
			RAM Error - Internal ECU fault	Transmission torque request value or request type dual store not equal			>= 3 RAM errors during key cycle. Performed every 25msec.	
				> 600 Nm			>= 3 out of 10	
			Range Error - Serial Communication message - (\$199 - PTEI3) TCM Requested Torque Increase				samples. Performed every 25 msec.	
				PR				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			- Trans torque intervention type	Requested torque intervention type toggles from not increasing request to increasing request			>= 3 multi- transitions out of 5 samples. Performed every 200msec.	
Torque Management Request Input	P2548	Determines if the performance launch torque request is valid		Message <> two's	Diagnostic enabled/ disabled	Enabled	>= 10 Protect errors out of 10	2 trip(s) Type B
Signal B			Message)	complement of message	Run/Crank Active	> 0.50 Sec	samples	-
			0					
				Message <> previous message rolling count value + one			>= 3 Rolling count errors out of 10 samples	
					No active DTC's	Fault bundles: IAC_SystemRPM_FA	Each test Performed every 12.5 msec	
ECM/PCM Internal Engine	P2610	This DTC determines if the engine off timer	Initial value test: Initial ignition off timer		ECM is powered down		Initial value test:	2 trips Type B
Off Timer Performance		does not initialize or count properly.	value OR	< 0 seconds	IAT Temperature	-40 °C ≤ Temperature ≤ 125	3 failures 1.375 sec /	
		Clock rate test: Checks the accuracy	Initial ignition off timer value	> 10 seconds		°C	sample	on next
		of the 1 second timer by comparing it with	Clock rate test: Time between ignition				Clock rate test:	key cycle if failure detected
		the 12.5 ms timer	off timer increments	< 0.8 seconds			8 failures out of 10 samples	
			Time between ignition off timer increments	> 1.2 seconds				
			Time since last ignition off timer				1 second / sample	
			•	≥ 1.375 seconds			test runs once each key-off	

Component/		Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Current ignition off					
			time < old ignition off					
			time					
			Current ignition off					
			timer minus old					
			ignition off timer	≠ 1				
Four Wheel Drive	P2771	Detects			Engine	<= 8192 N-m		Type B
Low Switch					Torque	>= 30 N-m		2 trips
Circuit		Fail Case 1:	Fail Case 1:		Engine	<= 5500 RPM	Fail Case 1:	
		Couninuous	Measured	<= 3.00 ratio	Speed	>= 1000 RPM	>= 2.0	
		Open (Stuck	Transfer Case	>= 2.40 ratio	Ignition	<= 32 V	Consecutive	
		Off)	Ratio		Voltage	>= 11 V	Seconds for	
					Throttle	<= 99.0 %	1 Times	
		Fail Case 2:	Fail Case 2:		Position	>= 5.0 %		
		Ground (Stuck	Measured	<= 1.85 ratio	Transmission	<= 130 ° C.	Fail Case 2:	
		On) in the Four	Transfer Case	>= 0.65 ratio	Temperature	>= -20 ° C.	>= 7.0	
		Wheel Drive	Ratio		Engine Run time	> 10 Sec	Consecutive	
					Vehicle Speed	>= 3 MPH	Seconds for	
					·		1 Times	
					Automatic	Not in Park, Neutral, or		
					Transmission	Reverse		
					Gear			
					State			
					Manual	Clutch Not engaged		
					Transmission			
					Disabled	TCM:		
					For Following	TransTurbineSpeedValid(TCM	1)	
					DTCS:	Trans_Gear_Defaulted(TCM)	,	
						ECM:		
						VehicleSpeedSensorError		
						P150A, P150B, P2160,		
						P2161		
						CrankSensorFaultActive		
						TPS_FA		
						TOSS_Fault		
						EngineTorqureInaccurate		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
O2Sensor Circuit Range/ Performance Bank 1 Sensor 1	P2A00	This DTC determines if the O2 sensor voltage is not meeting the voltage criteria to	Closed Loop O2S ready flag		No Active DTC's	TPS_ThrottleAuthorityDefault ed MAP_SensorFA	200 failures out of 250 samples.	2 trips Type B
		enable closed loop fueling.	A) O2S signal must be 1) O2S signal OR 2) O2S signal To set Closed Loop ready flag	> 550 mvolts < 350 mvolts	System Voltage	ECT_Sensor_FA FuelInjectorCircuit_FA P0131, P0151 P0132, P0152 10.0 volts < system voltage< 32.0 volts	Frequency: Continuous	
			Closed Loop O2S ready flag B) Once set to ready O2S cannot be	= True	Engine Speed Engine Airflow	1000 RPM <= Engine speed <= 3400 RPM 10.0 gps <= Engine Airflow<= 50.0 gps		
			2) O2S signal for time	< 550 mvolts > 5.0 seconds		= False		
			Then set Closed Loop ready flag	= False	Fuel State AFM Status Predicted Exhaust Temp (B1S1) Engine run time	= False DFCO not active = All Cylinders active >= 0.0 °C > 100 seconds		
						above met for > 5 seconds		
Deactivation System Performance	P3400	Detects a "failed to deactivate" condition when Deactivation Mode allowed:	ABS(Measured MAP – MAP Model 2) AND ((Measured MAP – MAP Model 2) filtered) (stored from previous all-Cylinder mode	< -10.0 kPa	DIAGNOSTIC EI Total filtered residual weight factors ECT IAT Engine RPM	>= 0.0 factor > -7 and < 125 Deg C > -20 and < 125 Deg C > 450 and < 5800 RPM	100 cylinder deactivation lag residual failures out of 200 samples	2 trip(s) Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			event) - ((Measured MAP – MAP Model 2) filtered) (current)	> 10.0 kPa		MAP Model 2 multiplied by MAP2 Residual Weight Factor based on RPM. See table IFRD Residual Weighting Factors	Performed once every 100 msec	
					(Conditions below must	ATION ENABLE CONDITIONS be met for >= 0 seconds before activation will begin)		
					Engine running Engine RPM	> 30.0 seconds > EngSpeedLwrLimitEnableT able AND < EngSpeedUprLimitEnableT able - Details on Supporting Tables Tab (P3400 Section)		
					Engine coolant	>= 44.0 and <= 128.0 Deg C		
					Ignition voltage Pedal Commanded Throttle Area Brake booster vacuum Engine oil temp Transmission gear	>= 11.0 and <= 32.0 Volts < 5 Percent >= 45.0 kPa >= 20 and <= 128 Deg C		
					Vehicle speed FCO not active for Time since last cylinder deac mode event Gear shift	HalfCylDisabledTransGr and HalfCylDisabledTransGrDevice eControl (when in device control) - See details on Supporting Tables Tab (P3400 Section) >= 11 MPH >= 3.0 Seconds >= 3.0 Seconds Not currently in progress		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					AC Clutch transition Tip In Bump Accelerator pedel delta	Not currently in progress Not active <= 50.0 Percent in 12.5 ms		
					Engine oil pressure	>= 187 and <= 455 kPa		
					Filtered engine vacuum			
					PRNDL state	> AllCylToHalfCylVacuum or EcoAllCylToHalfCylVacuum (in Eco mode) - See details on Supporting Tables Tab (P3400 Section) for 0.0 sec.		
						HalfCylDisabledPRNDL and HalfCylDisabledPRNDLDevic eControl tables (when in device control) - See details on Supporting Tables Tab (P3400 Section)		
					Oil aeration present			
						Aeration enabled by engine RPM > 3100 for 10 seconds, disabled by engine RPM < 3000 for 50 seconds		
					After exiting deac mode, must be in all cylinder			
					mode for	>= 60 seconds		
					DFCO mode Fuel shut off mode other than DFCO	Not currently in DFCO		
						Not currently in fuel shut-off		
					ETC Power management mode			
					Heater performance	Not active Not in Heater Performance Mode		
					POSD Intrusive			
						POSD diagnostic not active		

component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
ystem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					POPD Intrusive			
						POPD diagnostic not active		
					Low range 4WD	Not in Low Range 4WD		
					AFM is disabled at high	Trot in Low Hange TVD		
					percent ethanol			
					percent ethanol	Ethanol concentration > 95 %		
						disables AFM. Once disabled,		
						ethanol concentration must		
						be < 85 % to re-enable		
					If feature is enabled, AFM	1		
					is allowed only when			
					percent ethanol learn is			
					not in progress			
					1			
					1	Feature is Disabled		1
						i cature is Disabled		
						ANY OF THE CONDITIONS		
					If deactivation mode is	CYLINDER REACTIVATION		
					active for	>= 480 seconds		
					then reactivation will	100 00001100		
					occur if:			
					Deac mode active	>= 600 seconds		
						OR		
					Delta vacuum	> 5 or < -5 kPa		
					Engine RPM	>		
						EngSpeedLwrLimitDisableT		
						able AND <		
						EngSpeedUprLimitDisableT		
					1	able - Details on Supporting		
					1	Tables Tab (P3400 Section)		
					Engine power limited	Active		
					mode			
					Pedal Commanded			
					Throttle Area	> 6 Dereent		
						> 6 Percent		
					Piston protection	Active		
					Engine oil temperature			
					1	< 18 or > 130 Deg C		1
					Engine oil pressure			
		I		1		< 172 or > 470 kPa		1

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					Oil aeration present			
						Aeration enabled by engine		
						RPM > 3100 for 10 seconds,		
						disabled by engine RPM <		
						3000 for 50 seconds		
					Engine metal overtemp			
					protection			
						Active		
					Accelerator pedel delta	Active		
					Accelerator peder della	<= 50.0 percent in 12.5 mg		
					In device control only if	<= 50.0 percent in 12.5 ms		
					In device control only, if			
					PNDRL in Park or			
					Neutral, vehicle speed			
						<= 5.0 MPH		
					Transmission gear			
						HalfCylDisabledTransGr and		
						HalfCylDisabledTransGrDevic		
						eControl (when in device		
						control) - See details on		
						Supporting Tables Tab		
						(P3400 Section)		
					PRNDL state	(
						HalfOrdDisabledDDNDL and		
						HalfCylDisabledPRNDL and		
						HalfCylDisabledPRNDLDevic		
						eControl tables (when in		
						device control) - See details		
						on Supporting Tables Tab		
					.	(P3400 Section)		
					Ignition voltage	< 11.0 or > 32.0 Volts		
					Engine coolant	< 40.0 or > 132.0 Deg C		
					Vehicle speed	< 9.3 MPH		
					Brake booster vacuum			
					1	< 41.0 kPa		
					Filtered engine vacuum			
					1	> HalfCylToAllCylVacuum or		
	1				1			
					1	EcoHalfCylToAllCylVacuum		
					1	(in Eco mode) - See details		
					1	on Supporting Tables Tab		
	1	1	1	1	1	(P3400 Section) for 0 sec.		

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					ETC Power management			
					mode			
						Active		
					Converter overtemp			
					protect			
						Active		
					Hot coolant mode	Active		
					Engine running	= False		
					Engine overspeed			
					protection	Active		
					Engine metal overtemp			
					protect	Active		
					Cat. temp low	Active		
					POSD Intrusive	Active		
					FWD	In low range		
					Engine misfire	Detected		
					Heater performance	Active		
					POPD Intrusive	Active	1	
					No office PTOIS	Fault lave all a se		
					No active DTC's	Fault bundles:		
						Map_SensorFA		
						Vahiala Consad Consag Turan		
						VehicleSpeedSensorError ECT_Sensor_FA		
						EOP_Sensor_FA		
						PowertrainRelayFault		
						BrakeBoosterSensorFA		
						CrankSensorFA		
						CamSensorFA		
						IAT_SensorFA		
						IIAT_OEIISOITA		
						CylnderDeacDriverTFTKO		
						FourWheelDriveLowStateVali		
						In our writeel Dilve Low State vall		
						ľ		
						EngineTorqueEstInaccurate		
						3 1 1 1 1 1 1		
						TransmissionGearDefaulted		
						EnginePowerLimited		
1								

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Cylinder 1 Deactivation Solenoid Control Circuit	P3401	Checks the Solenoid Control Circuit electrical integrity for cylinder #1	The ECM detects that commanded state of driver and actual state of the control circuit do not match. (Short to ground, short to voltage, open circuit)		Engine RPM Ignition Voltage Diagnostic enabled/ disabled	>= 400.0 RPM <= 32.0 and >= 11.0 Volts Enabled	20 failures out of 25 samples Performed every 250 msec	2 trip(s) Type B
Cylinder 4 Deactivation Solenoid Control Circuit	P3425	Checks the Solenoid Control Circuit electrical integrity for cylinder #4	The ECM detects that commanded state of driver and actual state of the control circuit do not match. (Short to ground, short to voltage, open circuit)		Engine RPM Ignition Voltage Diagnostic enabled/ disabled	>= 400.0 RPM <= 32.0 and >= 11.0 Volts Enabled	20 failures out of 25 samples Performed every 250 msec	2 trip(s) Type B
Cylinder 6 Deactivation Solenoid Control Circuit	P3441	Checks the Solenoid Control Circuit electrical integrity for cylinder #6	The ECM detects that commanded state of driver and actual state of the control circuit do not match. (Short to ground, short to voltage, open circuit)		Engine RPM Ignition Voltage Diagnostic enabled/ disabled	>= 400.0 RPM <= 32.0 and >= 11.0 Volts Enabled	20 failures out of 25 samples Performed every 250 msec	2 trip(s) Type B
Cylinder 7 Deactivation Solenoid Control Circuit	P3449	Checks the Solenoid Control Circuit electrical integrity for cylinder #7	The ECM detects that commanded state of driver and actual state of the control circuit do not match. (Short to ground, short to voltage, open circuit)		Engine RPM Ignition Voltage Diagnostic enabled/ disabled	>= 400.0 RPM <= 32.0 and >= 11.0 Volts Enabled	20 failures out of 25 samples Performed every 250 msec	2 trip(s) Type B
Control Module Communication Bus A Off	U0073	This DTC monitors for a BUS A off condition	Bus off failures out of these samples	≥ 5 counts ≥ 5 counts	CAN hardware is bus OFF for Diagnostic enable timer	> 0.1125 seconds > 3.0000 seconds	Diagnostic runs in 12.5 ms loop	2 Trip(s) Type B

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Lost Communication With TCM	U0101	This DTC monitors for a loss of communication with the transmission control module	Message is not received from controller for this many counts	12 counts	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	The fail diagnostic runs in the 6.25 ms loop with pass conditions reported to the DFIR in the 1000ms loop.	
			out of these samples	12 counts	Power mode is RUN			Type B
					Communication bus is not OFF			
					or is typed as a C code			
					Normal Communication is enabled			
					Normal Transmit capability is TRUE			
					The diagnostic system is not disabled			
					The bus has been on for	> 3.0000 seconds		
					A message has been selected to monitor.			
Lost Communication with Transfer Case Control Module	U0102	This DTC monitors for a loss of communication with the transfer case control module	Message is not received from controller for this many counts	12 counts	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	The fail diagnostic runs in the 6.25 ms loop with pass conditions reported to the DFIR in the 1000ms loop.	2 Trip(s)
			out of these samples	12 counts	Power mode is RUN			Туре В
					Communication bus is not OFF			
					or is typed as a C code			
					Normal Communication is enabled			
					Normal Transmit capability is TRUE			

-		Monitor Strategy	Malfunction	Threshold	Secondary	Enable		MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					The diagnostic system is not disabled			
					The bus has been on for	> 3.0000 seconds		
					A message has been selected to monitor.			
Lost Communication With Fuel Pump Control Module	U0109	This DTC monitors for a loss of communication with the fuel pump control module	Message is not received from controller for this many counts	12 counts	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	The fail diagnostic runs in the 6.25 ms loop with pass conditions reported to the DFIR in the 1000ms loop.	2 Trip(s)
			out of these samples	12 counts	Power mode is RUN			Туре В
					Communication bus is not OFF			
					or is typed as a C code			
					Normal Communication is enabled			
					Normal Transmit capability is TRUE			
					The diagnostic system is not disabled			
					The bus has been on for	> 3.0000 seconds		
					A message has been selected to monitor.			
Lost Communication With Anti-Lock Brake System (ABS) Control Module	U0121	This DTC monitors for a loss of communication with the ABS control module.	Message is not received from controller for this many counts	12 counts	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	The fail diagnostic runs in the 6.25 ms loop with pass conditions reported to the DFIR in the 1000ms loop.	1 Trip(s)
			out of these samples	12 counts	Power mode is RUN			Type C
					Communication bus is not OFF			Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
					or is typed as a C code			
					Normal Communication is			
					enabled			
					Normal Transmit			
					capability is TRUE			
					The diagnostic system is			
					not disabled			
					The bus has been on for	> 3.0000 seconds		
					A message has been			
					selected to monitor.			
Lost	U0140	This DTC monitors for	Message is not	12 counts	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	The fail	1 Trip(s)
Communication		a loss of	received from				diagnostic runs in	
With Body		communication with	controller for this				the 6.25 ms loop	
Control Module		the Body Control	many counts				with pass conditions	
		Module.					reported to the	
							DFIR in the	
							1000ms loop.	
			out of these samples	12 counts	Power mode is RUN		10001113 100р.	Type C
			out of these samples	12 Counts	Fower mode is Non			Type C
					Communication bus is not			Special
					OFF			Type C
					or is typed as a C code			
					Normal Communication is			
					enabled			
				+	Normal Transmit			
					capability is TRUE			
					The diagnostic system is			†
					not disabled			
					The bus has been on for	> 3.0000 seconds		
					A message has been			
					selected to monitor.			
			<u> </u>		Selected to Monitor.	l .	1	

Component/ System			Secondary Parameters	Enable Conditions	Time Required	MIL illum.		
Lost Communication with	U1040	This DTC monitors for a loss of communication over	Class2 message not received from module for	>= 10 seconds	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	Diagnostic runs in 1000 ms loop	1 Trip(s)
Brake/Traction		the Class2 bus with the			Power mode is RUN			Type C
Controller - Device \$28 (Only		Brake/Traction (Device \$28) Control Module.			The diagnostic system is not disabled			Special Type C
used for ClassII Onboard Communication based Vehicles)					The bus has been on for	> 3.0000 seconds		
Lost Communication with Brake/Traction Controller -	U1041	This DTC monitors for a loss of communication over the Class2 bus with the		>= 10 seconds	Run/Crank Voltage	11 volts ≤ Voltage ≤ 32 volts	Diagnostic runs in 1000 ms loop	1 Trip(s)
Device \$29(Only		Brake/Traction (Device \$29) Control Module.			Power mode is RUN			Type C
used for ClassII Onboard		φ20) Control Module.			The diagnostic system is not disabled			Special Type C
Communication based Vehicles)					The bus has been on for	> 3.0000 seconds		

ECM Supporting Tables

DONGE	D2007	D2000	D2000	EADD

Cell Accum Min

					Bank1	Bank2	Bank1 Light	Bank2 Light	Bank1	Bank2
Post O2 Air Flow Mode	e Bank1 Decel	Bank2 Decel	Bank1 Idle	Bank2 Idle	Cruise	Cruise	Accel	Accel	Heavy Accel	Heavy Accel
Cell Accum Min Count (10 counts = 1 sec.)	300	300	300	300		300	300 30	0 300	300	300

Integral Offset Max

Post O2 Air Flow Mode Decel Idle Cruise Light Accel Heavy Accel Post O2 Integral Offset Max [mV] 0 0 0 0 0 0

Integral Offset Min

Post O2 Air Flow Mode Decel Idle Cruise Light Accel Heavy Accel Post O2 Integral Offset Min [mV] 0 0 0 0 0 0

O2 Lean Thresh

					Bank1	Bank2	Bank1 Ligi	t Bank2 Light	Bank1	Bank2
Post O2 Airflow Mode Cell Ba	nk1 Decel Ba	ank2 Decel Bank	1 Idle	Bank2 Idle	Cruise	Cruise	Accel	Accel	Heavy Accel	Heavy Accel
O2 Lean Threshold [mV]	600	600	600	600)	600	600 6	00 600	600	600

O2 Rich Thresh

						Bank1	Bank2	Bank1	Light I	Bank2 Light	Bank1	Bank2
	Post O2 Airflow Mode 0	Cell Bank1 Decel	Bank2 Decel	Bank1 Idle	Bank2 Idle	Cruise	Cruise	Accel		Accel	Heavy Accel	Heavy Acce
O2 Rich Threshold	[mV]	800	800	800	800		750	750	810	810	810	810

Out Of Window Count

Post O2 Airflow Mode Cell Decel Idle Cruise Light Accel Heavy Accel Out of Window Count (10 counts = 1 sec.) 0 0 0 0 0 0

Selected Cells

				Bank1	Bank2	Bank1 Light	Bank2 Light	Bank1	Bank2
Post O2 Airflow Mode Cell	Bank1 Decel Bank2	Decel Bank1 Id	le Bank2 Idle	Cruise	Cruise	Accel	Accel	Heavy Accel	Heavy Accel
Post O2 Airflow Mode Selected Cell	0	0	0	0	1	1 1	1	1	1
0 if not selected 1 if selected									

HV Post Low

						Bank1	Bank2	Bank1	Light E	Bank2 Light	Bank1	Bank2
	Post O2 Airflow Mode Cell	Bank1 Decel	Bank2 Decel B	lank1 Idle	Bank2 Idle	Cruise	Cruise	Accel	Α	Accel	Heavy Accel	Heavy Accel
KaFAPD_U_HV_F	PO2_FiltLoThresh	625	625	625	625	5	625	625	625	625	625	625

HV Post High

					Bank1	Bank2	Bank1 Ligi	nt Bank2 Light	Bank1	Bank2
Post O2 Airflow Mode C	Cell Bank1 Decel I	Bank2 Decel	Bank1 Idle	Bank2 Idle	Cruise	Cruise	Accel	Accel	Heavy Accel	Heavy Accel
KaFAPD U HV PO2 FiltHiThresh	775	775	775	775		725	725 7	85 78	785	785

HV Integral Offset Low

					Bank1	Ba	ank2	Bank1 Light	Bank2 Light	Bank1	Bank2
Post O2 Airflow Mode Ce	II Bank1 Decel I	Bank2 Decel	Bank1 Idle	Bank2 Idle	Cruise	Cr	ruise	Accel	Accel	Heavy Accel	Heavy Accel
KaFAPD U HV PO2 IntOffLoThresh	-115	-115	-115	-115		-365	-365	-365	-365	-365	-365

HV Integral Offset High

					Bank1	Bank2	Bank1 Ligh	it Bank2 Light	Bank1	Bank2
Post O2 Airflow Mode O	Cell Bank1 Decel Ba	ink2 Decel Ba	ank1 Idle	Bank2 Idle	Cruise	Cruise	Accel	Accel	Heavy Accel	Heavy Accel
KaFAPD U HV PO2 IntOffHiThresh	105	105	105	105		355	355 35	55 355	355	355

Post O2 Filt Coefficient

		Bank 1	Bank 2								
	Bank and Index	Index 0	Index 0	Index 1	Index 1	Index 2	Index 2	Index 3	Index 3	Index 4	Index 4
Filter Coefficient		0.0050	0.0050	0.0050	0.0050	0.0050	0.0050	0.0050	0.0050	0.0050	0.0050
Current Filtered Post O2 Volta	ge	0	0	500	500	600	600	700	700	800	800

ECM Supporting Tables

P0068: MAP / MAF / TPS Correleation									
		X-axis is TPS	S (%)						
		Data is MAP	threshold (kPa	1)					
X-axis	5.0003	10.0006	14.9994	19.9997	25.0000	30.0003	35.0006	39.9994	99.9985
Data	26.3984	23.3359	20.2734	19.1484	18.0234	13.7813	100.0000	100.0000	100.0000
		X axis is TPS	S (%)						
			threshold (grai	ms/sec)					
X-axis	5.0003	10.0006	14.9994	19.9997	25.0000	30.0003	35.0006	39.9994	99.9985
Data	17.6250	20.6016	23.5781	24.0938	34.6406	40.6641	255.0000	255.0000	255.0000
		Vi- i- F	: 0 /DE	N. 4.)					
			ine Speed (RF						
X-axis	600.00	1400.00	MAF vs RPM (2200.00	3000.00	3800.00	4600.00	5400.00	6200.00	7000.00
Data	25.0000	60.0000	100.0000	140.0000	180.0000	220.0000	250.0000	280.0000	300.0000
Data	25.0000	60.0000	100.0000	140.0000	180.0000	220.0000	250.0000	280.0000	300.0000
		X axis is Batt	ery Voltage (V)					
			MAF vs Voltag						
X-axis	6.00	7.00	8.00	9.00	10.00	11.00	12.00	13.00	14.00
Data	0.0000	18.0000	40.0000	75.0000	135.0000	250.0000	500.0000	500.0000	500.0000

P1682: Ignition Voltage Correleation

X-axis is IAT (DegC) Data is Voltage threshold (V)

X-axis 23.0000 85.0000 95.0000 105.0000 Data 7.0000 8.6992 10.0000

P0325/P0330 OpenCircuitThresh

Engine Speed (RPM): OpenCircuitThresh:	500	1000	1500	2000	2500	3000	3500	4000
	9	15	25	33	48	85	85	85
Engine Speed (RPM): OpenCircuitThresh:	4500	5000	5500	6000	6500	7000	7500	8000
	85	85	85	85	85	85	85	85

P0326 Knock Detection Enabled Factors:

FastRtdMax:

X - axis = Engine Speed (RPM) Y - axis = Manifold Pressure (kPa)

	0	512	1024	1536	2048	2560	3072	3584	4096	4608	5120	5632	6144	6656	7168	7680	8192
20	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
30	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
40	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
50	0.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
60	0.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
70	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
80	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
90	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
100	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
110	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
120	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
130	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
140	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
150	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
160	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
170	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
180	0.0	6.0	8.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0

Knock Detection Enabled Factors:	Knock Detect	ion Enabled =	: FastAttackR	ate * FastAtta	ckCoolGain * F	astAttackBa	roGain								
	Tanoon Dottoo		T dob titaon ti			add madned									
	RPM:	0	512	1024	1536	2048	2560	3072	3584	4096					
FastAttackRate:	Γ	3.00	3.00	3.00	3.00	3.00	3.00	3.00	3.00	3.00					
	<u>-</u>														
	RPM:	4608	5120	5632	6144	6656	7168	7680	8192						
FastAttackRate:		3.50	3.50	3.50	3.50	3.50	3.50	3.50	3.50						
	ECT (deg. C):	-40	-30	-20	-10	0	10	20	30	40					
	FastAttack	0.00	0.00	0.00	0.00	0.00	0.00	0.25	0.50	0.75					
	CoolGain:														
	ECT (deg. C):	50	60	70	80	90	100	110	120						
	FastAttack	1.00	1.00	1.00	1.00	1.00	1.00	1.10	1.20						
	CoolGain:														
	Baro:	55.00	61.25	67.50	73.75	80.00	86.25	92.50	98.75	105.00					
	FastAttack	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00					
	BaroGain:									<u> </u>					
P0327/P0332 ShortLowThresh															
	Engine Oil Te	mp (dea C):	90	95	100	105	110	115	120	125					
		wThreshSig	2.59	2.59	2.59	2.59	2.59	2.59	2.59	2.59					
	ShortLov	wThreshRet	2.69	2.69	2.69	2.69	2.69	2.69	2.69	2.69					
	F : 01.F	(1 0)	400	405	440		450	4==	400						
	Engine Oil Te	wThreshSig	130 2.59	135 2.44	140 2.29	145 2.14	150 1.98	155 1.83	160 1.68						
		wThreshRet	2.69	2.38	2.29	1.77	1.47	1.16	0.86						
December of Alitti	0		2.00	2.00	2.00			0	0.00						
P0328P0333 ShortHiThresh															
Engine Oil Temperature (deg C):	Engine Oil Te	mp (dea C):	90	95	100	105	110	115	120	125					
gp (g -).	Shorth	liThreshSig	4.58	4.58	4.58	4.58	4.58	4.58	4.58	4.58					
	Shorth	liThreshRet	6.66	6.66	6.66	6.66	6.66	6.66	6.66	6.66					
	Engine Oil Te	mn (dea C):	130	135	140	145	150	155	160						
		liThreshSig	4.58	4.58	4.58	4.58	4.58	4.58	4.58						
		liThreshRet	6.66	6.66	6.66	6.66	6.66	6.66	6.66						
		-					*								
Tables supporting P219A and P219B D	iagnostics:														
Tables supporting F213A and F213B D	nagnostics.			KtOX	YD_cmp_AFI	M LnathThi	rsh1								
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500
, ,	40 90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000

				KtOXY	D_cmp_AFIN	I_LngthThrsh	11										
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000
80	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000
125	90000	90000	90000	90000	90000	90000	90000	90000	90000	6000	6000	6000	90000	90000	90000	90000	90000
160	90000	90000	90000	90000	90000	90000	90000	90000	90000	6000	6000	6000	90000	90000	90000	90000	90000
200	90000	90000	90000	90000	90000	90000	90000	90000	90000	6000	6000	12208	12208	90000	90000	90000	90000
240	90000	4496	4496	4496	90000	90000	90000	90000	11776	11776	12208	12208	12208	90000	90000	90000	90000
280	90000	4496	4496	4496	11632	11632	90000	90000	11776	11776	13040	12224	12224	90000	90000	90000	90000
320	90000	4784	4784	8208	11632	11280	12528	14320	90000	13456	15136	13216	13216	90000	90000	90000	90000
360	90000	4784	4784	11840	12448	10944	12528	14320	14320	13056	11920	10704	10704	90000	90000	90000	90000
400	90000	90000	11216	11216	13376	12928	15648	14992	13056	13056	9936	8384	8384	90000	90000	90000	90000
440	90000	10160	10112	10064	12128	11776	13056	90000	14400	13040	9008	9456	9456	90000	90000	90000	90000
480	90000	10160	10160	9168	11168	11184	11744	15376	15776	13488	9584	9040	9040	90000	90000	90000	90000
520	90000	10608	10608	12176	11840	10256	13760	18576	9264	9136	11440	10512	10512	90000	90000	90000	90000
560	90000	10624	10624	13408	12528	9808	11184	8912	8608	9392	17680	10240	10240	90000	90000	90000	90000
640	90000	9552	9552	11616	11856	10240	11632	8752	10896	11808	18032	9024	9024	90000	90000	90000	90000
720	90000	9552	9552	10704	11856	10240	11632	8752	10896	11808	18032	9024	9024	90000	90000	90000	90000
800	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000

AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
80	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
125	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
160	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
200	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
240	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
280	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
320	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
360	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
400	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
440	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
480	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
520	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
560	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
640	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
720	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
800	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000

				KtOXY	D_cmp_AFIN	_LngthThrsl	h2										
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	90000	90000	90000	90000	90000	90000	90000	20288	20288	20288	90000	90000	90000	90000	90000	90000	90000
80	90000	90000	90000	90000	90000	90000	90000	20288	20288	20288	90000	90000	90000	90000	90000	90000	90000
125	90000	90000	90000	90000	90000	90000	90000	15744	15744	11872	6752	6752	90000	90000	90000	90000	90000
160	90000	90000	90000	11664	11664	9760	9584	11920	11184	11872	6752	6752	90000	90000	90000	90000	90000
200	90000	7280	7280	11888	11664	9760	9584	12656	14176	15200	20304	19024	17728	90000	90000	90000	90000
240	90000	7280	7280	12128	13440	11568	12544	14560	17664	14160	16656	17728	17728	90000	90000	90000	90000
280	90000	4672	4672	14112	12720	13776	13856	16768	15744	14784	16608	16464	16464	90000	90000	90000	90000
320	90000	4384	4384	11888	13552	16352	15696	18736	18112	13856	16096	15280	15280	90000	90000	90000	90000
360	90000	10400	10400	13536	13280	13440	14096	15584	13360	13488	22144	13600	13600	90000	90000	90000	90000
400	90000	13344	13344	13024	17360	16864	22448	14832	22944	16672	11504	10704	10704	90000	90000	90000	90000
440	90000	9888	9888	17696	18528	13264	19184	19376	20080	12240	13072	12176	12176	90000	90000	90000	90000
480	90000	11008	11008	10192	12176	14080	15680	16288	15904	15472	12272	12736	12736	90000	90000	90000	90000
520	90000	9952	9952	11888	13456	12080	17648	19536	9328	11952	12640	12256	12256	90000	90000	90000	90000
560	90000	11456	11456	15008	13792	12064	12608	10160	10560	13056	13440	14160	14160	90000	90000	90000	90000
640	90000	11792	11792	15536	15472	12816	12464	11184	13104	13168	16160	15168	15168	90000	90000	90000	90000
720	90000	11792	11792	15536	15472	12816	12464	11184	13104	13168	16160	15168	15168	90000	90000	90000	90000
800	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000	90000

			KtOXYD	_cmp_AFIM_	LngthThrsh2	_DoD (AFM a	applications of	only)									
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
80	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
125	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
160	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
200	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
240	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
280	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
320	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
360	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
400	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
440	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
480	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
520	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
560	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
640	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
720	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000
800	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000	100000

				KtOX	YD_K_AFIM_	QualFactor1											
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
80	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
125	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
160	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
200	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
240	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.75	0.00	0.00	0.00	0.00	0.00
280	0.00	0.00	0.85	0.00	0.00	0.00	0.00	0.00	0.00	0.75	0.00	0.80	0.00	0.00	0.00	0.00	0.00
320	0.00	0.00	0.80	0.00	0.75	0.00	0.00	0.00	0.00	0.00	0.75	0.80	0.00	0.00	0.00	0.00	0.00
360	0.00	0.00	0.00	0.00	0.75	0.75	0.75	0.75	0.00	0.00	0.00	0.85	0.00	0.00	0.00	0.00	0.00
400	0.00	0.00	0.00	0.75	0.75	0.00	0.75	0.00	0.00	0.75	0.85	0.75	0.00	0.00	0.00	0.00	0.00
440	0.00	0.00	0.00	0.80	0.75	0.75	0.00	0.00	0.00	0.80	0.85	0.85	0.00	0.00	0.00	0.00	0.00
480	0.00	0.00	0.75	0.80	0.85	0.80	0.75	0.00	0.80	0.80	0.85	0.85	0.00	0.00	0.00	0.00	0.00
520	0.00	0.00	0.75	0.75	0.85	0.85	0.80	0.75	0.90	0.85	0.85	0.85	0.00	0.00	0.00	0.00	0.00
560	0.00	0.00	0.80	0.75	0.80	0.90	0.85	0.90	0.90	0.85	0.75	0.85	0.00	0.00	0.00	0.00	0.00
640	0.00	0.00	0.80	0.00	0.75	0.85	0.85	0.90	0.85	0.85	0.75	0.90	0.00	0.00	0.00	0.00	0.00
720	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
800	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

KtOXYD_K_AFIM_QualFactor1_DoD (AFM applications only) AvaFlow / AvaRPM 250 500 750 1000 1250 1500 1750 2000 2250 250 3000 3500 4000 4500 5000 600																	
AvgFlow / AvgRPM	2	250 5	00 750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
4	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
8	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
12	5 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
16	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
20	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
24	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
28	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
32	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
36	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
40	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
44	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
48	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
52	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
56	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
64	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
72	0 0.	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
80	0	.00 0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

				KtO	XYD_K_AFIM	_QualFactor2	2										
AvgFlow / AvgRPM		250 50	0 750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
	40	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	80	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
1	125	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
1	160	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.80	0.80	0.90	0.00	0.00	0.00	0.00	0.00	0.00
	200	0.00	0.00	0.00	0.75	0.85	0.80	0.75	0.00	0.80	0.75	0.00	0.00	0.00	0.00	0.00	0.00
2	240	0.00	0.80	0.80	0.80	0.85	0.85	0.80	0.80	0.80	0.80	0.75	0.00	0.00	0.00	0.00	0.00
2	280	0.00	0 1.00	0.75	0.75	0.75	0.75	0.80	0.80	0.85	0.85	0.80	0.00	0.00	0.00	0.00	0.00
	320	0.00	0.90	0.80	0.85	0.80	0.80	0.75	0.85	0.85	0.85	0.85	0.00	0.00	0.00	0.00	0.00
	360	0.00	0.85	0.80	0.90	0.85	0.85	0.85	0.90	0.85	0.80	0.75	0.00	0.00	0.00	0.00	0.00
	100	0.00	0 0.75	0.80	0.85	0.75	0.80	0.90	0.85	0.85	0.95	0.95	0.00	0.00	0.00	0.00	0.00
	140	0.00	0 0.75	0.80	0.85	0.90	0.85	0.75	0.85	0.95	0.95	0.95	0.00	0.00	0.00	0.00	0.00
	180	0.00	0.90	0.90	0.90	0.90	0.90	0.90	0.95	0.95	0.95	0.95	0.00	0.00	0.00	0.00	0.00
5	520	0.00	0.90	0.75	0.95	0.90	0.90	0.75	1.00	0.95	0.95	0.95	0.00	0.00	0.00	0.00	0.00
	60	0.00	0.90	0.85	0.75	0.75	0.90	1.00	1.00	0.90	0.95	0.95	0.00	0.00	0.00	0.00	0.00
(640	0.00	0.90	0.90	0.85	0.85	0.75	0.95	0.95	0.95	0.90	0.95	0.00	0.00	0.00	0.00	0.00
7	720	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	son i	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

ECM Supporting Tables

	KtOXYD_K_AFIM_QualFactor2_DoD (AFM applications only) AvaFlow / AvaPPM 250 500 750 1000 1250 1500 1750 2000 2250 2500 2750 3000 3500 4000 4500 5000 6																
AvgFlow / AvgRPM	250	500	750	1000	1250	1500	1750	2000	2250	2500	2750	3000	3500	4000	4500	5000	6000
40	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
80	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
125	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
160	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
200	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
240	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
280	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
320	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
360	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
400	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
440	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
480	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
520	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
560	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
640	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
720	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
800	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Tables supporting Clutch Diagnostics:

	EngTorqueT	hreshold Tab	le			axis is Perce	nt Clutch Pe	dal Position,	0 = bottom of	travel
Axis	0	6.2485	12.497	18.7455	24.994	31.2425	37.491	43.7395	49.988	56.2365
Curve	10.0	10.5	14.0	18.5	27.0	35.0	40.0	51.5	80.0	87.0
Axis	62.485	68.7335	74.982	81.2305	87.479	93.7275	99.976	,		
Curve	-8192.0	-8192.0	-8192.0	-8192.0	-8192.0	-8192.0	-8192.0			

P0806

	ResidualErro	orEnableLow	Table			axis is Gear		
Axis	1st	2nd	3rd	4th	5th	6th	rev	neutral
Curve	100.0	100.0	100.0	100.0	100.0	100.0	100.0	100.0

P0806

	ResidualErro	orEnableHigh	Table			axis is Gear		
Axis	1st	2nd	3rd	4th	5th	6th	rev	neutral
Curve	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Tables supporting Clutch Pedal Position Status (analog Clutch Pedal Position Sensor applications only):

Clutch Pedal Top of Travel Achieved criteria

The clutch pedal Top of Travel state will transition from FALSE to TRUE when the following occurs:

Clutch Pedal Position <= 88 % each count is equal to 12.5ms > 3 counts

Clutch Disengaged criteria

The clutch state will transition from engaged to disengaged when the following occurs:

Clutch Pedal Position <= 50 %

each count is equal to 12.5ms

Clutch Pedal Bottom of Travel Achieved criteria

The clutch pedal Bottom of Travel state will transition from FALSE to TRUE when the following occurs:

Clutch Pedal Position < 16 %

each count is equal to 12.5ms

P0171 & P0174 (LONG TERM ONLY)	Long Term Trin	ı Lean (Lean I	Fail threshold	1)						
% Ethanol	0.00	6.25	12.50	18.75	25.00	31.25	37.50	43.75	50.00	56.25
Long Term Fuel Trim Lean Threshold	1.245	1.245	1.245	1.245	1.245	1.245	1.245	1.245	1.245	1.245
% Ethanol	62.50	68.75	75.00	81.25	87.50	93.75	100.00			
Long Term Fuel Trim Lean Threshold	1.245	1.245	1.245	1.245	1.245	1.245	1.245			
P0172 & P0175 (LONG TERM ONLY)	Non Purge Rich	Limit (Rich F	ail threshold)						
% Ethanol	0.00	6.25	12.50	18.75	25.00	31.25	37.50	43.75	50.00	56.25
Long Term Fuel Non-Purge Rich Threshold	0.755	0.755	0.755	0.755	0.755	0.755	0.755	0.755	0.755	0.755
% Ethanol	62.50	68.75	75.00	81.25	87.50	93.75	100.00			
Long Term Fuel Non-Purge Rich Threshold	0.755	0.755	0.755	0.755	0.755	0.755	0.755			

FCM Supporting Tables

							ECM S	upport	ing Ta	bles						
			rs Rich Intrus													
% Ethanol Long Term Fuel Purge Rich Threshold							37.50 0.760									
% Ethanol																
Long Term Fuel Purge Rich Threshold	0.760	0.760	0.760	0.760	0.760	0.760	0.760									
		The following		s the Long F	uel Trim cells	s utilized for F	ASD diagno	sis (cells ide	ntified with a	"Yes" are en	abled, and wi	th a "NO" are	e disabled)			
	ū		ū	CeFADR e CeFADR e	CeFADR e	CeFADR e	CeFADR e	CeFADR e	CeFADR e	CeFADR e	_ CeFADR_e_					
Cell I.D.	Cell00_Purg	Cell01_Purg	Cell02_Purg	Cell03_Purg	Cell04_Purg		Cell06_Purg	Cell07_Purg	Cell08_Purg	Cell09_Purg	Cell10_Purg	Cell11_Purg		Cell13_Purg	Cell14_Purg	Cell15_Purg OffDecel
FASD Cell Usage	CeFADD_e_ SelectedPur	CeFADD_e_ NonSelecte	CeFADD_e_ SelectedNo	CeFADD_e_ SelectedNo	CeFADD_e_ SelectedNo	CeFADD_e SelectedNo	_ CeFADD_e SelectedNo	_ CeFADD_e_ SelectedNo	_ CeFADD_e SelectedNo	CeFADD_e_ NonSelecte						
FASD Enabled in Cell?	geCell	geCell Yes	geCell Yes	geCell Yes	geCell Yes	geCell Yes	geCell Yes	dCell NO	nPurgeCell Yes	nPurgeCell Yes	nPurgeCell Yes	nPurgeCell Yes	nPurgeCell Yes	nPurgeCell Yes	nPurgeCell Yes	dCell NO
P0411																
Axis	SL Threshol	ld Bank 1 Tab	6.0	9.0	axis is avera	age engine ai	flow during t	test in gm/se 21.0	24.0	27.0	1					
Curve	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0	25.0						
Axis Curve	30.0	33.0 25.0	36.0 25.0	39.0 25.0	42.0 25.0	45.0 25.0	48.0 25.0]								
	25.0	25.0	25.0	25.0	25.0	25.0	25.0	J								
P0411	Phase 1 Bar	o Test Weigh	nt Factor				axis is Baro	in Kna								
Axis	40	50	60	70	80	90	100	110	120]						
Curve	0.0	0.0	0.5	1.0	1.0	1.0	1.0	1.0	0.0							
P0411	DI															
Axis	0.0	F Test Weigh 3.0	6.0	9.0	12.0	15.0	18.0	ne airflow in g	24.0	27.0	1					
Curve	0.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0]					
Axis Curve	30.0 1.0	33.0 0.5	36.0 0.0	39.0 0.0	42.0 0.0	45.0 0.0	48.0 0.0									
	1.0	0.5	0.0	0.0	0.0	0.0	0.0	1								
P0411	Phase 1 Sys	tem Volt Tes	t Weight Fact	or			axis is syste	m volts								
Axis	5.0	6.0	7.0	8.0	9.0	10.0	11.0	12.0	13.0	14.0]					
Curve	0.0	0.0	0.0	0.0	0.0	0.5	8.0	1.0	1.0	1.0]					
	15.0 1.0	16.0 1.0	17.0 0.8	18.0 0.5	19.0 0.5	20.0 0.5	21.0 0.5	1								
P0411								•								
P0411			Weight Facto				axis is Deg			_						
Axis Curve	-30 0.0	- 20	-10 0.0	0	10	20 1.0	30 1.0	40 1.0	50							
	0.0	0.0	0.0	0.5	1.0	1.0	1.0	1.0	1.0	_						
P2431	Baro Skewe	d Sensor We	ight Factor		axis is dista	nce traveled	from last Bar	o undate in k	(m							
Axis	0.0	2.0	4.0	6.0	8.0	10.0	12.0	14.0	16.0	18.0]					
Curve	1.0	0.8	0.5	0.3	0.0	0.0	0.0	0.0	0.0	0.0	_					
	20.0 0.0	22.0 0.0	24.0 0.0	26.0 0.0	28.0 0.0	30.0 0.0	32.0 0.0									
P0.440	0.0	0.0	0.0	0.0	0.0	0.0	0.0	1								
P2440	Bank 1 Valv	e Pressure E	rror			axis is weigl	nted time in s	econds								
Axis	0	1	2	3 -4.0	4	5	6	7	8							
Curve	-6.0	-6.0	-5.0	-4.0	-3.0	-3.0	-3.0	-3.0	-3.0	J						
P2440	Phase 2 Bar	o Test Weigh	nt Factor				axis is Baro	in Kna								
Axis	40	50	60	70	80	90	100	110	120]						
Curve	0.0	0.0	0.5	1.0	1.0	1.0	1.0	1.0	0.0	1						

P2440										
		Test Weight		0.0	40.0	45.0		e airflow in gm		07.0
Axis Curve	0.0	3.0 1.0	6.0 1.0	9.0 1.0	12.0 1.0	15.0 1.0	18.0 1.0	21.0	24.0 1.0	27.0 1.0
								1.0	1.0	1.0
Axis Curve	30.0 1.0	33.0 1.0	36.0 1.0	39.0 1.0	42.0 0.5	45.0 0.0	48.0 0.0			
Curve	1.0	1.0	1.0	1.0	0.5	0.0	0.0			
P2440										
		em Volt Test					axis is syster			
Axis	5.0	6.0	7.0	8.0	9.0	10.0	11.0	12.0	13.0	14.0
Curve	0.0	0.0	0.0	0.0	0.0	0.5	8.0	1.0	1.0	1.0
Axis	15.0	16.0	17.0	18.0	19.0	20.0	21.0			
Curve	1.0	1.0	0.8	0.5	0.5	0.5	0.5			
P2440										
	Phase 2 Amb	Temp Test V	Veight Factor				axis is Deg C			
Axis	-30	-20	-10	0	10	20	30	40	50	
Curve	0.0	0.0	0.0	0.5	1.0	1.0	1.0	1.0	1.0	
P2444										
	Bank 1 Pump	Pressure Er	ror			axis is weigh	nted time in se	econds		
Axis	0	1	2	3	4	5	6	7	8	
Curve	11.2	11.2	11.2	11.2	11.2	11.2	11.2	11.2	11.2	
P1400 Detail										
KnIDLC_T_ECT_Axis										
Coolant Temperature	-11	-10	1	2	16	17	38	39	100	
KalDLC_n_CLO_ThrshOfst[CilDLR_DR]	4000	405	405	405	405	405	405	1000	1000	
RPM Offset to be considered Cat Light Off	1000	125	125	125	125	125	125	1000	1000	
KalDLC_n_CLO_ThrshOfst[CilDLR_PN]										
RPM Offset to be considered Cat Light Off	1000	125	125	125	125	125	125	1000	1000	
K-IDI O FDIDI-D-DNI										
KalDLC_n_EngDsrdBase[CilDLR_PN] Coolant Temperature	-40	-28	-16	-4	8	20	32	44	56	68
Base RPM	800	800	800	800	800	750	725	710	695	680
Coolant Temperature	80	92	104	116	128	140	152			
Base RPM	665	650	650	650	725	725	725			
<u>-</u>										
KalDLC_n_EngDsrdBase[CilDLR_DR]										
Coolant Temperature	-40	-28	-16	-4	8	20	32	740	56	68
Base RPM	800	800	800	800	800	750	725	710	695	680
Coolant Temperature	80	92	104	116	128 725	140	152			
Base RPM	665	650	650	650	725	725	725			
P0420 / P0430 Detail										
MinimumEngineRunTime										
Coolant Temp	40	50	60	70	80					
Engine Run Time	100	100	100	100	100					
MinCatTemp)	X AXIS PTS								
CATD_ExhaustWarmMin_Loc_0	575	0								
CATD_ExhaustWarmMin_Loc_1	575	1								
CATD_ExhaustWarmMin_Loc_2	575	2								
CATD_ExhaustWarmMin_Loc_3	575	3								
CATD_ExhaustWarmMin_Loc_4 CATD_ExhaustWarmMin_Loc_5	575 575	4 5								
CATD_ExhaustWarmMin_Loc_5 CATD_ExhaustWarmMin_Loc_6	575	6								
CATD_ExhaustWarmMin_Loc_7	575	7								
MinAirflowToWarmCatalyst	^									
Engine Coolant MinAirFlowToWrmCat	0 18	45 10	90 6							
ITIII I III IOW I OVVIIII OAL	10	10	6							

0101, P0106, P0121, P012B	, P1101: IFRD Residual We TPS Residu	al Weight Fac		RPM													
RPM	0	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	9000
	1.000	1.000	1.000	1.000	1.000	1.000	1.000	0.722	0.686	0.673	0.472	0.467	0.343	0.279	0.284	1.000	1.000
		al Weight Fac															
M	0	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	9000
	1.000	1.000	1.000	1.000	1.000	1.000	1.000	0.608	0.594	0.502	0.388	0.386	0.349	0.352	0.343	1.000	1.000
		al Weight Fac															
/sec	0.0	50.0	70.0	73.0	76.0	79.0	82.0	85.0	89.0	95.0	100.0	110.0	120.0	150.0	200.0	280.0	350.0
	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
		lual Weight Fa			1750	2052	0750	2052	0750	1050	1750	5050	5750	2052	0750	7050	0000
M	0	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	9000
	1.000	1.000 lual Weight Fa	0.828	0.921	0.972	1.000	1.000	0.708	0.723	0.660	0.491	0.477	0.439	0.427	0.401	1.000	1.000
	0	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	0000
M	1.000	1.000	1.000	1.000	1,000	1.000	1.000	0.656	0.903	0.850	0.449	0.436	0.401	0.390	0.364	1.000	9000
		idual Weight			1.000	1.000	1.000	0.000	0.903	0.000	0.449	0.430	0.401	0.390	0.304	1.000	1.000
M	O SCIAPT RES	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	9000
101	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
		idual Weight			1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
M	0	250	750	1250	1750	2250	2750	3250	3750	4250	4750	5250	5750	6250	6750	7250	9000
	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
						1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
			ector based o	on % of Boost													
Boost				on % of Boost 0.19		0.31	0.38	0.44	0.50	0.56	0.63	0.69	0.75	0.81	0.88	0.94	1.00
	0.00 1.000 , P1101: IFRD Residual We	0.06 1.000 ighting Factor	0.13 1.000	0.19 1.000 arged Applica	0.25 1.000	0.31 1.000	0.38 1.000	0.44 1.000	0.50 1.000	0.56 1.000	0.63 1.000	0.69 1.000	0.75 1.000	0.81 1.000	0.88 1.000	0.94 1.000	1.00 1.000
101, P0106, P0121, P012B	0.00 1.000 1.000 1.000 1.000	0.06 1.000 ighting Factor al Weight Fac 250 1.000	0.13 1.000 rs (Super Chator based on 750 1.000	0.19 1.000 arged Applica RPM 1250 1.000	0.25 1.000												9000
101, P0106, P0121, P012B	0.00 1.000 1.000 1.000 1.000	0.06 1.000 ighting Factor al Weight Fac 250	0.13 1.000 rs (Super Chator based on 750 1.000	0.19 1.000 arged Applica RPM 1250 1.000	0.25 1.000 tions only)	1.000	1.000	3250	1.000 3750	1.000	1.000	1.000 5250	1.000 5750	1.000 6250	1.000	7250	9000
101, P0106, P0121, P012B	0.00 1.000 1,000 1,000 1,000 1,000 MAF Residu 0	0.06 1.000 ighting Factor al Weight Fac 250 1.000 al Weight Fac 250	0.13 1.000 es (Super Chator based on 750 1.000 etor based on 750	0.19 1.000 arged Applica RPM 1250 1.000 n RPM 1250	0.25 1.000 tions only) 1750 1.000	1.000 2250 1.000 2250	1.000 2750 1.000 2750	3250 1.000 3250	3750 1.000 3750	1.000 4250 0.833 4250	1.000 4750 0.714 4750	1.000 5250 0.625 5250	1.000 5750 0.556 5750	1.000 6250 0.500 6250	1.000 6750 0.500 6750	7250 0.500 7250	9000 0.500
101, P0106, P0121, P012B M	0.00 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000	0.13 1.000 rs (Super Chator based on 750 1.000 rtor based on 750 1.000	0.19 1.000 arged Applica RPM 1250 1.000 n RPM 1250 0.833	0.25 1.000 tions only) 1750 1.000 1750 0.833	1.000 2250 1.000	1.000 2750 1.000	3250 1.000	3750 1.000	1.000 4250 0.833	1.000 4750 0.714	5250 0.625	5750 0.556	1.000 6250 0.500	1.000 6750 0.500	7250 0.500	9000 0.500
101, P0106, P0121, P012B M	0.00 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac	0.13 1.000 rs (Super Chotor based on 750 1.000 rtor based on 750 1.000 ttor Based on	0.19 1.000 arged Applica RPM 1250 1.000 n RPM 1250 0.833 n MAF Estima	0.25 1.000 tions only) 1750 1.000 1750 0.833 te	1.000 2250 1.000 2250 0.733	1.000 2750 1.000 2750 0.696	3250 1.000 3250 0.500	3750 1.000 3750 0.400	1.000 4250 0.833 4250 0.300	1.000 4750 0.714 4750 0.300	5250 0.625 5250 0.300	5750 0.556 5750 0.200	6250 0.500 6250 0.200	6750 0.500 6750 0.200	7250 0.500 7250 0.714	9000 0.500 9000 0.714
101, P0106, P0121, P012B M M	0.00 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.00	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0	0.13 1.000 rs (Super Ch. tor based on 750 1.000 rtor based or 750 1.000 rtor Based or 47.0	0.19 1.000 arged Applica RPM 1250 1.000 n RPM 1250 0.833 n MAF Estima 56.0	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0	2250 1.000 2250 0.733 79.0	2750 1.000 2750 0.696 93.0	3250 1.000 3250 0.500	3750 1.000 3750 0.400	4250 0.833 4250 0.300	1.000 4750 0.714 4750 0.300	5250 0.625 5250 0.300	5750 0.556 5750 0.200	1.000 6250 0.500 6250 0.200	6750 0.500 6750 0.200	7250 0.500 7250 0.714 431.0	9000 0.500 9000 0.714 510.0
101, P0106, P0121, P012B M M	0.00 1.000 1.000 1, P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000	0.13 1.000 ss (Super Chitor based on 750 1.000 stor based or 750 1.000 stor Based or 47.0 0.909	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 1 MAF Estima 56.0 0.836	0.25 1.000 tions only) 1750 1.000 1750 0.833 te	1.000 2250 1.000 2250 0.733	1.000 2750 1.000 2750 0.696	3250 1.000 3250 0.500	3750 1.000 3750 0.400	1.000 4250 0.833 4250 0.300	1.000 4750 0.714 4750 0.300	5250 0.625 5250 0.300	5750 0.556 5750 0.200	6250 0.500 6250 0.200	6750 0.500 6750 0.200	7250 0.500 7250 0.714	9000 0.500 9000 0.714 510.0
1101, P0106, P0121, P012B PM PM	0.00 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Residu	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iul Weight Fac	0.13 1.000 rs (Super Ch. tor based on 750 1.000 ttor based or 750 1.000 ttor Based or 47.0 0.909	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773	2250 1.000 2250 0.733 79.0 0.719	2750 1.000 2750 0.696 93.0 0.660	3250 1.000 3250 0.500 111.0 0.584	3750 1.000 3750 0.400 131.0 0.501	1.000 4250 0.833 4250 0.300 156.0 0.408	4750 0.714 4750 0.300 184.0 0.336	5250 0.625 5250 0.300 218.0 0.294	5750 0.556 5750 0.200 259.0 0.268	6250 0.500 6250 0.200 307.0 0.243	6750 0.500 6750 0.200 6750 0.200	7250 0.500 7250 0.714 431.0 0.191	9000 0.500 9000 0.714 510.0 0.159
101, P0106, P0121, P012B ^{PM} ^M	0.00 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP Residu 0.0 1.000 MAP Residu 0.0 1.000 MAP Residu 0.0 1.000	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 lual Weight Fac	0.13 1.000 rs (Super Ch. tor based on 750 1.000 rtor based on 750 1.000 tor Based on 47.0 0.909 actor based of	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 1 MAF Estima 56.0 0.836 0.836	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773	2250 1.000 2250 0.733 79.0 0.719	2750 1.000 2750 1.000 2750 0.696 93.0 0.660	3250 1.000 3250 0.500 111.0 0.584	3750 1.000 3750 0.400 131.0 0.501	1.000 4250 0.833 4250 0.300 156.0 0.408 4250	1.000 4750 0.714 4750 0.300 184.0 0.336 4750	5250 0.625 5250 0.300 218.0 0.294	5750 0.556 5750 0.200 259.0 0.268	1.000 6250 0.500 6250 0.200 307.0 0.243	1.000 6750 0.500 6750 0.200 363.0 0.219	7250 0.500 7250 0.714 431.0 0.191	9000 0.500 9000 0.714 510.0 0.159
101, P0106, P0121, P012B ^{PM} ^M	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 0.00 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.0 0.625	0.06 1.000 ighting Factor al Weight Fac 250 1.000 al Weight Fac 250 1.000 al Weight Fac 40.0 1.000 lual Weight Fac 250 0.625	0.13 1.000 rs (Super Ch. tor based on 750 1.000 ctor based or 750 1.000 ctor Based or 47.0 0.909 actor based or 750	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773	2250 1.000 2250 0.733 79.0 0.719	2750 1.000 2750 0.696 93.0 0.660	3250 1.000 3250 0.500 111.0 0.584	3750 1.000 3750 0.400 131.0 0.501	1.000 4250 0.833 4250 0.300 156.0 0.408	4750 0.714 4750 0.300 184.0 0.336	5250 0.625 5250 0.300 218.0 0.294	5750 0.556 5750 0.200 259.0 0.268	6250 0.500 6250 0.200 307.0 0.243	6750 0.500 6750 0.200 6750 0.200	7250 0.500 7250 0.714 431.0 0.191	9000 0.500 9000 0.714 510.0 0.159
1101, P0106, P0121, P012B PM PM n/sec	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0 0.055 MAP2 Resid	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iual Weight Fac 250 0.625	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based or 750 1.000 tor Based or 47.0 0.999 octor based or 750 0.625	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625	2250 1.000 2250 0.733 79.0 0.719 2250 0.625	2750 1.000 2750 0.696 93.0 0.660 2750 0.625	3250 1.000 3250 0.500 111.0 0.584 3250 0.714	3750 1.000 3750 0.400 131.0 0.501 3750 0.625	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357	7250 0.500 7250 0.714 431.0 0.191 7250 0.333	9000 0.500 9000 0.714 510.0 0.159 9000 0.313
101, P0106, P0121, P012B M M /sec	0.00 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0.1.000 MAF Residu 0.0.0 1.000 MAP1 Residu 0.0.025 MAP2 Residu 0.025	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iual Weight Fac 40.0 0.625 iual Weight Fac 250 0.625	0.13 1.000 s (Super Ch. tor based on 750 1.000 stor based or 750 1.000 stor Based or 47.0 0.909 stor based or 750 0.625 stor based or 750	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 1 MAF Estima 56.0 0.836 DI RPM 1250 0.625 DI RPM 1250	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625	2250 1.000 2250 0.733 79.0 0.719 2250 0.625	2750 1.000 2750 0.696 93.0 0.660 2750 0.625	3250 1.000 3250 0.500 111.0 0.584 3250 0.714	3750 1.000 3750 0.400 131.0 0.501 3750 0.625	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500	5250 0.625 5250 0.300 218.0 0.294 5250 0.455	5750 0.556 5750 0.200 259.0 0.268 5750 0.417	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250	9000 0.500 9000 0.714 510.0 0.159 9000 0.313
101, P0106, P0121, P012B M M M	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residual Name	0.06 1.000 ighting Factor at Weight Fac 250 1.000 at Weight Fac 250 1.000 at Weight Fac 250 1.000 at Weight Fac 40.0 1.000 lual Weight Fac 250 0.625 lual Weight Fac 250 0.556	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based or 750 1.000 tor Based or 47.0 0.909 totor based or 750 0.625 totor based or 750 0.556	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.625 on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625	2250 1.000 2250 0.733 79.0 0.719 2250 0.625	2750 1.000 2750 0.696 93.0 0.660 2750 0.625	3250 1.000 3250 0.500 111.0 0.584 3250 0.714	3750 1.000 3750 0.400 131.0 0.501 3750 0.625	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357	7250 0.500 7250 0.714 431.0 0.191 7250 0.333	9000 0.500 9000 0.714 510.0 0.159 9000 0.313
101, P0106, P0121, P012B M M //sec M	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.625 MAP2 Resid 0 0.5566 SCIAP1 Residual	0.06 1.000 ighting Factoral Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iual Weight Fac 250 250 0.625 iual Weight Fac 250 0.556 idual Weight	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based or 750 1.000 tor Based or 47.0 0.909 tor based or 750 0.625 tor based or 750 0.556 Factor based	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.625 on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625	2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385	9000 0.500 9000 0.714 510.0 0.159 9000 0.313
101, P0106, P0121, P012B M M /sec M	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.625 MAP2 Residu 0 0.556 SCIAP1 Resi	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iual Weight Fac 250 0.625 iual Weight Fac 250 0.556 idual Weight I	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based or 750 1.000 tor Based or 47.0 0.909 tor based or 750 0.625 tor based or 750 0.556 Factor based 750	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 1 MAF Estima 56.0 0.836 DI RPM 1250 0.625 DI RPM 1250 0.556 I On RPM 1250	0.25 1.000 tions only) 1750 1.000 1.750 0.833 te 67.0 0.773 1750 0.625 1750 0.556	2250 1.000 2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556	2750 1.000 2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385	9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.385
101, P0106, P0121, P012B PM PM VM V/sec PM	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.625 MAP2 Resid 0 0.556 SCIAP1 Res	0.06 1.000 ighting Factor at Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iul Weight Fac 250 0.625 iual Weight Fac 250 0.556 idual Weight Fac 250 0.556	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based on 750 1.000 tor Based on 47.0 0.909 totor based of 750 0.625 totor based of 750 0.556 Factor based 750 0.556	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.625 on RPM 1250 0.625	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625	2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385	9000 9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.385
9101, P0106, P0121, P012B PM PM n/sec PM	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.625 MAP2 Resid 0 0.5566 SCIAP1 Res	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iual Weight Fac 250 0.625 iual Weight Fac 250 0.556 idual Weight 250 0.625	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based or 750 1.000 tor Based or 47.0 0.909 tor based or 750 0.625 Factor based 750 0.625 Factor based	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.556 I on RPM 1250 0.625 I on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625 1750 0.556	2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556 2250	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556 2750	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500 3250 0.556	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455 3750 0.556	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455 4750 0.556	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417 5250 0.556	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417 5750 0.556	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.385 6250 0.556	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385 6750 0.556	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385 7250 0.556	9000 9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.385
1101, P0106, P0121, P012B PM PM n/sec PM	0.00 1.000 1.000 1.000 1.000 , P1101: IFRD Residual We TPS Residu 0 1.000 MAF Residu 0 1.000 MAF Residu 0.0 1.000 MAP1 Resid 0 0.625 MAP2 Resid 0 0.556 SCIAP1 Res 0 0.625 SCIAP1 Res 0 0.625	0.06 1.000 ighting Factor al Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 ial Weight Fac 250 0.625 iual Weight Fac 250 0.556 idual Weight 250 0.625 idual Weight 250 0.625 idual Weight 250	0.13 1.000 s (Super Chitor based on 750 1.000 tor based on 750 1.000 tor Based on 47.0 0.909 actor based on 750 0.625 actor based on 750 0.556 Factor based on 750 0.625	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 1 MAF Estima 56.0 0.836 DR RPM 1250 0.625 DR RPM 1250 0.556 I OR RPM 1250 0.625 I OR RPM 1250 0.625 I OR RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625 1750 0.556	2250 1.000 2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 1.000	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556 2750 1.000	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500 3250 0.556	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455 3750 0.556	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455 4750 0.556	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417 5250 0.556	5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417 5750 0.556	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.385 6250 0.556	6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385 6750 0.556	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385 7250 0.556	9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.556
101, P0106, P0121, P012B PM PM v/sec PM	0.00 1.000 1.000 1.000 1.000 1.000 P198 Residual We TPS Residual Personal Testing Tes	0.06 1.000 ighting Factor at Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iulu Weight Fac 250 0.625 iulu Weight Fac 250 0.556 idual Weight Fac 250 0.625 idual Weight 250 0.625	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based on 750 1.000 tor Based on 47.0 0.909 totor based or 750 0.625 totor based or 750 0.556 Factor based 750 0.625 Factor based 750 0.625 Factor based 750 0.625	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.625 on RPM 1250 0.625 on RPM 1250 0.556 on RPM 1250 0.556	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625 1750 0.556 1.000	2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556 2250	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556 2750	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500 3250 0.556	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455 3750 0.556	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455 4750 0.556	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417 5250 0.556	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417 5750 0.556	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.385 6250 0.556	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385 6750 0.556	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385 7250 0.556	9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.556
D101, P0106, P0121, P012B PM n/sec PM PM	0.00 1.000 1.000 1.000 1.000 1.000 MAF Residu 0 1.000 MAF Resid 0.0 1.000 MAP1 Resid 0 0.0.625 MAP2 Resid 0 0.0.556 SCIAP1 Res 0 0.625 SCIAP2 Res 0 0.625 Boost Resid	0.06 1.000 ighting Factor al Weight Fac 250 1.000 al Weight Fac 250 1.000 al Weight Fac 40.0 1.000 lual Weight Fac 250 0.625 lual Weight Fac 250 0.556 idual Weight 250 0.625 idual Weight 250 0.625 idual Weight 250 0.656	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based on 750 1.000 tor Based on 47.0 0.909 tor based of 750 0.625 tor based of 750 0.625 Factor based of 750 0.656	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.656 on RPM 1250 0.656 on RPM 1250 0.656 on RPM 1250 0.656 on RPM	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625 1750 0.556 1.000	2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 0.556 2250 1.000	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556 2750 1.000	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500 3250 0.556 3250 0.625	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455 3750 0.556	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455 4250 0.556 4250 0.625	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455 4750 0.556 4750 0.625	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417 5250 0.556 5250 0.625	1.000 5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417 5750 0.556 5750 0.625	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.556 6250 0.600	1.000 6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385 6750 0.556 6750 0.600	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385 7250 0.556	9000 9000 0.500 9000 0.714 510.0 0.159 9000 0.313 9000 0.556 9000 0.600
6 Boost 10101, P0106, P0121, P012B 1PM 1PM 1PM 1PM 1PM 1PM 1PM 1P	0.00 1.000 1.000 1.000 1.000 1.000 P198 Residual We TPS Residual Personal Testing Tes	0.06 1.000 ighting Factor at Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 250 1.000 ial Weight Fac 40.0 1.000 iulu Weight Fac 250 0.625 iulu Weight Fac 250 0.556 idual Weight Fac 250 0.625 idual Weight 250 0.625	0.13 1.000 s (Super Ch. tor based on 750 1.000 tor based on 750 1.000 tor Based on 47.0 0.909 totor based or 750 0.625 totor based or 750 0.556 Factor based 750 0.625 Factor based 750 0.625 Factor based 750 0.625	0.19 1.000 arged Applica RPM 1250 1.000 1 RPM 1250 0.833 n MAF Estima 56.0 0.836 on RPM 1250 0.625 on RPM 1250 0.625 on RPM 1250 0.625 on RPM 1250 0.556 on RPM 1250 0.556	0.25 1.000 tions only) 1750 1.000 1750 0.833 te 67.0 0.773 1750 0.625 1750 0.556 1.000	2250 1.000 2250 1.000 2250 0.733 79.0 0.719 2250 0.625 2250 1.000	2750 1.000 2750 0.696 93.0 0.660 2750 0.625 2750 0.556 2750 1.000	3250 1.000 3250 0.500 111.0 0.584 3250 0.714 3250 0.500 3250 0.556	3750 1.000 3750 0.400 131.0 0.501 3750 0.625 3750 0.455 3750 0.556	1.000 4250 0.833 4250 0.300 156.0 0.408 4250 0.556 4250 0.455 4250 0.556	1.000 4750 0.714 4750 0.300 184.0 0.336 4750 0.500 4750 0.455 4750 0.556	1.000 5250 0.625 5250 0.300 218.0 0.294 5250 0.455 5250 0.417 5250 0.556	5750 0.556 5750 0.200 259.0 0.268 5750 0.417 5750 0.417 5750 0.556	1.000 6250 0.500 6250 0.200 307.0 0.243 6250 0.385 6250 0.385 6250 0.556	6750 0.500 6750 0.200 363.0 0.219 6750 0.357 6750 0.385 6750 0.556	7250 0.500 7250 0.714 431.0 0.191 7250 0.333 7250 0.385 7250 0.556	9000 0.500 9000 0.714 510.0 0.159 9000 0.313

ECM Supporting Tables

	harger Intake Flow I					
DTC Set	TPS Model		MAP 1	MAP 2	SCIAP 1	SCIAP 2
	Failure	Failure	Model	Model	Model	Model
			Failure	Failure	Failure	Failure
No DTC	F	F	F	F	F	F
No DTC	F	F	F	F	F	T
No DTC	F	F	F	F	T	F
P012B	F	F	F	F	T	T
No DTC	F	F	F	Т	F	F
P1101	F	F	F	T	F	Т
P1101	F	F	F	T	T	F
P1101	F	F	F	T	Т	Т
No DTC	F	F	T	F	F	F
P1101	F	F	Т	F	F	Т
P1101	F	F	Т	F	Т	F
P1101	F	F	Т	F	Т	Т
P0106	F	F	Т	Т	F	F
P1101	F	F	Т	Т	F	Т
P1101	F	F	Т	Т	Т	F
P1101	F	F	Ť	Ť	Ť	T
No DTC	F	Ť	F	F	F	F
P0101	F	†	F	F	F	T T
No DTC	F	Ť	F	F	T	F
P0101, P012B	F	i i	F	F	Ť	T
P1101	F	i i	F	T	F	F
P0101	F	 	F	T	F	T
	F	Ť	F	T	T	F
P1101						
P0101, P012B	F	T	F	T	T	T
P1101	F	T	T	F	F	F
P1101	F	T	T	F	F	T
P1101	F	T	T	F	T	F
P1101	F	T	T	F	T	Т
P1101	F	T	T	T	F	F
P1101	F	T	T	T	F	T
P1101	F	T	Т	Т	T	F
P1101	F	T	Т	T	Т	Т
P0121	T	F	F	F	F	F
No DTC	T	F	F	F	F	Т
P0121	Т	F	F	F	Т	F
P1101	Т	F	F	F	Т	Т
P1101	Т	F	F	Т	F	F
P1101	Т	F	F	Т	F	Т
P1101	Ť	F	F	Ť	Ť	F
P1101	Ť	F	F	Ť	Ť	Ť
P0121	'	F	,	F	Ė	F
P1101	T T	F	Ť	F	F	T
P0121	'	F	Ť	F	T	F
P1101	'	F	Ť	F	Ť	T
		F		T	F	F
P1101	T	F	T T	T	F	T
P1101	- <u> </u>				T	F
P1101		F	T	T	T	T
P1101	T		T	T		
P0121	T	T	F	F	F	F
P1101	T	T	F	F	F	T
P0121	T	Т	F	F	Т	F
P1101	T	T	F	F	T	Т
P1101	T	T	F	T	F	F
P1101	T	T	F	T	F	T
P1101	Т	Т	F	T	Т	F
P1101	T	T	F	T	Т	Т
P0121	Т	Т	Т	F	F	F
P1101	Т	Т	Т	F	F	Т
P0121	Ť	T	Ť	F	T	F

P012D: MAP/SCIAP Cold Run Time Threshold

X axis is Engine Coolant Temperature in Deg C
-30 -15 0 15 30
242.0 188.0 134.0 80.0 0.0

ECM Supporting Tables

P00B6: Fail if power up ECT exceeds RCT by these values

Z axis is the Fast Failure temp difference (° C) X axis is IAT Temperature at Power up (° C)

_	-40	-28	-16	-4	8	20	32	44	56	68	80	92	104	116	128	140	152	
	80	80	80	60	60	40	40	30	30	30	30	30	30	30	30	30	30	

P0116: Fail if power up ECT exceeds IAT by these values

Z axis is the Fast Failure temp difference (° C)

X axis is IAT Temperature at Power up (° C)

																152
80	80	80	70	60	45	35	25	25	25	15	15	15	15	15	15	15

P0128: Maximum Accumulated Airflow for IAT and Start-up ECT conditions

Z axis is the accumulated airflow failure threshold (grams)

X axis is ECT Temperature at Power up (° C)

Y axis is IAT min during test (° C)

IAT Range

Low -40 10.0 ° C 13185 13185 13185 13185 11804 10422 9041 7660 6279 4898 Primary 54.5 ° C 13185 Alternate 13418 13418 13418 12217 8612 7410 6209 -7.0 ° C 10.0 ° C 11015 9814 6209 6209

P0128: Maximum Accumulated Time for IAT and Start-up ECT conditions

Z axis is the accumulated time failure threshold (seconds)

X axis is ECT Temperature at Power up (° C)

Y axis is IAT min during test (° C)

IAT Range

20 80 Low 54.5 ° C 1100 845 505 420 Primary 10.0 ° C 1015 930 760 675 590 335 250 -7.0 ° C 10.0 ° C 1020 850 765 680 595 510 425 340 170

P0133 - O2S Slow Response Bank 1 Sensor 1" Pass/Fail Threshold table

Z axis is the pass/fail result (see note below)

X axis is Lean to Rich response time (msec)

Y axis is Rich to Lean response time (msec)

Note: If the cell contains a "0" then the fault is not indicated, if it contains a "1" a fault is indicated

	0.000	0.060	0.077	0.094	0.111	0.128	0.145	0.162	0.179	0.196	0.213	0.230	0.247	0.264	0.281	0.298	63.999
0.000	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.070	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.087	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.104	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
0.121	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.138	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.155	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.172	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.189	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	0
0.206	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	0
0.223	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	0
0.240	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	0
0.257	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	0
0.274	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	0
0.291	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	0
0.308	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	0
63.999	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

ECM Supporting Tables

P0153 - O2S Slow Response Bank 2 Sensor 1" Pass/Fail Threshold table

Z axis is the pass/fail result (see note below) X axis is Lean to Rich response time (msec)

Y axis is Rich to Lean response time (msec)

Note: If the cell contains a "0" then the fault is not indicated, if it contains a "1" a fault is indicated

	0.000	0.060	0.077	0.094	0.111	0.128	0.145	0.162	0.179	0.196	0.213	0.230	0.247	0.264	0.281	0.298	63.999
0.000	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.070	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.087	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0
0.104	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0	0
0.121	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.138	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.155	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.172	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	0
0.189	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	0
0.206	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	0
0.223	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	0
0.240	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	0
0.257	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	0
0.274	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	0
0.291	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	0
0.308	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	0
63.999	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

P1133 - O2S HC L to R Switches Limit Bank 1 Sensor 1" Pass/Fail Threshold table

Z axis is Limit for L/R HC switches

Y axis is Average flow during the response test (gps)

X axis is estimated Ethanol percentage

Note: The cell contains the minumum switches

	0.0	10.0	20.0	50.0	80.0
0.0	28	28	28	28	28
6.3	28	28	28	28	28
12.5	28	28	28	28	28
18.8	28	28	28	28	28
25.0	28	28	28	28	28
31.3	28	28	28	28	28
37.5	28	28	28	28	28
43.8	28	28	28	28	28
50.0	28	28	28	28	28
56.3	28	28	28	28	28
62.5	28	28	28	28	28
68.8	28	28	28	28	28
75.0	28	28	28	28	28
81.3	28	28	28	28	28
87.5	28	28	28	28	28
93.8	28	28	28	28	28
100.0	28	28	28	28	28

P1133 - O2S HC R to L Switches Limit Bank 1 Sensor 1" Pass/Fail Threshold table

Z axis is Limit for R/L HC switches

Y axis is Average flow during the response test (gps)

X axis is estimated Ethanol percentage

Note: The cell contains the minumum switches

	0.0	10.0	20.0	50.0	80.0
0.0	28	28	28	28	28
6.3	28	28	28	28	28
12.5	28	28	28	28	28
18.8	28	28	28	28	28
25.0	28	28	28	28	28
31.3	28	28	28	28	28
37.5	28	28	28	28	28
43.8	28	28	28	28	28
50.0	28	28	28	28	28
56.3	28	28	28	28	28
62.5	28	28	28	28	28
68.8	28	28	28	28	28
75.0	28	28	28	28	28
81.3	28	28	28	28	28
87.5	28	28	28	28	28
93.8	28	28	28	28	28
100.0	28	28	28	28	28

ECM Supporting Tables

P1153 - O2S HC L to R Switches Limit Bank 2 Sensor 1" Pass/Fail Threshold table

Z axis is Limit for L/R HC switches

Y axis is Average flow during the response test (gps) X axis is estimated Ethanol percentage

Note: The cell contains the minumum switches

	0.0	10.0	20.0	50.0	80.0
0.0	28	28	28	28	28
6.3	28	28	28	28	28
12.5	28	28	28	28	28
18.8	28	28	28	28	28
25.0	28	28	28	28	28
31.3	28	28	28	28	28
37.5	28	28	28	28	28
43.8	28	28	28	28	28
50.0	28	28	28	28	28
56.3	28	28	28	28	28
62.5	28	28	28	28	28
68.8	28	28	28	28	28
75.0	28	28	28	28	28
81.3	28	28	28	28	28
87.5	28	28	28	28	28
93.8	28	28	28	28	28
100.0	28	28	28	28	28

P1153 - O2S HC R to L Switches Limit Bank 2 Sensor 1" Pass/Fail Threshold table

Z axis is Limit for R/L HC switches

Y axis is Average flow during the response test (gps)

X axis is estimated Ethanol percentage

Note: The cell contains the minumum switches

0.0	10.0	20.0	50.0	80.0
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
28	28	28	28	28
	28 28 28 28 28 28 28 28 28 28 28 28 28 2	28 28 28 28 28 28 28 28 28 28 28 28 28 2	28 28 28 28 28 28	28 28 28 28 28 28 28<

P2270/P2272 - O2 Sensor Signal Stuck Lean Bank 1/2 Sensor 2 Rich Equiv Ratio

	0.0	500.0	1000.0	1500.0	2000.0
0.0	1.1201	1.1201	1.1201	1.1201	1.1201
25.0	1.1201	1.1201	1.1201	1.1201	1.1201
50.0	1.1299	1.1299	1.1299	1.1299	1.1299
75.0	1.1401	1.1401	1.1401	1.1401	1.1401
100.0	1.1499	1.1499	1.1499	1.1499	1.1499

Z axis is Equiv ratio during the test Y axis is MAP (kpa) X axis RPM

ECM Supporting Tables

P2271/P2273 - O2 Sensor Signal Stuck Rich Bank 1/2 Sensor 2 Lean Equiv Ratio

	0.0	500.0	1000.0	1500.0	2000.0
0.0	0.8999	0.8999	0.8999	0.8999	0.8999
25.0	0.8999	0.8999	0.8999	0.8999	0.8999
50.0	0.8999	0.8999	0.8999	0.8999	0.8999
75.0	0.8999	0.8999	0.8999	0.8999	0.8999
100.0	0.8999	0.8999	0.8999	0.8999	0.8999

Z axis is Equiv ratio during the test

Y axis is MAP (kpa) X axis RPM

Green Sensor Delay Criteria:

The specific diagnostic (from summary table) will not be enabled until the next ignition cycle after the airflow criteria below (by sensor location) has been met:

- * B1S1 Airflow greater than 22 gps for 120,000 grams of accumulated flow non-continuously. * B1S2 Airflow greater than 22 gps for 720,000 grams of accumulated flow non-continuously.
- * B2S1 Airflow greater than 22 gps for 120,000 grams of accumulated flow non-continuously.
- * B2S2 Airflow greater than 22 gps for 720,000 grams of accumulated flow non-continuously.

Note that all other enable criteria must be met on the next ignition cycle for the test to run on that ignition cycle.

Note: This feature is only enabled when the vehicle is new and cannot be enabled in service

P0300-P0308: Idle SCD

(decel index (> Idle SCD AND > Idle SCD ddt Tables))

load Load

		(account	100000071		dut rubicoj)								
	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
8	300	251	188	135	100	87	56	28	24	32767	32767	32767	32767
9	180	175	150	125	80	55	40	32	25	32767	32767	32767	32767
11	190	180	175	150	80	60	45	37	30	32767	32767	32767	32767
12	200	180	175	150	90	70	40	33	25	32767	32767	32767	32767
13	236	178	170	170	83	51	48	35	27	32767	32767	32767	32767
14	290	214	180	180	88	51	45	40	28	32767	32767	32767	32767
15	343	252	201	170	79	54	47	32	29	32767	32767	32767	32767
16	374	238	194	155	101	62	49	37	30	32767	32767	32767	32767
17	406	300	232	170	107	70	53	41	26	32767	32767	32767	32767
18	465	375	295	155	118	73	62	37	29	32767	32767	32767	32767
19	524	450	350	155	120	76	65	48	32	32767	32767	32767	32767
21	577	488	388	150	120	79	62	50	25	32767	32767	32767	32767
22	629	525	433	140	115	82	76	60	25	32767	32767	32767	32767
24	657	563	467	150	135	85	80	90	80	32767	32767	32767	32767
25	684	600	500	160	150	100	95	100	90	32767	32767	32767	32767
27	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
29	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767

P0300-P0308: Idle SCD ddt

	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
8	170	140	114	88	70	55	32	30	30	32767	32767	32767	32767
9	160	125	113	100	75	60	42	35	4	32767	32767	32767	32767
11	201	157	175	150	100	70	50	11	11	32767	32767	32767	32767
12	270	200	160	150	111	25	21	13	15	32767	32767	32767	32767
13	330	186	164	180	67	39	21	16	15	32767	32767	32767	32767
14	420	170	190	190	72	43	25	22	19	32767	32767	32767	32767
15	512	164	165	134	85	50	36	27	20	32767	32767	32767	32767
16	541	154	151	137	90	60	45	33	25	32767	32767	32767	32767
17	572	272	175	140	95	72	56	34	25	32767	32767	32767	32767
18	617	253	185	140	100	81	58	42	27	32767	32767	32767	32767
19	663	500	195	140	105	81	68	49	22	32767	32767	32767	32767
21	767	615	205	140	110	81	65	50	24	32767	32767	32767	32767
22	870	730	210	180	115	85	66	52	26	32767	32767	32767	32767
24	900	765	400	250	200	150	70	53	28	32767	32767	32767	32767
25	930	800	650	500	375	250	75	60	30	32767	32767	32767	32767
27	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
29	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767

ECM Supporting Tables

P0300-P0308: SCD Delta

load

		OR (decel in	dex >SCD De	Ita AND > SC	D Delta ddt Ta	ables))							
	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
8	276	251	188	125	100	87	56	36	28	22	32767	32767	32767
9	158	158	129	100	80	55	40	32	25	18	32767	32767	32767
11	154	154	122	90	80	60	60	60	48	18	32767	32767	32767
12	159	159	130	100	90	77	72	62	48	24	32767	32767	32767
13	238	178	159	140	125	90	77	64	50	25	32767	32767	32767
15	341	250	225	200	150	110	88	65	50	30	32767	32767	32767
17	406	300	233	165	170	120	95	70	55	35	32767	32767	32767
19	524	450	375	300	200	135	105	85	60	40	32767	32767	32767
22	629	525	433	340	250	160	135	110	70	45	32767	32767	32767
25	684	600	500	400	275	190	150	125	90	60	32767	32767	32767
29	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
33	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
38	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
42	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
48	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
54	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
61	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767

P0300-P0308: SCD Delta ddt

load

	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
8	165	130	116	104	79	64	59	54	34	17	32767	32767	32767
9	160	125	113	100	75	60	55	50	30	18	32767	32767	32767
11	201	158	141	123	100	70	65	60	55	23	32767	32767	32767
12	270	202	174	145	111	88	77	60	57	20	32767	32767	32767
13	337	253	217	180	150	115	82	65	59	25	32767	32767	32767
15	511	378	282	185	210	140	110	85	60	35	32767	32767	32767
17	572	423	312	200	240	160	120	90	60	45	32767	32767	32767
19	663	500	450	400	275	180	150	115	80	50	32767	32767	32767
22	872	730	595	460	325	220	175	135	100	55	32767	32767	32767
25	928	800	650	500	375	250	200	170	120	70	32767	32767	32767
29	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
33	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
38	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
42	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
48	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
54	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
61	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767

P0300-P0308: Idle Cyl Mode

Load

OR (decel index (>Idle Cyl Mode AND > Idle Cyl Mode ddt Tables)) 20

ECM Supporting Tables

P0300-P0308: Idle Cyl Mode ddt

load

	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
8	165	150	185	220	255	185	101	100	95	67	50	30	20
9	523	475	400	325	250	180	140	120	90	65	47	28	20
11	501	455	390	325	260	180	140	120	100	66	45	30	20
12	539	490	420	350	280	200	135	125	110	70	45	30	20
13	660	600	500	400	300	250	160	130	125	75	45	30	25
14	537	488	450	413	375	275	186	140	133	83	50	32	30
15	413	375	400	425	450	300	211	150	140	90	55	34	35
16	647	588	550	513	475	338	243	175	75	50	65	42	38
17	880	800	700	600	500	220	125	110	90	26	24	50	40
18	1210	1100	925	750	200	190	125	110	90	28	26	55	43
19	1540	1400	1150	900	220	175	125	110	90	60	90	60	45
21	1650	1500	1225	950	250	150	125	105	90	139	98	65	50
22	1760	1600	1300	1000	255	140	120	100	90	150	105	70	55
24	1760	1600	1325	1050	260	140	125	105	100	163	115	78	60
25	1760	1600	1350	1100	280	220	210	140	140	175	125	85	65
27	2255	2050	1675	1300	925	700	500	413	295	198	140	93	73
29	2750	2500	2000	1500	1000	800	550	450	325	220	155	100	80

P0300-P0308: Cyl Mode

OP (docal inday > C)	I Modo AND >	Cyl Mode ddt Tables\)	

				OR (decei inc	iex > Cyi iviod	e and > Cyl i	node dat Tabi	es))						
		500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
load	8	500	425	388	350	275	185	145	95	90	63	45	30	22
	9	475	400	363	325	250	180	140	90	88	60	37	28	20
	11	455	390	358	325	260	180	140	95	106	80	35	30	20
	12	490	420	385	350	280	200	145	100	107	60	43	30	20
	13	600	500	450	400	300	220	160	120	109	75	50	32	24
	15	725	600	538	475	350	250	187	150	110	87	58	34	28
	17	850	700	625	550	400	300	225	160	130	90	60	40	34
	19	1100	900	800	700	500	325	260	175	150	105	70	50	40
	22	1250	1025	913	800	575	400	331	250	180	120	85	60	45
	25	1300	1100	1000	900	700	450	350	300	220	140	105	75	55
	29	1650	1375	1238	1100	825	575	450	350	250	180	125	90	70
	33	1975	1650	1488	1325	1000	775	525	400	325	200	145	105	75
	38	2350	1950	1750	1550	1150	1000	638	475	388	250	170	120	90
	42	2900	2400	2150	1900	1400	1250	750	550	450	300	190	130	105
	48	3450	2850	2550	2250	1650	1500	983	802	513	350	210	140	120
	54	4000	3300	2950	2600	1900	1750	1215	1053	575	400	230	150	135
	61	4550	3750	3350	2950	2150	2000	1448	1305	638	450	250	160	150
-														,

		2200	2400	2600	2800	3000	3500	4000	4500	5000	5500	6000	6500	7000
load	8	17	12	11	10	8	3	3	4	4	3	2	3	3
	9	15	11	10	9	7	3	3	3	4	3	3	3	3
	11	15	12	10	9	7	4	3	3	4	4	3	3	3
ĺ	12	16	15	10	9	7	4	3	4	3	4	3	3	3
ĺ	13	18	15	11	9	7	3	3	4	4	3	3	3	3
l	15	22	16	13	10	8	4	3	4	4	3	3	3	3
ĺ	17	24	20	15	12	9	5	4	4	4	4	4	4	4
l	19	30	27	18	14	11	7	5	3	4	4	4	4	4
ĺ	22	35	28	22	17	14	8	4	4	4	4	4	4	4
l	25	40	33	26	20	16	8	5	4	4	4	4	4	4
l	29	50	40	30	24	18	8	6	3	4	4	4	4	4
l	33	58	45	35	28	22	9	7	5	4	4	4	4	4
l	38	67	53	41	33	26	10	7	5	4	4	4	4	4
l	42	75	60	47	38	30	11	8	5	4	4	4	4	4
l	48	84	68	53	43	34	12	9	5	4	4	4	4	4
l	54	92	75	59	48	38	13	10	5	4	4	4	4	4
	61	101	83	65	53	42	14	11	5	4	4	4	4	4

ECM Supporting Tables

P0300-P0308: Cyl Mode ddt

		500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
load	8	150	185	203	220	255	185	101	100	98	67	50	30	20
	9	475	400	363	325	250	180	140	120	95	75	34	28	20
	11	455	390	358	325	260	180	140	120	105	85	48	30	20
	12	490	420	385	350	280	200	135	125	113	74	47	30	20
	13	600	500	450	400	300	250	160	130	125	75	45	30	25
	15	375	400	413	425	450	300	211	150	140	90	55	34	35
	17	800	700	650	600	500	375	275	200	155	110	75	50	40
	19	1400	1150	1025	900	650	425	325	250	185	127	90	60	45
	22	1600	1300	1150	1000	700	500	400	300	220	150	105	70	55
	25	1600	1350	1225	1100	850	600	450	375	265	175	125	85	65
	29	2500	2000	1750	1500	1000	800	550	450	325	220	155	100	80
	33	2700	2200	1950	1700	1200	900	700	500	400	250	175	100	85
	38	3350	2700	2375	2050	1400	950	800	600	462	300	200	140	103
	42	4000	3200	2800	2400	1600	1000	900	700	525	350	240	150	120
	48	4650	3700	3225	2750	1800	1050	858	723	575	400	280	160	138
	54	5300	4200	3650	3100	2000	1100	815	745	625	450	320	170	155
									700	675	500	000	400	21
L	61	5950	4700	4075	3450	2200	1150	773	768	0/0	500	360	180	173
L	61													
_	61	2200	2400	2600	2800	3000	3500	4000	4500	5000	5500	6000	6500	7000
load	8	2200	2400	2600	2800 9	3000 8	3500 0	4000 0	4500 0	5000	5500	6000 0	6500 0	7000
load	8 9	2200 15 15	2400 11 11	2600 10 10	2800 9 9	3000 8 8	3500 0 0	4000 0 0	4500 0 0	5000 0 0	5500 0 0	6000 0	6500 0	7000 0 0
load	8 9 11	2200 15 15 15	2400 11 11 12	2600 10 10 10	2800 9 9 9	3000 8 8 8	3500 0 0	4000 0 0	4500 0 0 0	5000 0 0	5500 0 0	6000 0 0	6500 0 0	7000 0 0
load	8 9 11 12	2200 15 15 15 15	2400 11 11 12 15	2600 10 10 10 10	2800 9 9 9	3000 8 8 8 8	3500 0 0 0	4000 0 0 0	4500 0 0 0	5000 0 0 0	5500 0 0 0	6000 0 0 0	6500 0 0 0	7000 0 0 0
load	8 9 11 12 13	2200 15 15 15 16 17	2400 11 11 12 15 16	2600 10 10 10 10 10	2800 9 9 9 9 9	3000 8 8 8 8 8	3500 0 0 0 0	4000 0 0 0 0	4500 0 0 0 0	5000 0 0 0 0	5500 0 0 0 0	6000 0 0 0 0	6500 0 0 0 0	7000 0 0 0 0
load	8 9 11 12 13 15	2200 15 15 15 15 16 17 25	2400 11 11 12 15 16 20	2600 10 10 10 10 10 11 11	2800 9 9 9 9 9 10	3000 8 8 8 8 8	3500 0 0 0 0 0	4000 0 0 0 0 0 0	4500 0 0 0 0 0 0	5000 0 0 0 0 0 0	5500 0 0 0 0 0	6000 0 0 0 0 0	6500 0 0 0 0 0	7000 0 0 0 0 0
load	8 9 11 12 13 15	2200 15 15 15 16 17 25 30	2400 11 11 12 15 16 20 25	2600 10 10 10 10 10 11 11 14	2800 9 9 9 9 10 11 15	3000 8 8 8 8 8 9	3500 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0	6000 0 0 0 0 0 0	6500 0 0 0 0 0 0	7000 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19	2200 15 15 15 16 17 25 30 35	2400 11 11 12 15 16 20 25 22	2600 10 10 10 10 10 11 11 14 17 21	2800 9 9 9 9 10 11 15 16	3000 8 8 8 8 8 9 11	3500 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22	2200 15 15 15 16 17 25 30 35 42	2400 11 11 12 15 16 20 25 22 35	2600 10 10 10 10 10 11 14 17 21 25	2800 9 9 9 9 9 10 11 15 16 21	3000 8 8 8 8 8 8 9 11 15	3500 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25	2200 15 15 15 16 17 25 30 33 42 50	2400 11 11 11 12 15 16 20 25 22 35 40	2600 10 10 10 10 10 11 14 17 21 25 30	2800 9 9 9 9 9 10 11 15 16 21 22	3000 8 8 8 8 8 8 9 11 15 16	3500 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29	2200 15 15 15 16 17 25 30 35 42 50 60	2400 11 11 12 15 16 20 25 22 35 40 50	2600 10 10 10 10 10 11 14 17 21 25 30 35	2800 9 9 9 9 10 11 15 16 21 22 26	3000 8 8 8 8 8 9 11 15 16 19 22	3500 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29 33	2200 15 15 15 16 17 25 30 35 42 50 60 70	2400 11 11 12 15 16 20 25 22 35 40 50 55	2600 10 10 10 10 11 11 14 17 21 25 30 35 40	2800 9 9 9 9 10 11 15 16 21 22 26 30	3000 8 8 8 8 8 9 11 15 16 19 22 26	3500 0 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29 33 38	2200 15 15 15 16 17 25 30 35 42 50 60 70 80	2400 11 11 12 15 16 20 25 22 35 40 50 55 63	2600 10 10 10 10 11 11 14 17 21 25 30 35 40 48	2800 9 9 9 9 10 11 15 16 21 22 26 30 36	3000 8 8 8 8 8 9 11 15 16 19 22 26 31	3500 0 0 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29 33 38 42	2200 15 15 15 16 17 25 30 35 42 50 60 70 80 90	2400 11 11 11 12 15 16 20 25 22 35 40 50 55 63 70	2600 10 10 10 10 11 14 17 21 25 30 35 40 48 55	2800 9 9 9 9 10 11 15 16 21 22 26 30 36 42	3000 8 8 8 8 8 9 111 15 16 19 22 26 31 35	3500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29 33 38 42 48	2200 15 15 15 16 17 25 30 35 42 50 60 70 80 90 100	2400 11 11 11 12 15 16 20 25 22 35 40 50 63 70	2600 10 10 10 10 11 11 14 17 21 25 30 35 40 48 55 63	2800 9 9 9 9 10 11 15 16 21 22 26 30 36 42 48	3000 8 8 8 8 8 9 11 15 16 19 22 26 31 35 40	3500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
load	8 9 11 12 13 15 17 19 22 25 29 33 38 42	2200 15 15 15 16 17 25 30 35 42 50 60 70 80 90	2400 11 11 11 12 15 16 20 25 22 35 40 50 55 63 70	2600 10 10 10 10 11 14 17 21 25 30 35 40 48 55	2800 9 9 9 9 10 11 15 16 21 22 26 30 36 42	3000 8 8 8 8 8 9 111 15 16 19 22 26 31 35	3500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4000 0 0 0 0 0 0 0 0 0 0 0 0	4500 0 0 0 0 0 0 0 0 0 0 0 0	5000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5500 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	6000 0 0 0 0 0 0 0 0 0 0 0 0	6500 0 0 0 0 0 0 0 0 0 0 0 0	7000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

P0300-P0308: Rev Mode Table

				OR (decel in	dex > Rev Mo	de Table)								
		1100	1200	1400	1600	1800	2000	2200	2400	2600	2800	3000	3500	4000
oad	8	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	66	49	33
	9	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	59	46	33
	11	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	72	54	38
	12	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	88	66	47
	13	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	103	78	54
	15	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	113	86	61
	17	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	135	103	73
	19	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	160	123	87
	22	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	188	143	101
	25	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	217	165	118
	29	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	242	186	134
	33	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	297	227	161
	38	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	331	254	182
	42	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	380	291	209
	48	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	433	332	239
	54	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	491	377	271
	61	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	549	421	303

ECM Supporting Tables

P0300-P0308: Rev Mode Table (Con't)

				OR (decel in	dex > Rev Mo	de Table)	
		4500	5000	5500	6000	6500	7000
ad	8	23	16	11	7	5	4
	9	24	18	13	10	7	5
	11	27	19	13	10	7	5
	12	33	23	16	11	8	6
	13	38	26	19	13	9	6
	15	43	31	22	15	11	8
	17	52	37	27	19	14	10
	19	63	45	32	23	16	12
	22	72	51	36	26	18	13
	25	84	60	43	31	22	16
	29	96	69	50	36	26	19
	33	115	82	59	42	30	21
	38	131	94	68	49	35	25
	42	150	108	75	56	40	29
	48	160	120	85	64	46	33
	54	170	127	93	72	52	38
	61	190	157	113	81	58	42

P0300-P0308: AFM Mode Table

load Load **OR** (decel index > AFM Table if active fuel management)

	OR (decentifiex > Arivi Table if active fuer management)												
	500	600	650	700	800	900	1000	1100	1200	1400	1600	1800	2000
11	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
12	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
13	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
14	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
16	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
18	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
21	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
23	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
27	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
30	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
35	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
40	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
45	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
51	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
58	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
65	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767
74	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767	32767

	2200	2400	2600	2800	3000	3500
11	32767	32767	32767	32767	32767	32767
12	32767	32767	32767	32767	32767	32767
13	32767	32767	32767	32767	32767	32767
14	32767	32767	32767	32767	32767	32767
16	32767	32767	32767	32767	32767	32767
18	32767	32767	32767	32767	32767	32767
21	32767	32767	32767	32767	32767	32767
23	32767	32767	32767	32767	32767	32767
27	32767	32767	32767	32767	32767	32767
30	32767	32767	32767	32767	32767	32767
35	32767	32767	32767	32767	32767	32767
40	32767	32767	32767	32767	32767	32767
45	32767	32767	32767	32767	32767	32767
51	32767	32767	32767	32767	32767	32767
58	32767	32767	32767	32767	32767	32767
65	32767	32767	32767	32767	32767	32767
74	32767	32767	32767	32767	32767	32767

ECM Supporting Tables

P0300-P0308: Zero torque engine load

Zero Torque: All Cylinders active

RPM .	Pct load
500	12.00
600	11.37
650	10.00
700	10.50
800	11.00
900	10.25
1000	9.75
1100	9.25
1200	8.75
1400	8.50
1600	8.40
1800	8.30
2000	8.20
2200	8.20
2400	8.30
2600	8.30
2800	8.30
3000	8.30
3500	9.76
4000	11.22
4500	12.68
5000	14.14
5500	15.60
6000	17.06
6500	18.52
7000	19.98

Baro KPa	Multiplier
65	0.82
70	0.85
75	0.88
80	0.90
85	0.93
90	0.95
95	0.97
100	1.00
105	1.03

Zero Torque: Active Fuel Management (AF									
RPM	Pct load								
500	15.00								
600	15.00								
650	15.00								

zeio rorque.	Active Fuel iv
RPM	Pct load
500	15.00
600	15.00
650	15.00
700	15.00
800	13.50
900	12.20
1000	11.40
1100	11.00
1200	11.00
1400	11.00
1600	11.00
1800	11.00
2000	11.00
2200	11.00
2400	11.00
2600	11.00
2800	11.00
3000	11.00
3500	14.00
4000	17.00
4500	19.99
5000	22.99
5500	25.99
6000	28.98
6500	31.98
7000	34.98

Note: Zero torque is adjusted for Baro. Misfire thresholds are relative to (maximum air density PID \$1188 SAE xxx) and do not shift appreciably with altitude compared to (current density as defined PID \$04 SAE1979)

Catalyst Damaging Misfire Percentage

load Load

	0	1000	2000	3000	4000	5000	6000	7000
0	11	8	6	5	5	5	5	5
10	11	8	6	5	5	5	5	5
20	11	8	6	5	5	5	5	5
30	8	6	6	5	5	5	5	5
40	6	6	6	5	5	5	5	5
50	6	6	5	5	5	5	5	5
60	5	5	5	5	5	5	5	5
70	5	5	5	5	5	5	5	5
80	5	5	5	5	5	5	5	5
90	5	5	5	5	5	5	5	5
100	5	5	5	5	5	5	5	5

 $\label{eq:RoughRoadSource} \mbox{RoughRoadSource = $$CeRRDR_e$_WheelSpeedInECM or $CeRRDR_e$_SerialDataFromABS Rough Road Threshold}$

Kph	0	12	24	36	48	60	72	84	96	108	120	132	144	158	170	181	194
Accel	0.26	0.26	0.27	0.28	0.29	0.30	0.31	0.32	0.34	0.39	0.49	0.55	0.58	0.58	0.59	0.59	0.60

ECM Supporting Tables

-635.1322

-635,1322

-635.1322

-635.1322

-635,1322

-635.1322

-635.1322

-635.1322

-635 1322

P0442: EONV Pressure Threshold Table (in Pascals)

X axis is fuel level in %

-635.1322

-635.1322

-635.1322

-635.1322

-635.1322

51.8750

57.5000

63,1250

74.3750

80.0000

Y axis is temperature in deg C 12.4998 18.7497 24.9996 31.2495 37.4994 43.7493 49.9992 56.2491 62.4990 68.7490 74.9989 81.2488 87.4987 93.7486 99.9985 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 -10.0000 -4.3750 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635,1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 1.2500 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 6.8750 -635.1322 -635.1322 -635.1322 -635.1322 12.5000 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 18 1250 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 1322 -635 132 23.7500 -635.1322 -635.1322 -635.132 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 29.3750 -635.1322 -635.1322 -635.1322 -635.132 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 35,0000 -635.1322 -635.1322 -635,1322 -635.132 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635,1322 -635.1322 -635.1322 -635,1322 -635,1322 -635.1322 -635.1322 -635.132 40.6250 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 46.2500 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.1322 -635.132

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-635.1322

-635.132

-635.132

-635.132

-635.1322

-635.1322

P0442: Estimate of Ambient Temperature Valid Conditioning Time

EAT Valid Conditioning Time (in seconds)
Axis is Ignition Off Time (in seconds)

-635.1322

-635,1322

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-635,1322

-635.132

-635,1322

-635.1322

-635.1322

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-635.1322

-635.1322

-635.1322

-635.1322

-635.1322

Axis	•	Curve
AAIS	0	300
	600	400
	1200	500
	1800	600
	2400	600
	3000	600
	3600	600
	4200	600
	4800	600
	5400	600
	6000	578
	6600	556
	7200	533
	7800	511
	8400	489
	9000	467
	9600	444
	10200	422
	10800	400
	11700	388
	12600	375
	13500	363
	14400	350
	15300	338
	16200	325
	17100	313
	18000	300
	19200	283
	20400	267
	21600	250
	22800	233
	24000	217
	25200	200

ECM Supporting Tables

P0496: Purge Valve Leak Test Engine Vacuum Test Time (Cold Start) as a Function of Fuel Level

Purge Valve Leak Test Engine Vacuum Test Time (in seconds)

Axis is Fuel	Axis is Fuel Level in %										
Axis	Curve										
0	40										
6	40										
12											
19	40										
25	40										
31	40										
37	40										
44	40										
50	40										
56	40										
62	40										
69	40										
75	40										
81	40										
87	40										
94	40										
100	40										

P0461, P2066, P2636: Transfer Pump Enable

TransferPumpOnTimeLimit (in seconds)

Axis is Fuel	Level in % Curve
0	0
3	220
6	220
9	220
13	220
16	275
19	330
22	385
25	440
28	495
31	550
34	605
38	660
41	715
44	771
47	826
50	881
53	936
56	991
59	1046
63	1101
66	1156
69	1211
72	1266
75	1321
78	1376
81	1431
84	1486
88	1541
91	1596
94	1651
97	1706
100	1761

KtEGRD_p_StepDelta

	X axis is Kpa BARO													
	65	70	75	80	85	90	95	100	105					
ſ	3.1953	3.1953	3.1953	3.1953	3.1953	3.1953	3.1953	3.1953	3.1953					

KtEGRD_p_StepMAP_DIFF	x	(axis is Kpa B	ARO														
	65	70	75	80	85	90	95	100	105								
	-0.0391	-0.0391	-0.0391	-0.0391	-0.0391	-0.0391	-0.0391	-0.0391	-0.0391								
KtEGRD_Cnt_StepSamplesPerTrip																	
	65	(axis is Kpa B/ 70	ARO 75	80	85	90	95	100	105								
	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000								
KtEGRD_Cnt_SamplesAfterStep																	
	65	(axis is Kpa B/ 70	ARO 75	80	85	90	95	100	105								
	10.0000	10.0000	10.0000	10.0000	10.0000	10.0000	10.0000	10.0000	10.0000								
WEODD 0 4 0 4 4 5 5 4																	
KtEGRD_Cnt_SamplesAfterReset		axis is Kpa B															
	10.0000	70 10.0000	75 10.0000	10.0000	85 10.0000	10.0000	95 10.0000	10.0000	105 10.0000								
KtPHSD_phi_CamPosErrorLimlc1	>	(axis is Deg C															
	-40.0000	axis is RPM -28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
400 800	0 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
120	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000
160 200	0000.8	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
240i 280i		8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
320 360	8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
400	0000.8	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000
440 480	0000.8	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
520 560		8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
600i 640i	0000.8	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000	8.0000 8.0000
680		8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000	8.0000
KtPHSD phi CamPosErrorLimEc1																	
Kti 1105_ptil_ddiiii dde1101Eiiiled1		(axis is Deg C ' axis is RPM															
	-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
40i 80i	2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
120 160		2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
2000 2400		2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
280	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
320 360		2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
440 480	2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
520 560		2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
640 680		2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
																	·

KtPHSD_phi_CamPosErrorLimIc2																		
		X	axis is Deg C															
			axis is RPM															
		-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400 800	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
	1200	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	1600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	2000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	2400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	2800	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	3200 3600	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
	4000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	4400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	4800	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	5200	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	5600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	6000 6400	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
	6800	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
KtPHSD_phi_CamPosErrorLimEc2																		
			axis is Deg C															
		-40.0000	axis is RPM -28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	800	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	1200	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	1600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	2000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	2400 2800	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
	3200	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	3600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	4000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	4400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	4800 5200	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000	2.0000 2.0000
	5600	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	6000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	6400	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
	6800	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000	2.0000
KtPHSD_t_StablePositionTimeIc1																		
Ktr 110D_t_otabler osition Timeler		×	axis is Deg C															
			axis is RPM															
	_	-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	800	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	1200 1600	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350
	2000	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	2400	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	2800	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	3200	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	3600	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	4000 4400	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350	3.350 3.350
	4800	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	5200	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	5600	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	6000	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	6400	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350
	6800	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350	3.350

								<u> </u>	pportii	<u>.g . a.</u>								
KtPHSD_t_StablePositionTimeEc1		_	axis is Deg C															
			axis is Deg C															
		-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	1200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	1600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2800 3200	2.000 2.000																
	3600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
KtPHSD t StablePositionTimeIc2																		
KIFH3D_I_StableF05Itt0111111eit2		×	axis is Deg C															
		Ŷ	axis is RPM															
		-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	1200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	1600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2400 2800	2.000 2.000																
	3200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	3600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6400 6800	2.000 2.000	2.000															
	0800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
KtPHSD_t_StablePositionTimeEc2																		
		X	axis is Deg C															
			axis is RPM															
	_	-40.0000	-28.0000	-16.0000	-4.0000	8.0000	20.0000	32.0000	44.0000	56.0000	68.0000	80.0000	92.0000	104.0000	116.0000	128.0000	140.0000	152.0000
	400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	1200 1600	2.000 2.000																
	2000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	2800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	3200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	3600	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	4800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5200	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	5600 6000	2.000 2.000																
	6400	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
	6800	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000	2.000
		2.000		000		000			000	000		000						

ECM Supporting Tables

Closed Loop Enable Criteria Coolant greater than KtFSTA_T_ClosedLoopTemp Start-Up Coolant -40 -28 -16 20 32 44 56 68 80 92 104 116 128 140 152 35.0 Coolant 80.0 75.0 55.0 45.0 35.0 35.0 35.0 35.0 35.0 35.0 35.0 35.0 35.0 and engine run time greater than KtFSTA_t_ClosedLoopTime Start-Up Coolant -28 -16 20 56 68 80 92 104 116 128 140 152 Close Loop Enable Time 120.0 90.0 65.0 45.0 25.0 10.0 10.0 10.0 10.0 10.0 10.0 10.0 10.0 70.0 70.0 70.0 70.0

and pre converter 02 sensor voltage greater than

KfFULC_U_O2_SensorReadyThrshHi

> 550 Voltage *milliVolts*

or less than

KfFULC_U_O2_SensorReadyThrshLo

< 350 oltage milliVolts

Voltage milliVolts

COSC (Converter Oxygen Storage Control) not enabled

Consumed AirFuel Ratio is stoichiometry i.e. not in component protection

POPD or Catalyst Diagnostic not intrusive

and

All cylinders whose valves are active also have their injectors enabled

and cylliders

O2S_Bank_ 1_TFTKO, O2S_Bank_ 2_TFTKO, FuelInjectorCircuit_FA and CyInderDeacDriverTFTKO = False

Long Term FT Enable Criteria

Closed Loop Enable and Coolant greater than

KfFCLL_T_AdaptiveLoCoolant

> 35 Celcius Coolant

or less than

KfFCLL_T_AdaptiveHiCoolant

< 140 Coolant <u>Celcius</u>

and MAP less than

KtFCLL_p_AdaptiveLowMAP_Limit

 Barometric Pressure
 65
 70
 75
 80
 85
 90
 95
 100
 105

 Manifold Air Pressure
 20.0
 20.0
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KIFCLL_P_Auapt

TPS_ThrottleAuthorityDefaulted = False

and

Flex Fuel Estimate Algorithm is not active

and

Catalyst or EVAP large leak test not intrusive

Secondary Fuel Trim Enable Criteria

Closed Loop Enable and KfFCLP_U_O2ReadyThrshLo

< 350 Voltage *milliVolts*

KcFCLP_Cnt_O2RdyCyclesThrsh

> 10 events

Time (events * 12.5 milliseconds)

Long Term Secondary Fuel Trim Enable Criteria

KtFCLP_t_PostIntglDisableTime

Start-Up Coolant -40 16 50 61 84 106 118 129 140 185.0 185.0 185.0 30.0 60.0 Post Integral Enable Time 185.0 110.0 60.0 60.0 60.0 60.0 30.0 30.0 40.0 40.0 40.0 60.0 KtFCLP_t_PostIntglRampInTime Start-Up Coolant 106 Post Integral Ramp In Time 60.0 60.0 60.0 60.0 60.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0 30.0

and

ECM Supporting Tables

 $KeFCLP_T_IntegrationCatalystMax$

< 900 Celcius

Modeled Catalyst Temperature and

KeFCLP_T_IntegrationCatalystMin

> 500

Modeled Catalyst Temperature

Celcius

KfFCLP_T_CoolantThrsh

> 80 Celcius

and

PO2S_Bank_1_Snsr_2_FA and PO2S_Bank_2_Snsr_2_FA = False

Tables supporting Engine Oil Temperature Sensor

P0196

	FastFaillem	ιρυιπ			AXIS IS ENGI	ne Coolant I	emperature a	T ECM Power	-up, Degrees	C							
Axis	-40	-28	-16	-4	8	20	32		56	68	80	92	104	116	128	140	152
Curve	79.5	79.5	79.5	60.0	60.0	39.8	39.8	30.0	30.0	30.0	30.0	30.0	30.0	30.0	30.0	30.0	30.0

TotalAccumulatedFlow Axis is Power up Engine Oil temperature, Curve is accumulated engine grams airflow Axis 32 44 56 68 104 116 140 152 4000 Curve 14000 13000 12000 10000 9000 8000 5000 5000 4000 3000 3000 3000

Tables supporting Deactivation System Performance

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_	••	~	

Axis

	EngSpeedLv	vrLimitEnable	eTable	AXIS is Gear State, Curve is Engine Speed						
Axis	1st Gear	2nd Gear	3rd Gear	4th Gear	5thGear	6th Gear	Neutral	Reverse	Park	
Curve	950	950	950	950	950	950	950	950	950	

 EngSpeedUprLimitEnableTable
 AXIS is Gear State, Curve is Engine Speed

 Axis
 1st Gear
 2nd Gear
 4th Gear
 5th Gear
 6th Gear
 Neutral
 Reverse
 Park

 Curve
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 EngSpeedUprLimitDisableTable
 AXIS is Gear State, Curve is Engine Speed

 Axis
 1st Gear
 2nd Gear
 3rd Gear
 4th Gear
 5th Gear
 6th Gear
 Neutral
 Reverse
 Park

 Curve
 3000
 3000
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HalfCylToAll	ICylVacuum (1997)			Horizontal AXIS is Gear State, Vertical axis is Engine RPM									
RPM	1st Gear	2nd Gear	3rd Gear	4th Gear	5th Gear	6th Gear	Neutral	Park	Reverse				
0.0	6	6	31	31	30	20	6	6	6				
100.0	5	5	31	31	30	20	5	5	5				
200.0	4	4	31	31	30	20	4	4	4				
300.0	4	4	31	31	30	20	4	4	4				
400.0	4	4	31	31	30	20	4	4	4				
500.0	4	4	31	31	30	20	4	4	4				
600.0	4	4	31	31	30	20	4	4	4				
700.0	4	4	31	31	30	20	4	4	4				
800.0	4	4	30	31	30	20	4	4	4				
900.0	4	4	28	29	29	20	4	4	4				
1000.0	4	4	26	29	28	19	4	4	4				
1100.0	4	4	25	27	28	17	4	4	4				
1200.0	4	4	24	24	25	16	4	4	4				
1300.0	4	4	17	17	21	14	4	4	4				
1400.0	4	4	10	11	17	11	4	4	4				
1500.0	4	4	6	7	13	8	4	4	4				
1600.0	4	4	4	5	10	7	4	4	4				
1700.0	4	4	4	4	8	6	4	4	4				
1800.0	4	4	4	4	4	5	4	4	4				
1900.0	4	4	4	4	4	4	4	4	4				
2000.0	4	4	4	4	4	4	4	4	4				
2100.0	4	4	4	4	4	4	4	4	4				
2200.0	4	4	4	4	4	4	4	4	4				
2300.0	4	4	4	4	4	4	4	4	4				
2400.0	4	4	4	4	4	4	4	4	4				
2500.0	4	4	4	4	4	4	4	4	4				
2600.0	4	4	4	4	4	4	4	4	4				
2700.0	4	4	4	4	4	4	4	4	4				
2800.0	4	4	4	4	4	4	4	4	4				
2900.0	4	4	4	4	4	4	4	4	4				
3000.0	4	4	4	4	4	4	4	4	4				
3100.0	4	4	4	4	4	4	4	4	4				
3200.0	4	4	4	4	4	4	4	4	4				

RPM	1st Gear	2nd Gear	3rd Gear	4th Gear	5th Gear	6th Gear	Neutral	Park	Reverse
0.0	4	4	4	4	4	4	4	4	4
100.0	4	4	4	4	4	4	4	4	4
200.0	4	4	4	4	4	4	4	4	4
300.0	4	4	4	4	4	4	4	4	4
400.0	4	4	4	4	4	4	4	4	4
500.0	4	4	4	4	4	4	4	4	4
600.0	4	4	4	4	4	4	4	4	4
700.0	4	4	4	4	4	4	4	4	4
800.0	4	4	4	4	4	4	4	4	4
900.0	4	4	4	4	4	4	4	4	4
1000.0	4	4	4	4	4	4	4	4	4
1100.0	4	4	4	4	4	4	4	4	4
1200.0	4	4	4	4	4	4	4	4	4
1300.0	4	4	4	4	4	4	4	4	4
1400.0	4	4	4	4	4	4	4	4	4
1500.0	4	4	4	4	4	4	4	4	4
1600.0	4	4	4	4	4	4	4	4	4
1700.0	4	4	4	4	4	4	4	4	4
1800.0	4	4	4	4	4	4	4	4	4
1900.0	4	4	4	4	4	4	4	4	4
2000.0	4	4	4	4	4	4	4	4	4
2100.0	4	4	4	4	4	4	4	4	4
2200.0	4	4	4	4	4	4	4	4	4
2300.0	4	4	4	4	4	4	4	4	4
2400.0	4	4	4	4	4	4	4	4	4
2500.0	4	4	4	4	4	4	4	4	4
2600.0	4	4	4	4	4	4	4	4	4
2700.0	4	4	4	4	4	4	4	4	4
2800.0	4	4	4	4	4	4	4	4	4
2900.0	4	4	4	4	4	4	4	4	4
3000.0	4	4	4	4	4	4	4	4	4
3100.0	4	4	4	4	4	4	4	4	4
3200.0	4	4	4	4	4	4	4	4	4

ECM Supporting Tables

HalfCylDisabledPRNDL	
PRNDL Drive 1	1
PRNDL Drive 2	1
PRNDL Drive 3	0
PRNDL Drive 4	0
PRNDL Drive 5	0
PRNDL Drive 6	0
PRNDL Neutral	1
PRNDL Reverse	1
PRNDL Park	1
PRNDL Transitional 1	1
PRNDL Transitional 2	1
PRNDL Transitional 4	1
PRNDL Transitional 7	1
PRNDL Transitional 8	1
PRNDL Transitional 11	1
PRNDL Transitional 13	1
PRNDL Transitional Illegal	1
PRNDL Transitional Between State	1

HalfCylDisabledPRNDLDeviceContro	
PRNDL Drive 1	1
PRNDL Drive 2	1
PRNDL Drive 3	0
PRNDL Drive 4	0
PRNDL Drive 5	0
PRNDL Drive 6	0
PRNDL Neutral	0
PRNDL Reverse	1
PRNDL Park	0
PRNDL Transitional 1	1
PRNDL Transitional 2	1
PRNDL Transitional 4	1
PRNDL Transitional 7	1
PRNDL Transitional 8	1
PRNDL Transitional 11	1
PRNDL Transitional 13	1
PRNDL Transitional Illegal	1
PRNDL Transitional Between State	1

 HalfCylDisabledTransGr
 AXIS is Gear State

 1st Gear
 2nd Gear
 3rd Gear
 4th Gear
 5thGear
 6th Gear
 Neutral
 Reverse
 Park

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AllCylToHalfCylVacuum Horizontal AXIS is Gear State, Vertical axis is Engine RPM 1st Gear 2nd Gear 5th Gear 6th Gear Reverse 3rd Gear 4th Gear Neutral Park 100.0 200.0 300.0 400.0 500.0 700.0 900.0 1000.0 1100.0 1200.0 1300.0 1500.0 1600.0 1700.0 1800.0 1900.0 2000.0 2100.0 2200.0 2400.0 2500.0 2600.0 2800.0 2900.0 3000.0 3200.0

Axis Curve

ECM Supporting Tables

RPM	1st Gear	2nd Gear	3rd Gear	4th Gear	5th Gear	6th Gear	Neutral	Park	Reverse
0.0	48	48	48	48	48	48	48	48	48
100.0	48	48	48	48	48	48	48	48	48
200.0	48	48	48	48	48	48	48	48	48
300.0	48	48	48	48	48	48	48	48	48
400.0	48	48	48	48	48	48	48	48	48
500.0	48	48	48	48	48	48	48	48	48
600.0	48	48	48	48	48	48	48	48	48
700.0	48	48	48	48	48	48	48	48	48
800.0	48	48	48	48	48	48	48	48	48
900.0	48	48	48	48	48	48	48	48	48
1000.0	48	48	48	48	48	48	48	48	48
1100.0	48	48	48	48	48	48	48	48	48
1200.0	48	48	48	48	48	48	48	48	48
1300.0	48	48	48	48	48	48	48	48	48
1400.0	48	48	48	48	48	48	48	48	48
1500.0	48	48	48	48	48	48	48	48	48
1600.0	48	48	48	48	48	48	48	48	48
1700.0	48	48	48	48	48	48	48	48	48
1800.0	48	48	48	48	48	48	48	48	48
1900.0	48	48	48	48	48	48	48	48	48
2000.0	48	48	48	48	48	48	48	48	48
2100.0	48	48	48	48	48	48	48	48	48
2200.0	48	48	48	48	48	48	48	48	48
2300.0	48	48	48	48	48	48	48	48	48
2400.0	48	48	48	48	48	48	48	48	48
2500.0	48	48	48	48	48	48	48	48	48
2600.0	48	48	48	48	48	48	48	48	48
2700.0	48	48	48	48	48	48	48	48	48
2800.0	48	48	48	48	48	48	48	48	48
2900.0	48	48	48	48	48	48	48	48	48
3000.0	48	48	48	48	48	48	48	48	48
3100.0	48	48	48	48	48	48	48	48	48
3200.0	48	48	48	48	48	48	48	48	48

P0521

Axis Curve

Axis Curve

Axis Curve

Axis Curve

EngSpeedW	eightFactorT	able		AXIS is Engine RPM, Curve is Weight Factor					
0	500	900	1100	1500	1750	2000	3500	4000	
0.00	0.00	0.00	0.45	0.45	0.45	0.45	0.45	0.00	

EngOilTemp	WeightFacto	rTable		AXIS is Engi	ne Oil Temp	Deg C, Curve	is Weight Fa	ctor
-10	-5	60	80	90	100	120	130	140
0.00	0.70	0.70	0.70	0.70	0.70	0.70	0.70	0.00

EngLoadSta	bilityWeightF	actorTable		AXIS is Delta	APC, Curve	is Weight Fa	ctor	
0	5	10	20	30	50	100	200	399
1.00	1.00	1.00	0.30	0.00	0.00	0.00	0.00	0.00

EngOilPredi	ctionWeightF	actorTable		AXIS is Pred	icted Engine	Oil Pressure	, Curve is En	gine Oil Predi	iction Weight Factor
160	170	225	275	360	375	400	500	600	
0.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00	0.00	

Cert Doc Bundle Name			Pcodes			
IAC_SystemRPM_FA	P0506	P0507	-			
TCM EngSpdReqCkt	P150C					
	1					
A/F Imbalance Bank1	P219A					
A/F Imbalance Bank2	P219B					
All Illibalatice Balikz	1 2 19 0					
Clutch Sensor FA	P0806	P0807	P0808			
	P0807	P0007	P0000			
ClutchPositionSensorCircuitLo FA						
ClutchPositionSensorCircuitHi FA	P0808					
E IT: 0 / B/ E/	D0.17.1	D0470				
FuelTrimSystemB1_FA	P0171	P0172				
FuelTrimSystemB2_FA	P0174	P0175				
FuelTrimSystemB1_TFTKO	P0171	P0172				
FuelTrimSystemB2_TFTKO	P0174	P0175				
EngineMetalOvertempActive	P1258					
FuelInjectorCircuit_FA	P0201	P0202	P0203	P0204	P0205 P0206 P0207 P0208	
FuelInjectorCircuit_TFTKO	P0201	P0202	P0203	P0204	P0205 P0206 P0207 P0208	
AIRSystemPressureSensor FA	P2430	P2431	P2432	P2433	P2435 P2436 P2437 P2438	
AIR System FA	P0411	P2440	P2444			
AIRValveControlCircuit FA	P0412					
AIRPumpControlCircuit FA	P0418					
CatalystSysEfficiencyLoB1_FA	P0420					
CatalystSysEfficiencyLoB2_FA	P0430					
, , , =						
AmbientAirPressCktFA	P2228	P2229				
AmbientAirPressCktFA NoSnsr	P0106	P0107	P0108			
7 III I I I I I I I I I I I I I I I I I	For Naturally Aspirated					
AmbientAirDefault	Engines:	P0106	P0107	P0108	P2227 P2228 P2229	
7 thiolone the Scientif	For Super Charged	1 0 100	1 0107	1 0100	12221 12220 12220	
	Engines:	P012B	P012C	P012D	P2227 P2228 P2229	
	For Engines with no Baro	1 0120	1 0120	1 0120	12221 12220 12220	
	Sensor:	P0106	P0107	P0108		
	Selisor.	1 0 100	1 0107	1 0100		
IAT SensorCircuitTFTKO	P0112	P0113				
IAT SensorCircuitFA	P0112	P0113				
IAT SensorCircuitFP	P0112	P0113				
IAT_SensorTFTKO	P0112 P0111	P0113 P0112	P0113			
IAT_SensorFA	P0111	P0112 P0112	P0113			
IAT_SensorCktTFTKO	P0097	P0098	10113			
IAT2_SensorCktTFTKO IAT2_SensorCktTFTKO NoSnsr	P0097 P0112	P0098 P0113				
	P0112 P0097	P0113 P0098				
IAT2_SensorCircuitFA	P0097 P0112					
IAT2_SensorCircuitFA_NoSnsr		P0113				
IAT2_SensorcircuitFP	P0097	P0098				
IAT2_SensorcircuitFP_NoSnsr	P0112	P0113	D0000			
IAT2_SensorTFTKO	P0096	P0097	P0098			
IAT2_SensorTFTKO_NoSnsr	P0111	P0112	P0113			
IAT2_SensorFA	P0096	P0097	P0098			
IAT2_SensorFA_NoSnsr	P0111	P0112	P0113			
0 1 5	D0004					
SuperchargerBypassValveFA	P2261					
CylDeacSystemTFTKO	P3400					
MAF_SensorPerfFA	P0101					
MAF_SensorPerfTFTKO	P0101					
MAP_SensorPerfFA	P0106					
MAP_SensorPerfTFTKO	P0106					
SCIAP_SensorPerfFA	P012B					
SCIAP_SensorPerfTFTKO	P012B					
ThrottlePositionSnsrPerfFA	P0121					

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	70101		Pcode	S	
ThrottlePositionSnsrPerfTFTKO	P0121				
MAF_SensorFA	P0101	P0102	P0103		
MAF SensorTFTKO	P0101	P0102	P0103		
MAF SensorFP	P0102	P0103			
MAF SensorCircuitFA	P0102	P0103			
	P0102				
MAF_SensorCircuitTFTKO	P0102	P0103			
MAP_SensorTFTKO	P0106	P0107	P0108		
MAP_SensorFA	P0106	P0107	P0108		
SCIAP SensorFA	P012B	P012C	P012D		
SCIAP SensorTFTKO	P012B	P012C	P012D		
SCIAP SensorCircuitFP	P012C	P012D			
AfterThrottlePressureFA_NA	P0106	P0107	P0108		
AfterThrottlePressureFA SC	P012B	P012C	P012D		
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AfterThrottleVacuumTFTKO_NA					
AfterThrottleVacuumTFTKO_SC	P012B	P012C	P012D		
SCIAP_SensorCircuitFA	P012C	P012D			
AfterThrottlePressTFTKO_NA	P0106	P0107	P0108		
AfterThrottlePressTFTKO_SC	P012B	P012C	P012D		
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ECT_Sensor_Ckt_TPTKO	P0117	P0118			
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ECT Sensor DefaultDetected	P0117	P0118	P0116		
ECT_Sensor_FA	P0117	P0118	P0116	D0.100	
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ECT_Sensor_Perf_FA	P0116				
ECT_Sensor_Ckt_FP	P0117	P0118			
ECT_Sensor_Ckt_High_FP	P0118				
ECT_Sensor_Ckt_Low_FP	P0117				
THMR Insuff Flow FA	P00B7				
THMR Therm Control FA	P0597	P0598	P0599		
THMR RCT Sensor Ckt FA	P00B3	P00B4	. 0000		
THMR ECT Sensor Ckt FA	P0117	P0118	P0116	P0125	P00B6
THININ_ECT_Sellsol_CKL_FA	FOIII	F0110	F0110	F0125	FUUDU
O2S Bank 1 TFTKO	P0131	P0132	P0134	P2A00	
O2S_Bank_ 2_TFTKO	P0151	P0152	P0154	P2A03	DOLON DOLON DOLON DOLON DOLON DOLON
O2S_Bank_1_Sensor_1_FA	P2A00	P0131	P0132	P0133	P0134 P0135 P0053 P1133 P015A P015B P0030
O2S_Bank_1_Sensor_2_FA	P013A	P013B	P013E	P013F	P2270 P2271 P0137 P0138 P0140 P0141 P0054 P0036
O2S_Bank_2_Sensor_1_FA	P2A03	P0151	P0152	P0153	P0154 P0155 P0059 P1153 P015C P015D P0050
O2S_Bank_2_Sensor_2_FA	P013C	P013D	P014A	P014B	P2272 P2273 P0157 P0158 P0160 P0161 P0060 P0056
PO2S_Bank_1_Snsr_2_FA	P0137	P0138	P0140	P0036	P0054 P0141 P2270 P2271
PO2S_Bank_2_Snsr_2_FA	P0157	P0158	P0160	P0056	P0060 P0161 P2272 P2273
EngineMisfireDetected TFTKO	P0300	P0301	P0302	P0303	P0304 P0305 P0306 P0307 P0308
EngineMisfireDetected FA	P0300	P0301	P0302	P0303	P0304 P0305 P0306 P0307 P0308
	1	1 0001	1 0002	. 5500	. 555 5555 1 5550 1 5551 1 5550
CrankCamCorrelationTFTKO	P0016	P0017	P0018	P0019	
CrankSensorFA	P0335	P0336			
CrankSensorTFTKO	P0335	P0336			
CamSensorFA	P0016	P0017	P0018	P0019	P0340 P0341 P0345 P0346 P0365 P0366 P0390 P0391
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CrankIntakeCamCorrelationFA	P0016	P0018			
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IntakeCamSensorTFTKO	P0016	P0018	P0340	P0341	P0345 P0346
IntakeCamSensorFA	P0016	P0018	P0340 P0340	P0341 P0341	P0345 P0346 P0345 P0346
IIIIaneGaIIIGEIIGUIFA	F0010	FUUIO	FUJ4U	F U 34 I	1 00-0 1 00-0

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Cert Doc Bundle Name			Pcode								
ExhaustCamSensorTFTKO	P0017	P0019	P0365	P0366	P0390 P0391						
ExhaustCamSensorFA	P0017	P0019	P0365	P0366	P0390 P0391						
IntakeCamSensor_FA	P0016	P0018	P0340	P0341	P0345 P0346						
IntakeCamSensor_TFTKO	P0016	P0018	P0340	P0341	P0345 P0346						
ExhaustCamSensor_FA	P0017	P0019	P0365	P0366	P0390 P0391						
ExhaustCamSensor_TFTKO	P0017	P0019	P0365	P0366	P0390 P0391						
CrankIntakeCamCorrFA	P0016	P0018									
CrankExhaustCamCorrFA	P0017	P0019									
CrankSensorFaultActive	P0335	P0336									
CrankSensor_FA	P0335	P0336									
CrankSensorTestFailedTKO	P0335	P0336									
CrankSensor_TFTKO	P0335	P0336									
CamSensor_FA	P0016	P0017	P0018	P0019	P0340 P0341 P0345 P0346 P0365 P0366 P0390 P0391						
CamSensorAnyLocationFA	P0016	P0017	P0018	P0019	P0340 P0341 P0345 P0346 P0365 P0366 P0390 P0391						
CamSensor_TFTKO	P0016	P0017	P0018	P0019	P0340 P0341 P0345 P0346 P0365 P0366 P0390 P0391						
EvapPurgeSolenoidCircuit_FA	P0443										
EvapFlowDuringNonPurge_FA	P0496										
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EvapSmallLeak_FA	P0442										
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FuelLevelDataFault	P0461	P0462	P0463	P2066	P2067 P2068						
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IgnitionOffTimer FA	P2610										
IgnitionOffTimeValid	P2610										
EngineModeNotRunTimerError	P2610										
EngineModeNotRunTimer_FA	P2610										
_											
VehicleSpeedSensor_FA	P0502	P0503	P0722	P0723							
VehicleSpeedSensorError	P0502	P0503	P0722	P0723							
LowFuelConditionDiagnostic	Flag set to TRUE if the	e fuel level < 10 %									
-	AND										
	No Active DTCs:		FuelLevelData	aFault							
			P0462								
			P0463								
	for at least 30 seconds	s.									
Transfer Pump is Commanded On	Fuel Volume in Primar	y Fuel Tank < 0.0 liters									
	AND										
		dary Fuel Tank ≥ 100.0	liters								
	AND										
		e < TransferPumpOn1	TimeLimit Table								
	AND										
		en Off for at least 0.0 se	econds								
	AND	- Makes I 1 = 1 :	and and the second	(-141 f D							
		e Valve Leak Test, Larç	ge Leak Test, and W	aiting for Purge) is	not running						
	AND										
	Engine Running										

Cont Dea Broades							
Cert Doc Bundle Name	D0040	D0044	Pcodes	D0044	D0000 D0004 D0000 D0004		
AnyCamPhaser_FA	P0010	P0011	P0013	P0014	P0020 P0021 P0023 P0024		
AnyCamPhaser_TFTKO	P0010	P0011	P0013	P0014	P0020 P0021 P0023 P0024		
IntkCamPhaser_FA	P0010	P0011	P0020	P0021			
EGRValvePerformance FA	P0401	P042E					
EGRValveCircuit_FA	P0403	P042E P0404	P0405	P0406			
	P0405	P0404 P0406	P0405 P042E	F0400			
EGRValve_FP EGRValveCircuit TFTKO	P0403	P0406 P0404	P042E P0405	P0406			
EGRValveCircuit_TFTKO EGRValvePerformance_TFTKO	P0401	P0404 P042E	F0405	F0400			
EGRValverenoimance_TFTRO	F0401	FU42E					
EngOilTempSensorCircuitFA	P0197	P0198					
EngOilModeledTempValid	ECT_Sensor_FA	IAT_SensorCircuitF	=A				
		_					
EngOilPressureSensorCktFA	P0522	P0523					
EngOilPressureSensorFA	P0521	P0522	P0523				
0.1.1.0.0.	D0 40 4	D0.400	D0.447	D0.16-	20.400 20.44 20.40		
CylnderDeacDriverTFTKO	P3401	P3409	P3417	P3425	P3433 P3441 P3449		
BrakeBoosterSensorFA	P0556	P0557	P0558				
BrakeBoosterVacuumValid	P0556	P0557	P0558				
BrakeBoosterVacuumValid	VehicleSpeedSensor FA	MAP SensorFA	1 0000				
BrakeBooster vacaam vana	Verilaleopeedocrisor_1 A	WAI _OCISON A					
CylnderDeacDriverTFTKO	P3401	P3409	P3417	P3425	P3433 P3441 P3449		
Engine Torque Est Inaccurate	EngineMisfireDetected EA	EugliniadtorCircuit	EA EugliniadtorCirc	uit EuolTrimQvet	OMPERIOITIIMME SOMAD SOECDI/aluaDorforamaco EA		
EngineTorqueEstInaccurate	Engine wished elected_FA	FuelinjediorCircuit_	_FA FuelinjediorCirc	uit_ Fuer minisyst	emEFuelTrim MAF_Se MAP_Se EGRValuePerforamnce_FA		
PPS1_OutOfRange_Composite	P2122	P2123	P0651				
PPS2_OutOfRange_Composite	P2127	P2128	P0641				
PPS1_OutOfRange_Composite	P2122	P2123	P0651				
PPS2_OutOfRange_Composite	P2127	P2128	P0641				
PPS1 OutOfRange	P2122	P2123					
PPS2 OutOfRange	P2127	P2128					
PPS1_OutOfRange	P2122	P2123					
PPS2 OutOfRange	P2127	P2128					
AcceleratorPedalFailure	P2122	P2123	P2127	P2128	P2138 P0641 P0651		
ControllerRAM_Error_FA	P0604			. 2.20	. 2.00		
ControllerProcessorPerf FA	P0606						
TPS1_OutOfRange_Composite	P0122	P0123	P0651				
TPS2_OutOfRange_Composite	P0222	P0223	P0652				
TPS FA	P0120	P0122	P0123	P0220	P0222 P0223 P2135		
TPS TFTKO	P0120	P0122	P0123	P0220	P0222 P0223 P2135		
TPS Performance FA	P0068	P0121	P1516	P2101			
TPS Performance TFTKO	P0068	P0121	P1516	P2101			
TPS_FaultPending	P0120	P0122	P0123	P0220	P0222 P0223 P2135		
TPS ThrottleAuthorityDefaulted	P0068	P0120	P0122	P0123	P0220 P0222 P0223 P1516 P2135 P2176		
EnginePowerLimited	P0068	P0606	P0120	P0122	P0123 P0220 P0222 P0223 P0641 P0651		
J 22	P1516	P2101	P2120	P2122	P2123 P2125 P2127 P2128 P2135 P2138 P2176		
5VoltReferenceA FA	P0641	-	-				
5VoltReferenceB_FA	P0651						
TOSS_Fault	ECM:	P0502	P0503				
	TCM:	P0722	P0723				
ChiffColonoidEquite (TCMA)	M20/M70:	D0751	D0752	D0750	D0757		
ShiftSolenoidFaults (TCM)	M30/M70:	P0751 P0751	P0752 P0752	P0756 P0756	P0757		
	MYC/MYD:	70/01	PU/02	PU/30	P0757 P0973 P0974 P0976 P0977		

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TransTurbineSpeedValid(TCM)	M30/M70: MYC/MYD:	P0716 P0716	P0717 P0717	P07BF	P07C0
Trans_Gear_Defaulted(TCM)	M30/M70:	P0705	P1810	P1815	P1816 P1817 P1818 P1915 P1820 P182A P1822 P182C P1823 P182D P1825 P182E P1826 P182F
KS_CktPerfB1B2_FA	P0324	P0325	P0326	P0327	P0328 P0330 P0332 P0333
EST_DriverFltActive	P0351	P0352	P0353	P0354	P0355 P0356 P0357 P0358

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Brake Pedal	C0161.71	BLS GMLAN signal monitoring	BLS CAN monitoring	BLS GMLAN signal is invalid "Brake Pedal Initial Travel Achieved Validity" = 1	-	Continuous	500ms.	Special Type C
								NO MIL
Brake Pedal	C0161.00	Signal monitoring	Brake light switch permanently high	1. If the BLS-signals is high for 60 s, while the gas pedal is stepped, with vehicle speed > 3 m/s, offset-compensated pVor < 5 bar and no control is active, a fault is set.	-	Vehicle speed > 3 m/s and offset-compensated < 5 bar	1. 60 s	Special Type C
			Bls vs. Pressure sensor plausibility	2. If the Pre-pressure has climbed to pPre > 10 bar after braking and Brake light switch signal is set in software without the actual Brake light switch signal being set and the Pump motor being actuated. A fault is set if the Fault detection time is exceeded.		2. No Rfp is running no active pressure increase	2. 1s	NO MIL
				OR If the Pre-pressure pPre > 80 bar and no Brake light switch signal is set. A fault is set if the Fault detection time is exceeded.		For pPre > 80bar continuous		
LF, RF, LR, RR Wheel Speed Sensor Circuit	C0035.00 C0040.00 C0045.00		· Open circuit in the WSS line	Wheel speed sensor test starts immediate after power. Especially shorts between WSS lines and shorts to UZ can be detected by switching single WSS channels in sequence. After end of test only the channels with no fault are switched on.	-	Once after power up	1 s	Special Type C NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
	C0050.00		Short circuit to GND in the WSS line Short circuit between WSSlines Loose contact in WSS connector Input amplifier in ECU faulty					
LF, RF, LR, RR Wheel Speed Sensor Circuit	C0035.00	WSS line monitoring	Failure criteria's:	The sensor circuitry has two current levels I = 7mA and I= 14mA. These current levels are monitored by the input amplifier located on the ECU. If the sensor line is broken, shorted to ground or shorted to supply voltage a faulty current level will be detected.	-	WSS line faults are detected, if the fault condition exists uninterrupted for t >= 200ms.	> 200 ms	Special Type C
	C0040.00		· Open circuit in the WSS line	Mutual shorts between sensor lines are detected after power up in a self test which turns on single channels in sequence.				NO MIL
	C0045.00		· Short circuit to UZ in the WSS line	Defective sensor channels are turned of to prevent damage due to overheat. Single and multiple faults are detected and the fault locations are given.				
	C0050.00		Short circuit to GND in the WSS line Loose contact in WSS connector Input amplifier in ECU faulty					

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System			Criteria	Value	Parameters		Required	illum.
LF, RF, LR, RR Wheel Speed Sensor Circuit	C0035.00	WSS Status monitoring	Failure criteria:	Power supply of the wheel speed sensor input amplifier is continuous monitored.	-	Continuous	200 ms	Special Type C
	C0040.00 C0045.00		· Input amplifier in ECU faulty	WSS low voltage is also continuous monitored (only necessary for active sensors) In case of WSS low voltage WSS line monitoring is not active.				NO MIL
				Backward current that flows in the WSS input amplifier is also				
	C0050.00			continuous monitored. Filter time is 200 ms. The pulse width (t(high) > 2 ms) of DF11s WSS sensors is continuous monitored but only if vehicle speed is > 0km/h and < 20 km/h. This ensures that the correct active sensor is mounted (DF11i switched with DF11s) and that the sensor is not corrupted. Filter time is 3.5 s.				
LF, RF, LR, RR wheel speed sensor, plausibility	C0035.5A	Lambda monitoring	Failure Criteria's:	There are two monitors for static wheel slip:	-	Testing is activated when monitoring conditions are met and no under voltage is detected	main monitor (I5):	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
	C0040.5A		· Permanently bad signal	The main monitor (λ5) needs additional information of the ESP-sensors and is active for a velocity > 20 km/h and no under voltage is detected. The backup monitor (λ6) manages with the wheel speeds alone. If the following fault conditions are fulfilled, the fault counter tLam is increased. After 5s, a suspicious flag is set, so that the corresponding wheel is not longer used for the reference speed calculation and no control			20s for 1 defective WSS	NO MIL
	C0045.5A		· Tooth wheel missing, WSS not installed, too great airgap	is active anymore. After that, a fault is detected, if the fault counter exceeds its limit, which depends on the current system state and the driving situation.			40s for 2 defective WSS	
	C0050.5A		· Worn or missing teeth · Noise	Main Monitor (λ5): If the maximum difference of wheel speeds related to maximum wheel speed exceeds 5% (free rolling wheel speeds transformed to the center of			backup monitor (l6):	
			· Open circuit, Short circuit to Uconst	rear axle) a wheel specific wheel speed sensor fault is set, if the faulty wheel is always the same, otherwise a generic wheel speed sensor fault is set.			normally 20s	
			· Interference between lines	detection filter time			With a spinning wheel 80s	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
System	Code	Description	Criteria	- the above conditions apply for 20s for 1 defective WSS. - the above conditions apply for 40s for 2 defective WSS. Backup Monitor (λ6): If the velocity is higher than 50 km/h, the deviation between the fastest and the slowest wheel must exceeds 6% related to the fastest wheel. If the velocity is below 50 km/h, the deviation must exceed an	Parameters	Conditions	Required	illum.
				absolute value of 3km/h. In case of a detected curve, the threshold is increased with an additional value of 4 km/h. detection filter time: normally 20s With a spinning wheel 80s				
LF, RF, LR, RR wheel speed sensor, plausibility	C0035.5A	Startup monitoring	Failure Criteria's:	Fast monitoring:	-	Testing is activated any time the conditions above are met and no under	Usually 20 s	Special Type C
	C0040.5A		· Permanently bad signal	A test is performed at the time the vehicle is accelerated to 12km/h.		voltage is detected		NO MIL
	C0045.5A			a) once after energizing the system		±		
	C0050.5A			b) if the vehicle was stationary for approx. 2s.				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
yyoto	9000	Boompalon	Ontonia	The test detects a failure if one (or two) wheel are at vmin and the other wheels are above 12 km/h for longer than 1s. The monitoring could detect double faults, but only at the driven axle. A fault could also be set during driving. If one wheel speed gets to vmin at a vehicle	Tarumotoro	Conditions	rtoquiiou	
				velocity vFzRef = v1, a fault is detected if the vehicle has				
				accelerated to a velocity of v1+18 km/h and the wheel speed at the faulty wheel remains at vMin. This monitoring could only detect singular faults. Slow monitoring: The slow start-up monitoring does not depend on the driving situation or on the vehicle velocity. Therefore it is always performed. However,				
				failures are detected much slowly. The failure detection time is usually about 20 seconds. The monitoring function detects a failure if both non driven wheels are under 3 km/h and the driven wheels have a velocity above 12 km/h over a period of time longer than the defined failure detection time.				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				For 2WD systems, in case of double failure at the non driven wheels, this fault will not be set. This monitoring function can				
				detect double failures.				
LF, RF, LR, RR wheel speed sensor, plausibility	C0035.5A	Missing Teeth Detection	Failure Criteria:	Every time, if a gap in the wheel speed sensor signal occurs cyclically with one wheel rotation, a fault counter	±-	The monitoring is active from 10 km/h to 80km/h and if no ABS-control is active at a front wheel	10 wheel rotations	Special Type C
	C0040.5A		· Worn or missing teeth	is increased by one. If the fault counter exceeds its limit of 6, a wheel specific fault is stored in		AND a rear wheel.		NO MI
	C0045.5A		teetii	the EEPROM.				
	C0050.5A							
LF, RF, LR, RR wheel speed sensor, plausibility	C0035.5A	LF, RF, LR, RR WSS - Dynamic Monitoring	Failure Criteria's:	A monitoring is provided for wss signal dropout.	<u>-</u>	-Vehicle speed is greater than 43 kph	60 ms	E Special Type C
	C0040.5A		· Open circuit, Short circuit to Uconst	If there is a loss of wss signal and the vehicle speed is greater than 43 kph, a fault counter becomes active.				NO MIL
	C0045.5A		 Loose contact in WSS connector 					
	C0050.5A							
LF, RF, LR, RR wheel speed sensor, plausibility		WSS Long-term Signal Disturbance Monitoring	Failure Criteria's:	Interference and signal disturbance like:	-	Continuous	10s	Special Type C
	C0040.5A C0045.5A		 Permanently bad signal Worn or missing teeth 	 non-plausible high frequency received, non-plausible high wheel acceleration, 				NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
	C0050.5A		 Noise Loose contact in WSS connector Interference between lines 	non-plausible high wheel jerk and non-plausible deltaT and Edges at low speed. In case of Active WSS set of failure is done after 10s. During this time an Einst-bit is set. It monitors up to four faults				
Generic Wheel speed sensor, slipping or wrong toothed	C0245.00	Mismatch speed between wheels	ABS continuous control monitoring	1. The monitoring reports a failure if the ABS target slip is exceeded for a time period >= 10 s at one or more wheels. If the driver brakes or the velocity is lower than 50 km/h the detection time is enlarged to 60s.		1. Continuous	1. 10 s If the driver brakes or the velocity is lower than 50 km/h the detection time is enlarged to 60s.	Type C
			2. Wss suspected failure monitoring	2. A suspected Wss (wheel speed sensor) failure is detected using the following information: • Wss electromagnetic noise detection • 50/60Hz interference (passive Wss only) • suspected dynamic failure • suspected flat tire • suspected absent signal • suspected permanent slip		2. Continuous	2. 0.5 s in control. 2s or 5 s outside control	NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
LF Outlet valve	C0550.00	Valve monitor	Fault criteria's	The electrical feedback signal does not match the actuation signal for the corresponding valve:	-	Continuous	30 ms	Special Type C
LF Inlet valve			 Interruption of valve 	Actuation Signal != Feedback Signal				NO MIL
RF Outlet RF Inlet valve			Short to GND Short to UBVR	Fault filter time is t = 30ms (for current controlled valves and under voltage conditions: t =80ms)				
LR Outlet valve			· VR (Valve Relay) defect	,				
LR Inlet valve RR Outlet valve			 Fly back diode Short/ Interruption in Actuation/ Feedback lines 					
RR Inlet valve Shutoff Valve 1 (HSV1/ASV1) Switching Valve 1 (USV1) Shutoff Valve 2 (HSV2/ASV2) Switching Valve 2 (USV2)								
LF Outlet valve	C0550.00	Cyclic Valve and Relay Test (CVRT)	Fault criteria's	Malfunctions of electrical valve actuation and valve relay are detected.	-	CVRT is executed immediately after power on and then periodic every t = 20s. The Test	Up to 20 s	Special Type C
LF Inlet valve			· Interruption of valve	First the valve relay (VR) is switched off. Then the voltage value of UVR (voltage at the valve relay) is measured. A Fault is found if UVR is not within 0.1*UZ < UVR < 0.8*UZ.		is canceled if any control/valve actuation takes place or if the Vehicle is in motion and the BLS is on.		NO MIL
RF Outlet			· Short to GND	After that all valves are switched on sequential, UVR and valve feedback is measured.				

mponent/ F	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
tem (Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Inlet valve			· Short to UBVR	A Fault is found if UVR is not 0.2*UZ < UVR < 0.8*UZ and the Valve Feedback is not act. Valve == FALSE and not act. Valve == TRUE.				
Outlet valve			· VR (Valve Relay) defect	At least VR is switched on again.				
Inlet valve			 Short/ Interruption in Actuation/ Feedback lines 					
Outlet valve Inlet valve Inteff Valve 1 IV1/ASV1) Itching Valve 1 IV1) Itchiff Valve 2 IV2/ASV2) Itching Valve 2 IV2/ASV2)								
	C0550.00	Valve and pump motor test (VPMT)	Fault criteria's	The valve and pump motor test detects electrical actuation malfunction of ABS valves. The test actuates all valves in series (to detect short cuts or shunts between the valve lines). Faults are detected by monitoring the valve response signals.		The Valve and Pump motor Test is performed once after ignition on if vehicle speed is >= 15 km/h.	Immediately	Specia Type C
nlet valve			· Interruption of valve	At the same time the pump motor is actuated. The monitor functions for the pump motor are described separately.				NO MIL
Outlet Inlet valve Outlet valve			Short to GNDShort to UBVRShort between valves					
			defect					
Outlet Inlet valve			valve Short to GND Short to UBVR Short between valves VR (Valve Relay)	lines). Faults are detected by monitoring the valve response signals. At the same time the pump motor is actuated. The monitor functions for the pump motor				

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Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
RR Inlet valve			 Short/ Interruption in Actuation/ Feedback lines 					
Shutoff Valve 1 (HSV1/ASV1) Switching Valve 1 (USV1) Shutoff Valve 2 (HSV2/ASV2) Switching Valve 2 (USV2)								
LF Outlet valve	C0550.00	ASV/USV Valve Test		The valve and pump motor test detects electrical actuation malfunction of USV and ASV/HSV valves. The test	-	The ASVUSV Test is performed once after ignition on at standstill if the BLS is off and at	Immediately	Special Type C
LF Inlet valve				actuates all valves in series (to detect shorts or shunts		vehicle speed is v >= 15 km/h if the BLS is on.		NO MIL
RF Outlet			· Short to GND	between the valve lines).				
RF Inlet valve				Faults are detected by				
LR Outlet valve				monitoring the valve response signals.				
LR Inlet valve			· VR (Valve Relay) defect					
RR Outlet valve RR Inlet valve			 Fly back diode Short/ Interruption in Actuation/ Feedback lines 					
Shutoff Valve 1 (HSV1/ASV1) Switching Valve 1 (USV1) Shutoff Valve 2 (HSV2/ASV2) Switching Valve 2 (USV2)								

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
LF Outlet valve	C0550.00	Valve Drift Test (current controlled valves)	Fault criteria's	The drift test is executed only once during an ignition Cycle. It detects partly shorted valve coils, almost defective coils or malfunction of the valve driver. The test requires identical temperature of the tested	-	The drift test executes only once during an ignition Cycle The test is triggered if the following conditions are fulfilled:	10min	Special Type C
LF Inlet valve			· Interruption of valve	valves. At first the power stages are set in test mode. Then a test pattern with different current is applied to current controlled valves. After that the test mode is also checked with a different test pattern. Then the power stages are reset to parent mode. The		t = 10min after power up or end of control, no BLS is applied, brake pressure is < 10bar, vehicle speed >15km/h, vehicle acceleration > 0.5m/s2		NO MIL
RF Outlet			· Short to GND	are reset to normal mode. The valve feedback is evaluated. In case of a deviation the test is		and supply voltage > 11 volts.		
RF Inlet valve LR Outlet valve			· Short to UBVR · VR (Valve Relay) defect	repeated two times until a failure is set.				
LR Inlet valve RR Outlet valve RR Inlet valve Shutoff Valve 1 (HSV1/ASV1) Switching Valve 1 (USV1) Shutoff Valve 2 (HSV2/ASV2) Switching Valve 2 (USV2)			· Fly back diode · Current control					
Device Power	C0899.00	Supply voltage monitoring	Supply voltage too low	Low-voltage during operation. The monitored supply voltage is filtered and limited to a rise time of 4 volts per second.	-	Continuous	20 ms	Special Type C
				UZ is monitored for a level of: filtered UZ < 9.3V outside control, or a level of: filtered UZ < 9.2V during control.		Power mode != Crank		NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
				If the Voltage is lower than this threshold, the DTC will be detected.				
Device Power	C0900.00	Supply voltage monitoring	Supply voltage too high	High-voltage during operation. The monitored supply voltage is filtered and limited to a rise time of 4 volts per second.	-	Continuous	20 ms	Special Type C
				High voltage problem will be monitored if filtered UZ is > 16.8V. If the Voltage is higher than this threshold, a DTC Supply voltage too high will be detected.		Power mode != Crank		NO MIL
Pump motor	C0110.00		Fault criteria's Open circuit in UM line Short circuit to UZ in UM line Motor relay faulty - sticks Motor faulty (Open circuit) Faulty input stage in control unit Faulty output stage in control unit		_	Stop monitor is active if the pump is off i.e. not actuation and no slowdown.	>1s	Special Type C NO MIL
Pump motor	C0110.00	Pump run monitor	Fault criteria's Open circuit in UBMR line Short circuit to GND in UM line	The monitor detects pump supply faults, FET continuous off, UBMR interruptions (fuse blown) and high resistance of FET and supply line. A failure is detected if the voltage UM < (UZ - 4.0V) for a time t >= 100ms.	-	The monitor is active if the pump is switched on (FET on) Remark: the run monitor is idle during pump PWM actuation (i.e. pump control) in the off-phase	> 100 ms	Special Type C NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Motor relay faulty fails to energize Faulty input stage in control unit Faulty output stage in control unit					
Pump motor	C0110.00	Pump slowdown monitor	Fault criteria's	After the end of the actuation of the motor relay has, the pump motor is still in motion and is generating a Voltage during it's slowdown. The generated UM is monitored for a certain time on high level. The time depends on the supply voltage and is in the range of t = 30ms to t = 125ms.	_	Monitor is always active in the transition	Normally > 4 s	Special Type C
			· Short circuit to GND in UM line	If the slow down condition isn't met, the pump is activated again (see actuation times below) and the slowdown time is measured again. This is repeated for maximum n = 3 times. If, after the last pump activation, the pump motor slowdown time is still to short, a failure is detected.		"pump on -> pump off".		NO MIL
			fault	Actuation times: 1st actuation: 200 ms				
			· Faulty output stage in control unit	2nd actuation: 1000 ms 3rd actuation: 3000 ms				
Valve relay	C0121.00	FSA Test (Fail Save Circuit Test)	Fault criteria's	Watchdog and VR function is tested during startup.	-	Once during startup.	Immediately	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			line	FSA test detects if the VR/Enable remains in off position when it is turned on and vice versa. Reason could be short to GND or UZ, interrupted lines or a defective output stage etc.				NO MIL
			 Short circuit to UZ in UVR line Short circuit to GND in UVR line Valve relay faulty (Fails to energize; Drops out; Sticks) Faulty output stage in control unit (Short or open circuit) 					
Valve relay	C0121.00	UVR Monitor	Fault criteria's Open circuit in VR line Open circuit in UBVR line Valve relay faulty (Fails to energize; Drops out) Faulty output stage in control unit (Open circuit)	A Fault is detected if UVR < 0.8 * UZ for a time t > 500ms.		Continuous	500 ms	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Valve relay	C0121.00	CVRT (Cyclic Valve and Relay Test) for VR monitoring	in VR line Short circuit to GND in VR line	This test evaluates the function of the VR (vale relay) periodically. The VR is switched off and back on. VR malfunction and UVR short to UZ or UBVR and medium or high ohmic short of UVR (or a valve) to UZ, UBVR or GND are detected.	-	Continuous	Immediately	Special Type C NO MIL
Pressure Sensor failure, circuit	C0131.00	Pressure sensor Supply monitoring	Failure criteria: Sensor supply out of range	Sensor Supply Voltage > 5. V OR	-	Continuous	60ms	Special Type C NO MIL
				Sensor Supply Voltage < 4.5V				
Pressure Sensor failure, circuit	C0131.00	Pressure signal line monitoring	Failure criteria:	Pressure Signal Voltage > 3.29V	-	Continuous	100ms	Special Type C
			out of range	OR Pressure Signal Voltage < 0.129V				NO MIL
Pressure Sensor C01 failure, circuit	C0131.00	Pressure signal offset monitoring	Failure criteria:	The DS-offset value must be in the range of ±15 bar.	-	After DS-initialization, no under voltage, no pumps are running	0	Special Type C
			· Pressure sensor offset exceeds range.			and no BLS-signal is set		NO MIL

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Lateral Accelerometer Circuit	C0186.00	Sensor signal failure	Lateral acceleration out of range.	The AY-signal is limited to an electrical stop of 1.8g. If Ay > 1.5g for more than 500ms fault is detected.	-	Continuous after initialization.	1. > 500 ms	Special Type C
			Lateral acceleration value during standstill is too large.	At standstill the plausible range of Ay < 0.7g. If the filtered value of Ay > 0.7g than fault is set.		Monitoring during standstill	2. > 400 ms	NO MIL
			3. AYS offset out of range.	3. Under normal driving conditions the long time filtered driving direction is straight ahead. The long time filtered Ay-value is called Offset. If the Offset value is higher than 2.25 m/s2 an Ay-fault is determined. Failure detection time depends on the driving distance, vehicle speed and on the amount of failed Ay-signal.		3. Monitoring during straight driving	3. Immedia tely when offset exceeds limit	
			4. AY gradient monitoring.	A signal gradient higher 55g/sec sets a fault. The AY-signal is filtered by a peak-filter.		4. After init and no ABS active	4. Depend s on driving conditio n.	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
Lateral Accelerometer Circuit	C0186.5A	Sensor plausibility failure	Lateral acceleration plausibility fault during model validity.	If during stabile vehicle behavior an Ay-Failure larger then 2.5 m/s2 is occurring, the VDC controller will disregard the Ay sensor information so that a false VDC intervention is prevented. Failure is detectable if this condition applies for t > 2s and stable driving conditions are given.	-	After initialization, no under voltage, sensor offsets calculated, VDC not temporary passive, FZREF > 5 m/s recognized forward driving direction and no banking curve	> 2 s	Special Type C NO MIL
Yaw Rate Circuit	C0196.00	Monitoring of Yaw rate status reported in CAN message.	If the CAN received signals indicate internal DRS sensor failure the fault will be set after predefined filtering.	-	-	Continuous.	Typical 100ms	Special Type C NO MIL
Yaw Rate Circuit	Yaw Rate Circuit C0196.00 Yaw Rate s monitoring		Yaw rate sensor offset exceeds limit.	If offset value is outside the plausible range ± 5.25 °/s at start of driving a DRS-Offset fault is set.	-	1. After initialization, no under voltage, no control active, reference yaw rate less than 55 °/s and no internal LWS-failure.	1. Imediate ly.	Special Type C
			Yaw rate sensitivity monitoring.	2. DRS-sensitivity is estimated by comparison of the reference yaw rate (build by model based sensor monitoring) and measured yaw rate during cornering. The fault criteria is approx. 25% sensitivity failure		2. After initialization, no undervoltage, DRS-Offset calibration finished, no control active, DRS-reference yaw rate less than 55°/s and higher than 5°/s, Ay < 7 m/s2, slip at driven axle less than 3%, recognized forward driving direction, no LWS-failure and no banking curve	2. Depend s on driving situation .	NO MIL

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Component/	Fault		Malfunction		-	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			 Yaw rate sensor gradient fault. 	3. If the yaw rate is greater than 10 – 23 degrees/s / 40ms (depending on driving conditions) a suspected fault is detected after t > 280ms and fault detection occurs after t > 10s.		 Continuous after initialization. No undervoltage. 	3. 800 ms and forward driving is recogniz ed	
Yaw Rate Circuit	C0196.5A	Yaw Rate plausibility monitoring	A failure is set if the offset corrected DRS signal deviates sufficiently	The comparisons include static and dynamic thresholds which vary	-	Continuous and no undervoltage.	Depends on driving situation.	Special Type C
			from the reference yaw rate and from the yaw rate calculated via a model based upon LWS signal and vehicle speed.	dependent upon current vehicle maneuver and circumstances.				NO MIL
Yaw rate sensor	U2142	Lost communication with yaw rate sensor.	1. If a DRS CAN message is not received by EBCM fault is set. The receive CAN message from YAW sensor are: 0x130, 0x131 and 0x140.	1. –		1. Continuous.	1. 300ms	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			2. If transmitted message was not transmitted a fault is set. 3. Monitoring includes line short to ground, line short to supply voltage and mutual line short. Line interruptions are detected by CAN message monitor. After detecting a BUSOFF failure the transmission is reinitialized. A BUSOFF fault is established if reinitialization is tried for 15 times in sequence without success.	2. –		2. Continuous 4. Continuous 4. During sensor CAN controller initialization.	 600ms 3. 300ms 4. Imediately. 	NO MIL
Steering Position Signal	C0710.00	Steering angle sensor circuit	SAS-A and/or SAS-B not changing	1. If one or both of the SAS-A and SAS-B signals is not changing (due to short to ground, etc.) while the SAS is being turned, a fault will be set once the SAS-Analog signal has changed by at least 30degrees	-	1. Continuous during driving. However, this fault can only be detected when the SAS-Analog signal is changing – that is when the angle is between +/- 225 degrees.	1. 40ms	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			2. SAS-A and SAS-B Shorted together	2. If the SAS-A and SAS-B signals are shorted together, they will change state at exactly the same time. Every time this happens a count will be incremented by 1. Every 20ms, this count will be decremented by 1. If the count ever reaches 2, this fault will be set.		Continuous while driving	2. 2 counts	NO MIL
			3. SAS-Index Signal Not Changing	3. If the SAS-Index stays high and the SAS-A and SAS-B signals change by more than 25 degrees, or the SAS-Index stays low and the SAS-A and SAS-B signals change by more than 345 degrees.		3. Continuous while driving	3. 40ms	
			4. SAS-Index Signal Coming Too often monitoring	4. If there are two different SAS-Indexes and the SAS-Analog angle changes by less than 5 degrees, a fault will be set.		4. Continuous while driving	4. 40ms	
			5. SAS-Analog Signal Changing Too Fast monitoring	5. If the SAS-Analog signal rises from its lowest value to its highest value (or vice versa) in less than 250 degrees in one direction (based on the SAS-A and SAS-B signals), a fault will be set.		5. Continuous while driving	5. 40ms	

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			6. SAS-A and SAS-B Swapped monitoring	6. If the steering angle based on the SAS-A and SAS-B signals changes in the opposite direction of the analog angle, a fault will be set once the SASAnalog signal has changed by at least 30 degrees if it lasts 40ms.		6. Continuous during driving. However, this fault can only be detected whenthe SAS-Analog signal is changing that is when the angle is between +/- 225 degrees.	6. 40ms	
			7. SAS Turning Too Fast monitoring	7. If the SAS-A and SAS-B signals change significantly faster than the specified maximum turning rate of the Steering Angle Sensor, a fault will be set. This is done to protect the operating system from crashing due to excessive interrupt handling. The number of SAS-A and SAS-B edges each 20ms is counted. If this count exceeds the limit at the end of the 20ms, the fault will be set.		7. Continuous.	7. 50 counts	
Steering Position Signal	C0710.00	Steering angle sensor circuit	8. SAS-Analog Not Changing monitoring	8 If the angle changes by more than 530 degrees based on the SAS-A and SAS-B signals, and the SAS-Analog angle changes by less than 5 degrees, a fault will be set if it lasts 40ms.		8. Continuous while driving	8. 40ms	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
		(Cont.)	9. SAS- 5 Volt supply fault	9 If the SAS 5V supply is greater than 5.3V or less than 4.5V for more than 60ms, the fault will be set.		9. Continuous.	9. 60ms	NO MIL
	Steering angle sensor signal monitoring.	1. SAS Offset monitoring	1. If the SAS offset value exceeds a threshold of approximately 15 deg a SAS-fault is determined. Failure detection time depends on the driving distance, vehicle speed and on the amount of failed SAS-signal. Within 30 km of symmetrical driving the calculated offset corresponds to the sensor offset.		Continuous during driving. The maximum admissible range for SAS offset compensation is when steering angle <30 deg or straight ahead driving can be detected from WSS.	1. Immediate ly.	Special Type C	
			2. SAS Gradient monitoring	2. Rapid changes of the SAS-Signal cannot occur under normal conditions. A SAS-gradient-failure is set, if:			2. Immediate Iy	NO MIL
			3. SAS range monitoring	- signal gradient (steering angle velocity) from one 20 ms-cycle to another is higher than 40° or		2. After SAS- initialization and FZREF > 1.4 m/s; no under voltage and at least one SAS- message was sent in the current 20ms- cycle	3. 600ms	
			4. SAS constant signal	- change of this gradient (steering angle acceleration) is higher than 15			4. Depends on driving conditions	

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Component/	Fault	Monitor Strategy	Malfunction		Secondary	Enable	Time	MIL
System	Code	Description	Criteria		Parameters	Conditions	Required	illum.
			5. SAS Wrong Sign Monitoring	and no signal peak is recognized by a peak-filter		After initialization and no under voltage detected	5. Depends on driving conditions	
				3. Range of SAS-Signal is limited by mechanical stop of steering mechanism. If value is higher than possible range for more than 300ms a fault is determined.				
				4. At a minimum change of e.g. 5° in the signal, the monitoring is reset. If there is no change in the signal, but a right AND left cornering has been recognized which would have required a change in SAS signal larger than 5 deg (lateral acceleration > 2 m/s² in combination with a yaw rate > 6 °/s in both directions), a fault is determined.		4. Initialization once in every ignition cycle. The monitoring is active until a reset by a change in the SAS signal or until a right and left cornering can be recognized		
				5. This monitoring detects a wrong built in steering angle sensor. The model yaw rates, calculated from the WSS and SAS are compared. During driving these signals must have the same sign. If the signal signs are different, a fault is determined.				

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
						5. Once in every ignition cycle. Stable driving with a minimum yaw rate of 3 deg/s is necessary.		
Steering Position Signal	C0710.5A	Steering angle sensor plausibility monitoring.	The steering angle is compared to a steering angle calculated from yaw based on a vehicle model a reference. The difference between measured SAS-signal and	Threshold depends on driving conditions.		Continuous during driving when the stability criteria of the monitoring is met.		Special Type C
			SAS signal calculated from YRS-signal is evaluated for fault detection.					
Steering Position Signal	C0455.00	Steering angle sensor circuit monitoring.	SAS. Steering Angle Sensor Analog signal	If the SAS-Analog signal is outside of its working range compared to the 5volt supply voltage – less than 9% or greater than 90 of 5V supply - a fault will be set.		Continuous during driving.	120ms	Special Type C NO MIL
Vacuum sensor	C1100.00	Vacuum sensor circuit monitoring	Vacuum Sensor Supply monitoring	Sensor supply voltage is continuously monitored (except power on). A sensor supply failure is detected if Sensor Supply Voltage > 5.25V OR Sensor Supply Voltage < 4.75V for t >= 200ms		1. Continuous	1. 20 0m s	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Vacuum Sensor line monitoring	2. Vacuum sensor line is continuous monitored (except power on). Line faults like open, short to GND or short to UZ are detected. A Fault is set if the vacuum sensor signal is U VAC > 3.15V OR U VAC < 0.3V for a time t >= 200ms		2. Continuous		NO MIL
Vacuum sensor	C1100.00	Vacuum sensor signal monitoring	Vacuum Sensor Plausibility	Vacuum signal remains constant during a brake apply greater than 20 bar/sec starting from 0 bar.		Continuous	1s	Special Type C NO MIL
Brake Fluid	C0267.00	Brake Fluid low	When the brake fluid signal in GMLAN message 0x12A (LS_Device_Information) from BCM indicates the low brake fluid is true, the fault is set.	-	_	Continuous	Immediately	Special Type C NO MIL
Stability System Active Too Long	C0252.00	Implausible Control	Implausible FZR- interventions or wrong signal.	The monitoring reports a failure if continuous ESC control occurs for a time period >= 10 s. A continuous ESC control for longer than 10s is not possible under normal conditions	_	Continuous at vehicle reference speed greater than 6m/s, no detectedunder voltage and a fault is not already detected	1. 10s	Special Type C

Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			Implausible controller intervention.	 A fault is set if all 4 wheel inlet valves are continuously maintaining pressure or releasing pressure during the ABS control. 		Ignition on. Then 'Power on self-test (POS)'. Continuous monitoring. Active ABS control.	2. 2s	NO MIL
Electronic Control	C0550.00		Internal control unit failures of	-	ļ-	Continuous.	Immediately	
Unit Hardware		ECU hardware.	the μC's and peripheral integrated circuits					Type C
			will be continuous monitored for proper function.					NO MIL
Electronic Control Unit Software	C0569.00	Calibration not programmed.	If the re-program flag in EEPROM indicates the ECU is not reprogrammed, the	-	-	Wrong configuration can be realized and detected after ignition	Immediately	Special Type C
			fault is set. The re-program flag is set to not reprogrammed when the ECU is built with default calibration block. The reprogram flag will be reset to reprogrammed once the ECU is reprogrammed successfully.			on.		NO MIL
CAN System fail	U2100.00	CAN system monitoring	Failure criteria:	-	-	Monitored whenever CAN chip initializes.	Immediately	Special Type C
			· CAN controller fails to initialize.					NO MIL
Lost Comms with ECM	U0100.00	ECM Lost Communication	Following messages are missing from the bus:	N/A	-	Continuous	2.5*period or	Special Type C
			0x1C3/0x1C1 PPEI_Engine_Torque_Status 2				250 ms (whichever is greater)	NO MIL

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Component/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
System	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			0x0C9 PPEI_Engine_General_Statu s1 0x2C3/0x2C5 PPEI_Engine_Torque_Status _3					
Lost Comms with TCM	U0101.00	TCM Lost Communication	Following messages are missing from the bus:	N/A	-	Continuous	2.5*period or	Special Type C
			0x1F5 PPEI_Trans_General_Status _2 0x0F9 PPEI_Trans_General_Status _1 0x2D1 (NR3) PPEI_Transfer_Case_Status				250 ms (whichever is greater)	NO MIL
Lost Comms With BCM	U0140.00	BCM Lost Communication	Following messages are missing from the bus:	N/A	-	Continuous	2.5*period or	Special Type C
			0x0F1PPEI_Brake_Apply_St atus 0x1F1 PPEI_Platform_General_Stat us 0x12A LS_Device_Information				250 ms (whichever is greater)	NO MIL
Lost Comms With TCCM	U0102.00	BCM Lost Communication	Following messages are missing from the bus:	N/A	-	Continuous	2.5*period or	Special Type C
(NQH/NQG variants)			0x2D1 PPEI_Transfer_Case_Status				250 ms (whichever is greater)	NO MIL

nponent/	Fault	Monitor Strategy	Malfunction	Threshold	Secondary	Enable	Time	MIL
tem	Code	Description	Criteria	Value	Parameters	Conditions	Required	illum.
			0x1CB PPEI_TC_Coupling_Status					
Invalid GMLAN data		GMLAN signals validity monitoring.	Failure criteria:	-	-	Continuous after 5 sec from power up.	500ms	Special Type C
	C0561.72		· GMLAN signal is invalid					NO MIL
	C0561.74							
ine torque	C0242.00	Torque signal monitor.	Engine Torque Inhibit	When the GMLAN signal EngTrqRdFIrSt in 0x1C1/0x1C3 from ECM is not "Torque Reduction OK" or "Torque Reduction Limited", the fault is set after 500ms. The fault is reset after the signal EngTrqRdFIrSt is "Torque Reduction OK" or Torque Reduction Limited" for 500ms.	-	Continuous.	500ms	Special Type C NO MIL
				the fault is set after 500ms. The fault is reset after the signal EngTrqRdFlrSt is "Torque Reduction OK" or Torque Reduction Limited" for				